

# Optimization in a nutshell – Introducing *optiLang* to Master's students

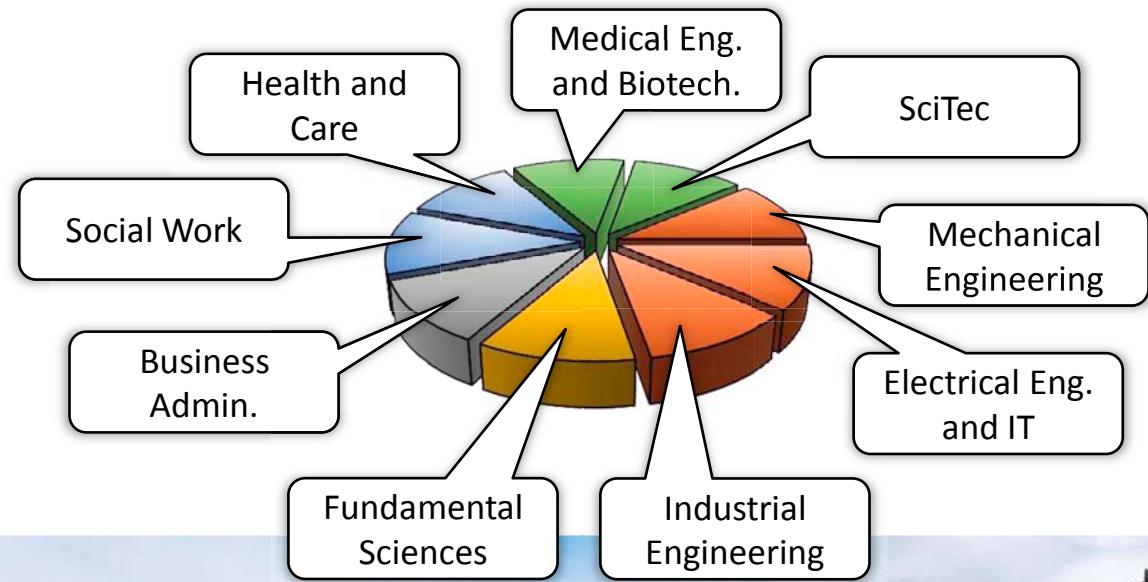
Prof. Dr.-Ing. Frank Dienerowitz



# Welcome to our university!

## ***Ernst-Abbe-Hochschule Jena*** ***University of Applied Sciences***

4'700 Students  
400 employees  
125 professors



source: EAH Jena

My customers  
Master's Course "Scientific Instrumentation"

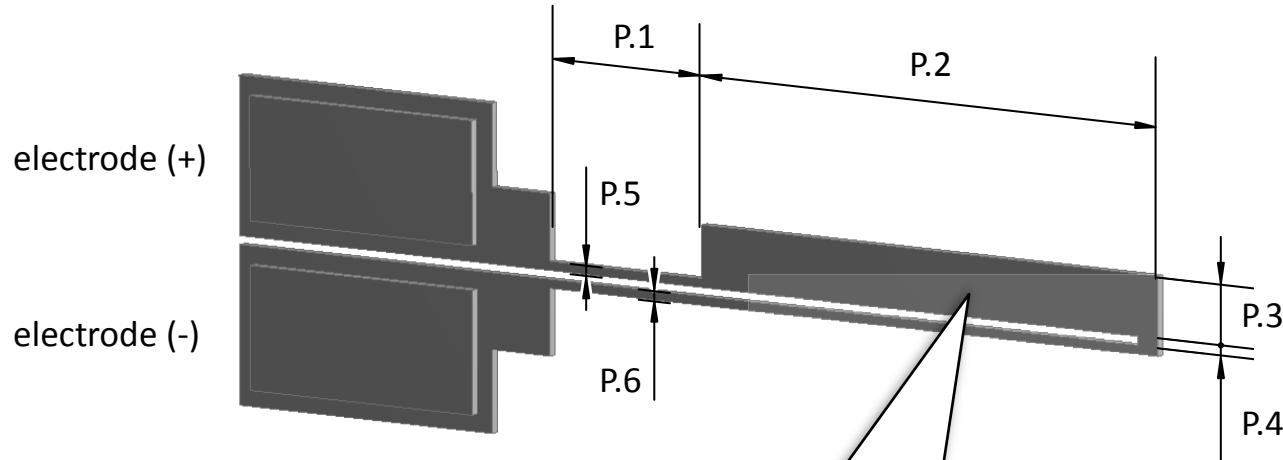
- *Ba.Eng. / Ba.Sc.:* Electrical, Mechanical, Physics, C&I
- fairly "normal" math and IT-skills



