



Simulation and Optimization Methods for Reliability Analysis

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Weimar, November 21, 2013

PLAN OF PRESENTATION



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- Description of the model
 - Brute force Monte Carlo benchmarking
 - Quality assessment of estimators by resampling and Bayes



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 - Genetic algorithm
 - Nelder-Mead with constraints
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 - Turning the random field on
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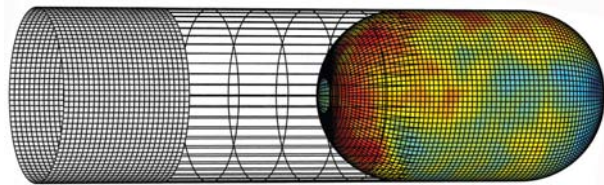
Thanks to: Dynardo GmbH, INTALES, CTU Prague, Astrium Ottobrunn

DESCRIPTION OF THE MODEL



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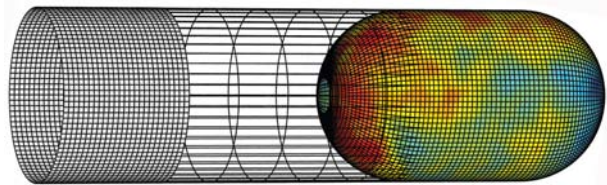
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Small launcher model:

FE-model, ABAQUS, 18.000 elements, shell elements and beam elements for stiffeners.
91.000 DoF.

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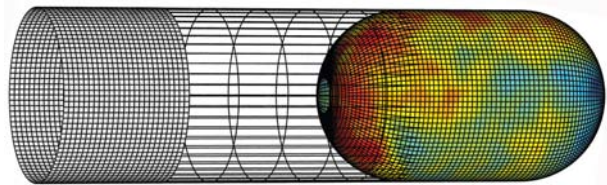
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Input statistics: Uniform distributions with spread $\pm 15\%$ around nominal value.

Output: Failure probability

$$p_f = P(\Phi(\mathbf{x}) > 1)$$

defined by the the critical demand-to-capacity ratio (CDCR)

$$\Phi(\mathbf{x}) = \max \left\{ \frac{PEEQ(\mathbf{x})}{0.07}, \frac{SP(\mathbf{x})}{180}, \frac{0.001}{EV(\mathbf{x})} \right\},$$

combining 3 failure criteria (plastification of metallic part, rupture of composite part, buckling).

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Result of benchmark simulation:

$$p_f = 0.0116.$$

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First analysis: Bootstrap resampling. Drawing from the original sample of size $N = 5000$ with replacement, $B = 10000$ samples with the same (empirical) distribution and corresponding p_f are obtained. Result: an estimate of the statistical variation of p_f .



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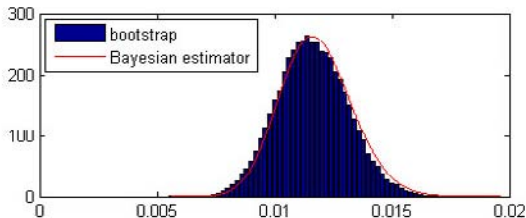
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Variation of p_f
around its estimated
value of 0.0116.

RELIABILITY ANALYSIS: FASTER METHODS (1)



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Subset Simulation:

$$P(F) = P(F_m|F_{m-1})P(F_{m-1}|F_{m-2})\dots P(F_1|F_0)P(F_0)$$

where $F = F_m$ and F_0 is the starting region.

$$F = \{\mathbf{x} : \Phi(\mathbf{x}) > 1\}, \quad F_i = \{\mathbf{x} : \Phi(\mathbf{x}) > \alpha_i\}$$

and α_i is chosen so that $P(F_i|F_{i-1}) = 0.2$, say.

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Asymptotic sampling: $p_f = \Phi(-\beta)$, $\beta = \Phi^{-1}(1 - p_f)$.

Transformation to normal probability space with $\sigma = 1$. Instead of simulating $\beta = \beta(1)$, one simulates $\beta(v)$ for smaller values of $v = 1/\sigma$, which is easy, and sets up a regression

$$\beta(v) = A + Bv + C/v + \dots$$

Best model chosen by data analysis.

RELIABILITY ANALYSIS: FASTER METHODS (2)



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Importance sampling:

$$p_f = \int \mathbb{1}_F(\mathbf{x})\rho(\mathbf{x}) d\mathbf{x} = \int \mathbb{1}_F(\mathbf{x})\frac{\rho(\mathbf{x})}{g(\mathbf{x})}g(\mathbf{x}) d\mathbf{x}.$$

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How to choose $g(\mathbf{x})$? Start with cheap sensitivity analysis.