They will most certainly encounter  
“optimisation” in their career!

source: EAH Jena

Typical Challenge  
Improve the design!



**MEMS actuator**

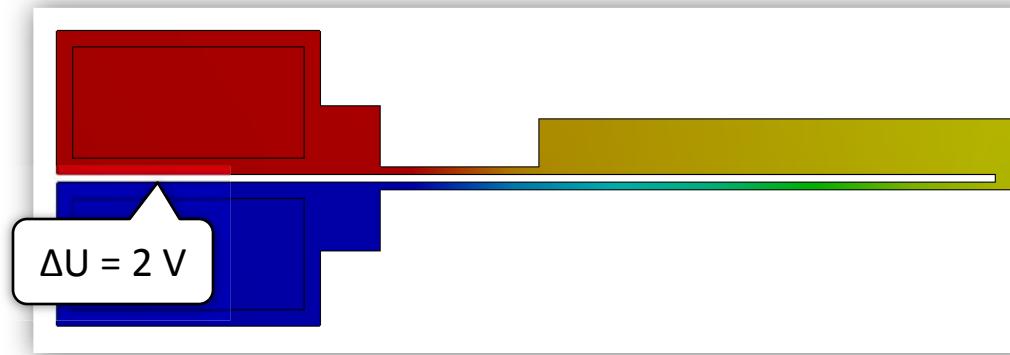
- made of polysilicon
- blade length 3 mm
- thickness 50  $\mu\text{m}$



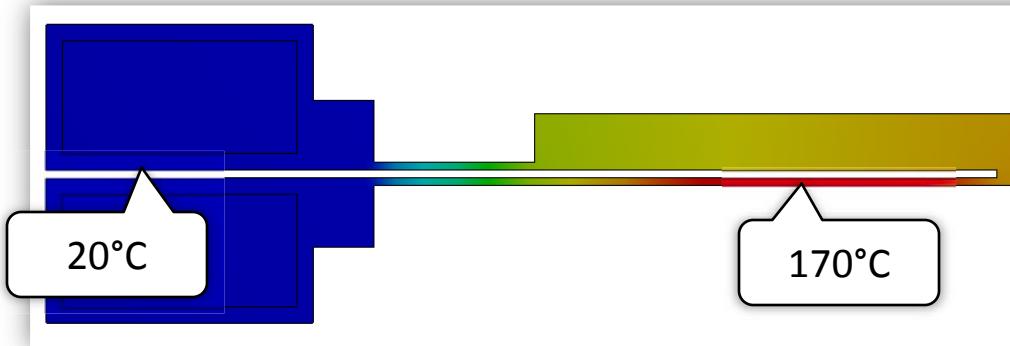
source:  
Ansys WB 14.5  
tutorial

Typical Challenge  
Improve the design!