Employing all tricks of the trade (Latin hypercube sampling, correlation control), a sample size around 100 – 200 suffices.

Determine the most relevant input parameters.

Distort their distribution according to the degree of correlation with the output (assuming monotone dependence).

RELIABILITY ANALYSIS: COMPARISON

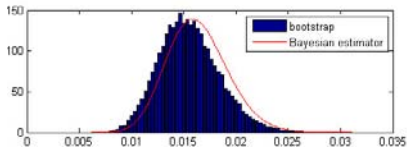


	MC	SS	AS	IS
Sample Size	5000	780	800	780
Estimated p_f	0.0116	0.0155	0.0093	0.0084
Bootstrap 95%-CI	0.0088 – 0.0146	0.0104 – 0.0217	0.0028 – 0.0219	0.0055 – 0.0118
Bayesian 95%-CI	0.0090 – 0.0150	0.0112 – 0.0225		

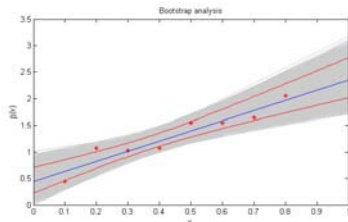
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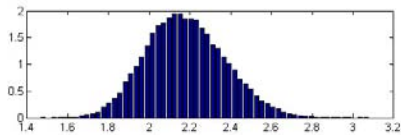
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Subset simulation: Bootstrap and Bayesian estimate of the variability of p_f .



Asymptotic sampling: Bootstrap regression and corresponding distribution of β .





Derivative-free methods:

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- Genetic algorithms. An initial set of points is improved (with respect to the value of the objective function) by randomly changing coordinates and interchanging components. When a local optimum has been identified, a restart is undertaken to cover other regions of the search space.



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In all cases, the implementation of bounds (on input) and constraints (on output) requires additional rules.

WORST CASE SCENARIOS

First application: In reliability analysis, the location of the failure region and the most critical points are of interest.



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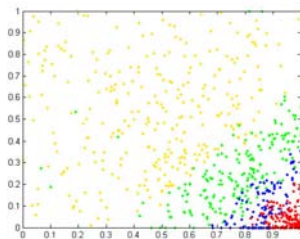
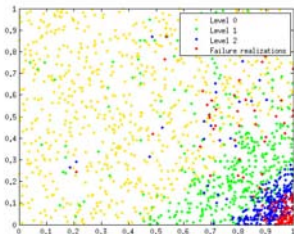
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All algorithms compute clouds of points that can be ordered according to their Φ -values and used for further analysis.

Subset Simulation (top) and genetic algorithm (bottom), pressure load sphere 2 versus yield stress cylinder 3.

Legend

yellow	0 – 0.9543
green	0.9544 – 0.9885
blue	0.9886 – 1
red	> 1



MASS OPTIMIZATION UNDER CONSTRAINT

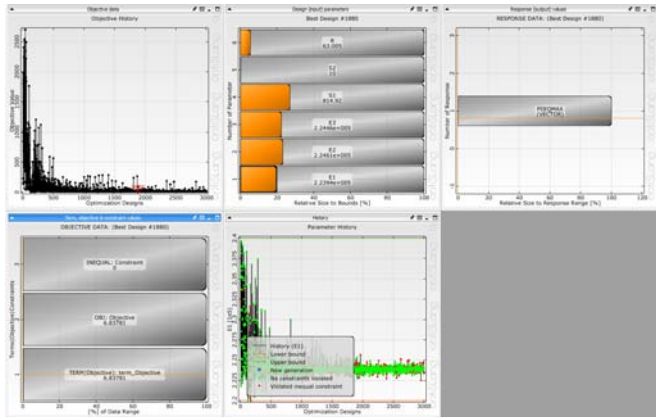
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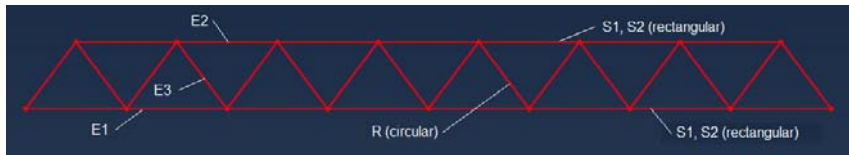
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optiSLang-Gui particle swarm