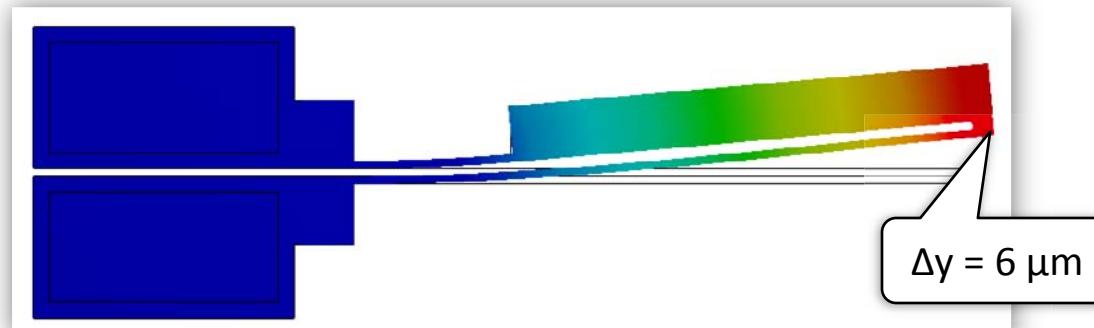
Electrical  
Potential



Temperature  
Field



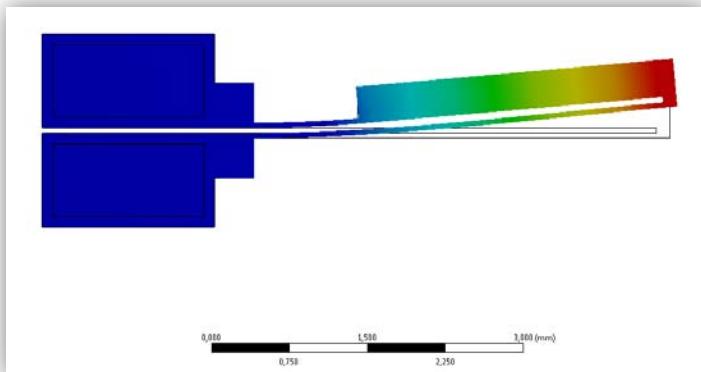
Displacement  
Field



## Typical Challenge Improve the design!

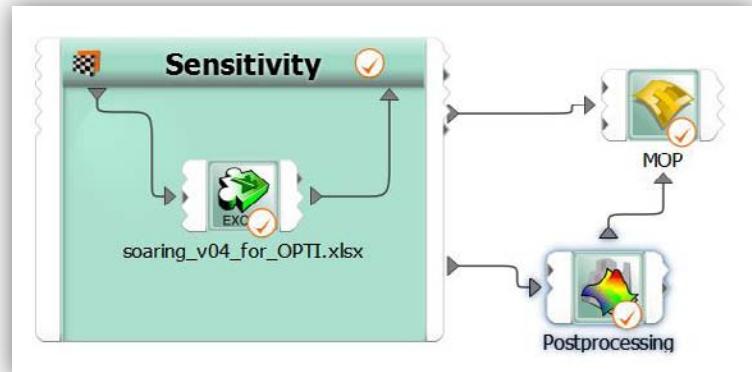
Plan A:

“making it up as you go along”



Plan B:

“best practice”



1. setup experiment and begin exploring a somewhat “defined” design space
2. realise: applying the “typical” full factorial DoE sampling restricts the number of parameters to be explored
3. conclude a rather limited “optimisation”

1. develop a parametric model of the problem; define design space, objective and constraints
2. setup experiment and interface with optimisation tool
3. explore and optimise the design in true 21<sup>th</sup> century fashion

conclusion: I need a bare-essentials optimisation course for my students!

# Course Outline

## Part 1 - Lecture

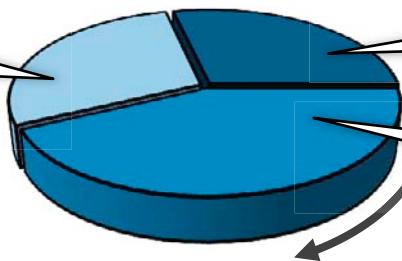
### Introduction

1 hour

Models and Parameters

Typical Workflow

Motivation



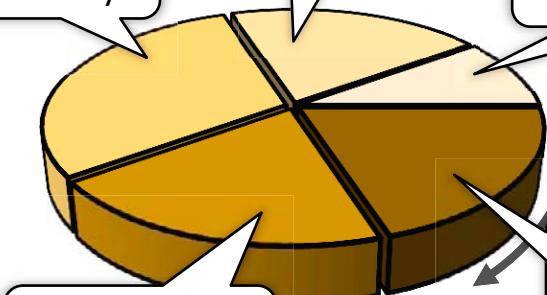
### Sensitivity Analysis

2 hours

Evaluating Sensitivity

MOP

Parallel Coordinates Plot



"Advanced" DoE Schemes

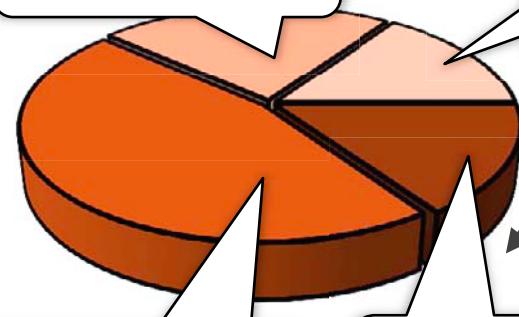
"Simple" DoE Schemes

### Optimisation

1.5 hours

Multiple Objective Optimisation