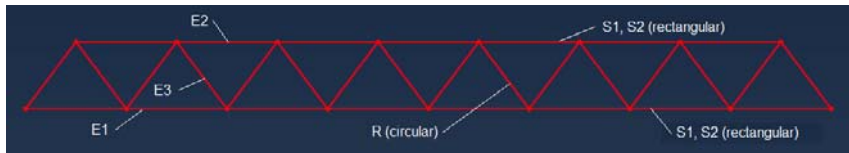
TRUSS STRUCTURE – COMPARISON OF RESULTS



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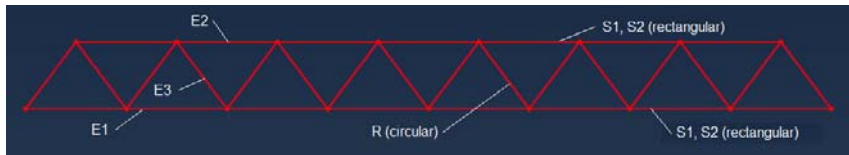


Objective value: MASS
Constraint: PEEQ = 0

Bounds:

S1	S2	R	E1	E2	E3
10	10	10	220000	220000	220000
3000	3000	1000	240001	240001	240001

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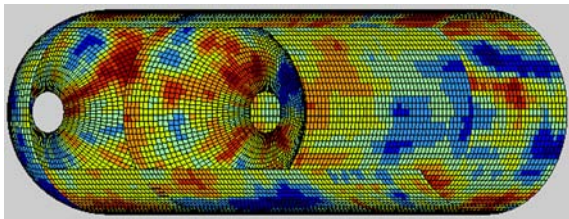
	Function calls	Mass	S1	S2	R	E1	E2	E3
GA - GRADE	1620	6.98346	828.30	10.00	63.78	240001	222901	220000
Nelder-Mead	349	6.80596	799.27	10.11	62.95	223330	238207	228351
GA - optiSLang	1528	6.85535	817.40	10.00	63.07	229650	220620	220960
PS - optiSLang	1996	6.08253	730.28	10.00	59.26	223280	229500	224290

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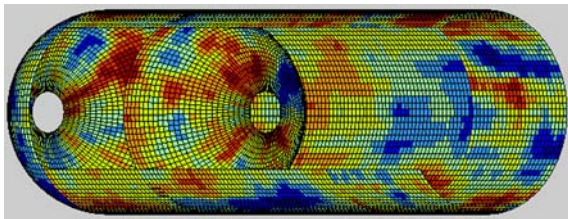
RANDOM FIELD MODELLING (1)

A random field on the small launcher model (material properties)



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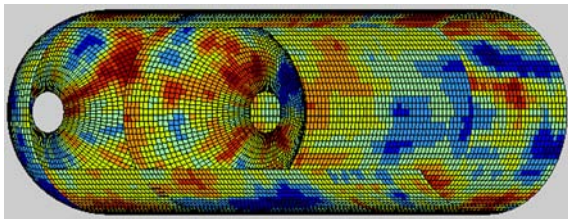
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Typical autocovariance function

$$\text{COV}(X_P, X_Q) = \sigma^2 \exp(-\text{dist}_1(P, Q)/l_1) \exp(-\text{dist}_2(P, Q)/l_2)$$



Exemplary application:

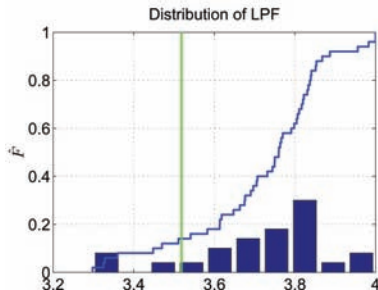
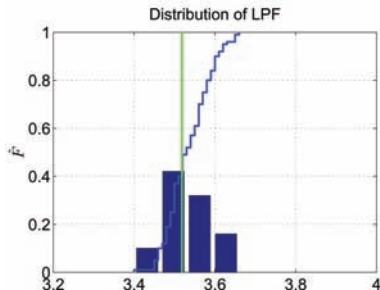
- Loads as random variables as before
- Material properties as random fields
- **Question:** Change of output with/without random field

RANDOM FIELD MODELLING (2)

Exemplary application:

- Loads as random variables as before
- Material properties as random fields
- **Question:** Change of output with/without random field

Example – change of distribution of load proportionality factor LPF without random field (left) and with random field (right):



Thank you for your attention!