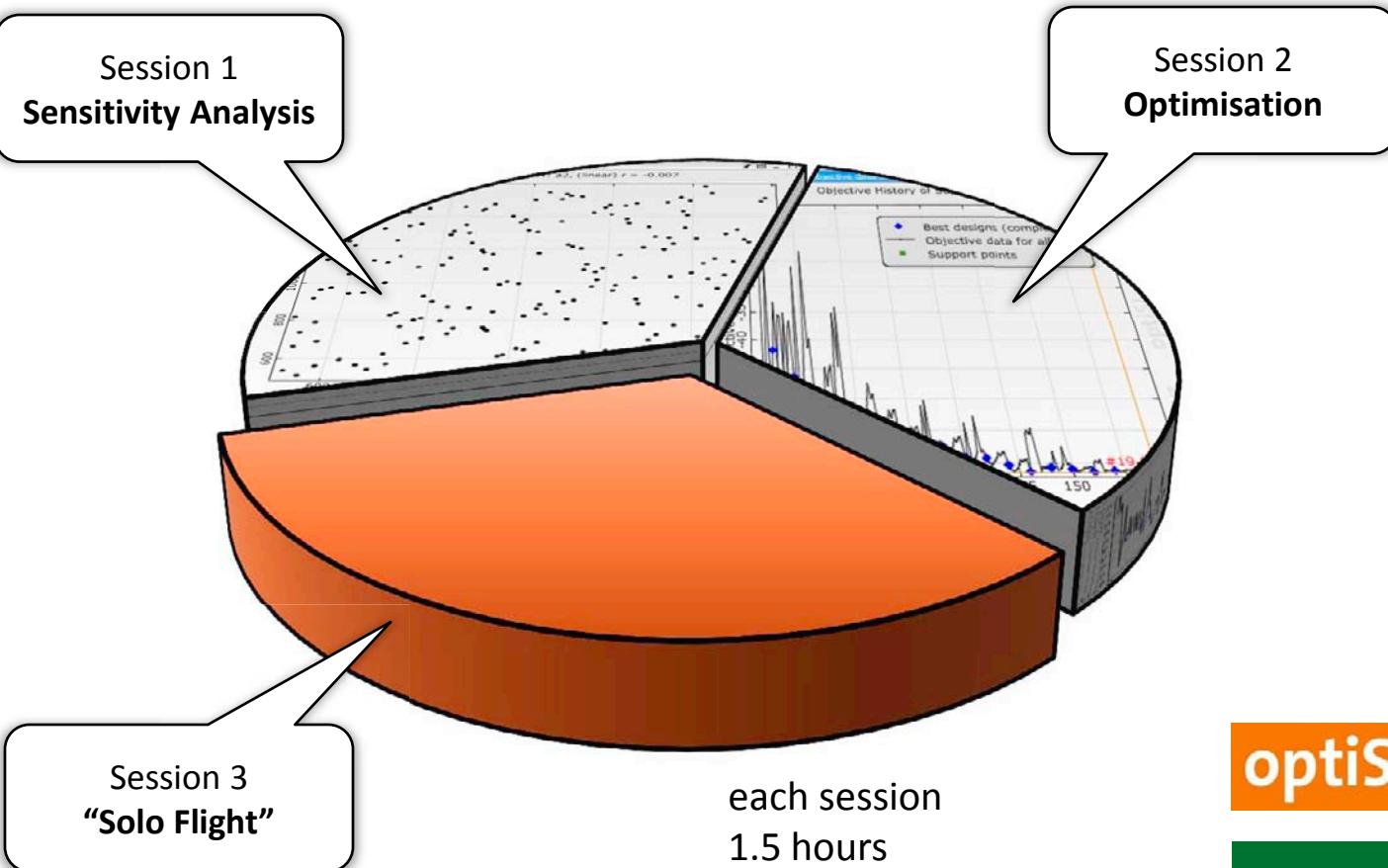
Robust Design



Methods (Gradient, Simplex, ARSM, EA)

Objective Function, Design Space & Constraints

Course Outline  
**Part 2 – Computer Lab**



**optiSLang®**



## Course Outline

### Part 2 – Computer Lab – The “Solo Flight”

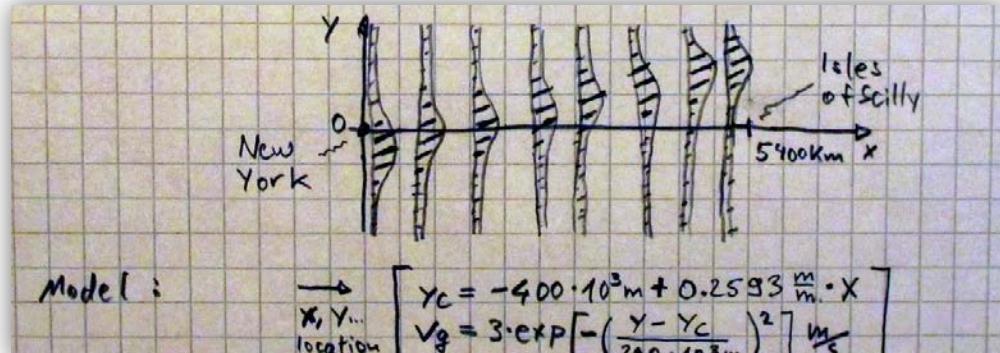
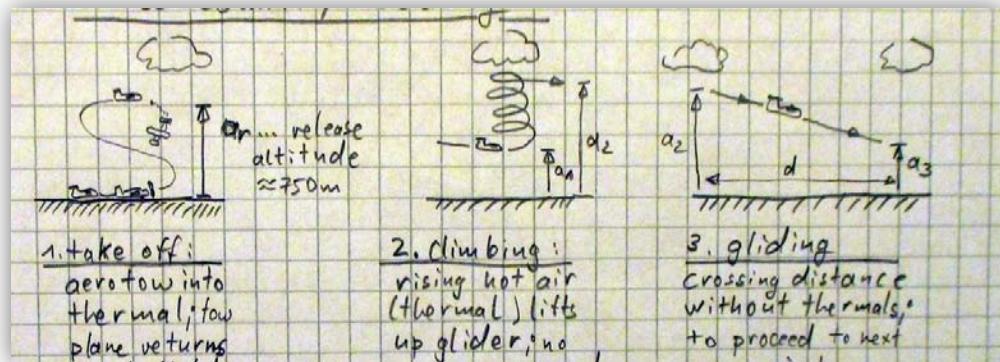
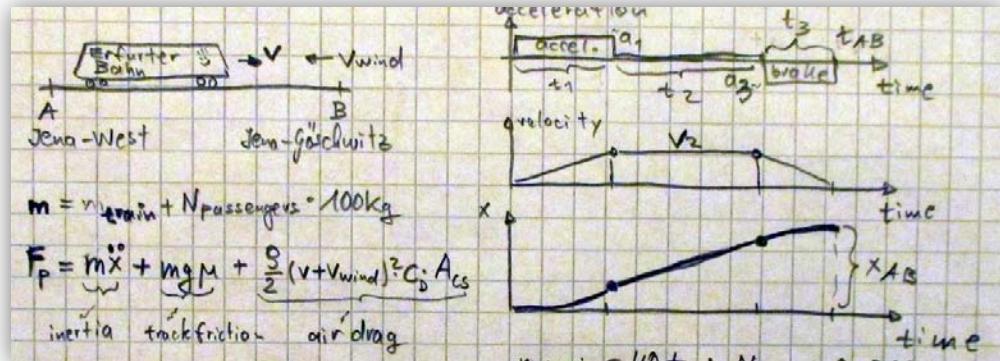
#### Railway Fuel Efficiency



#### Cross Country Soaring



#### Blue Riband of the Atlantic



# Course Outline

## Topics we can't explore ... for now!

the contents of our  
***bare-essentials*** course:

- a few parameters
- deterministic, continuous
- single objective optimisation
- solver: MS Excel

stochastic and  
discrete parameters

developing a good  
parametric model

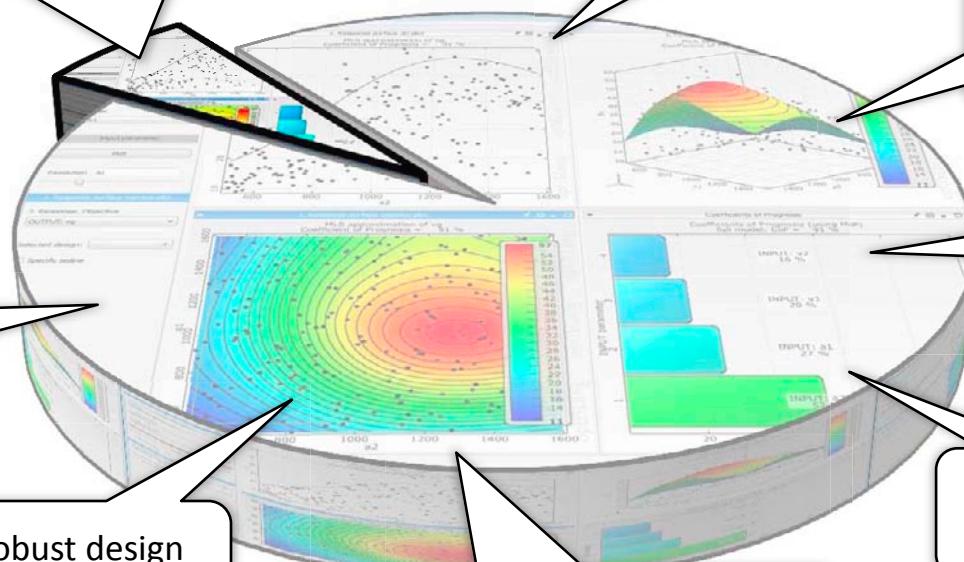
direct vs. model  
based optimisation

and many  
other topics ...

loads of  
parameters

robust design  
optimisation

interfacing with ANSYS,  
Matlab, SimulationX etc



# Computational Landscape

## The model and the optimisation problem

**model:** 
$$z(x, y) = \sum_{i=1}^5 c_i \cdot \exp \left[ -\frac{(x - a_i)^2}{\pi} - \frac{(y - b_i)^2}{\pi} \right] \cdot \cos [\pi(x - a_i)^2 + \pi(y - b_i)^2]$$
$$a = [3, 5, 2, 1, 7], b = [5, 2, 1, 4, 9], c = [1, 2, 5, 3, 3]$$

**design space:**  $3.0 \leq x \leq 4.0$  longitude  
 $3.8 \leq y \leq 4.8$  latitude

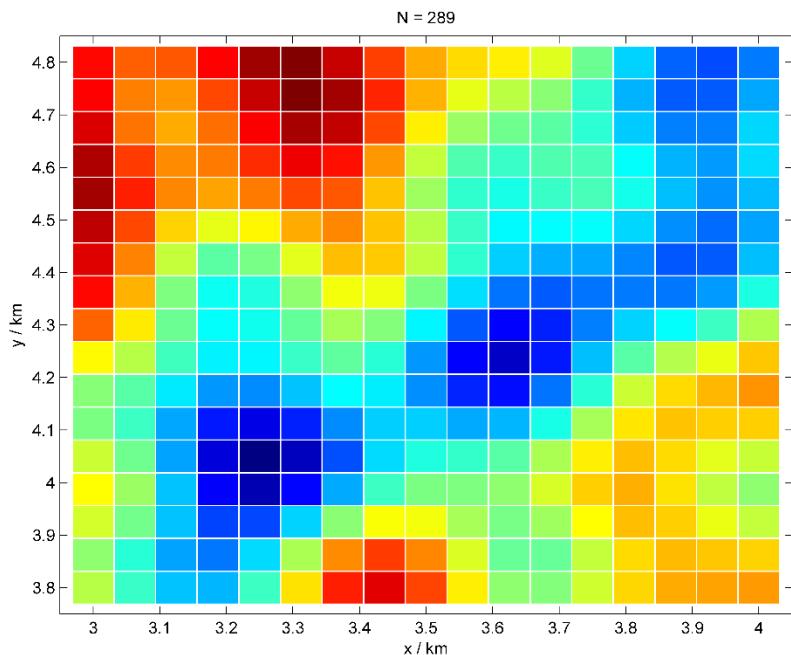
**objective:**  $z \rightarrow \min!$  “locate the deepest valley!”

source:  
*Test functions for optimization needs*  
MARCIN MOLGA, Czesław SMUTNICKI,  
2005

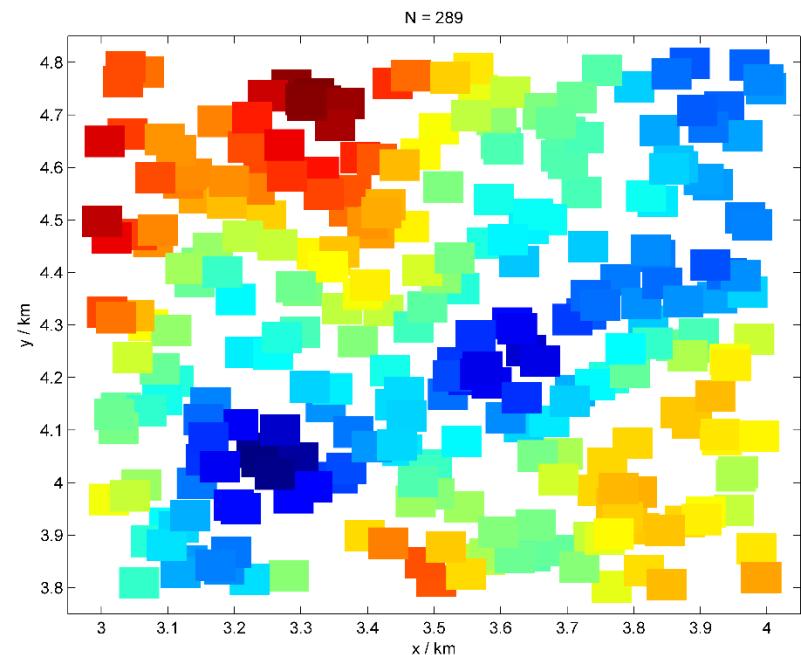


# Computational Landscape Probing the Unknown: $N = 9, 25, 81, 289$

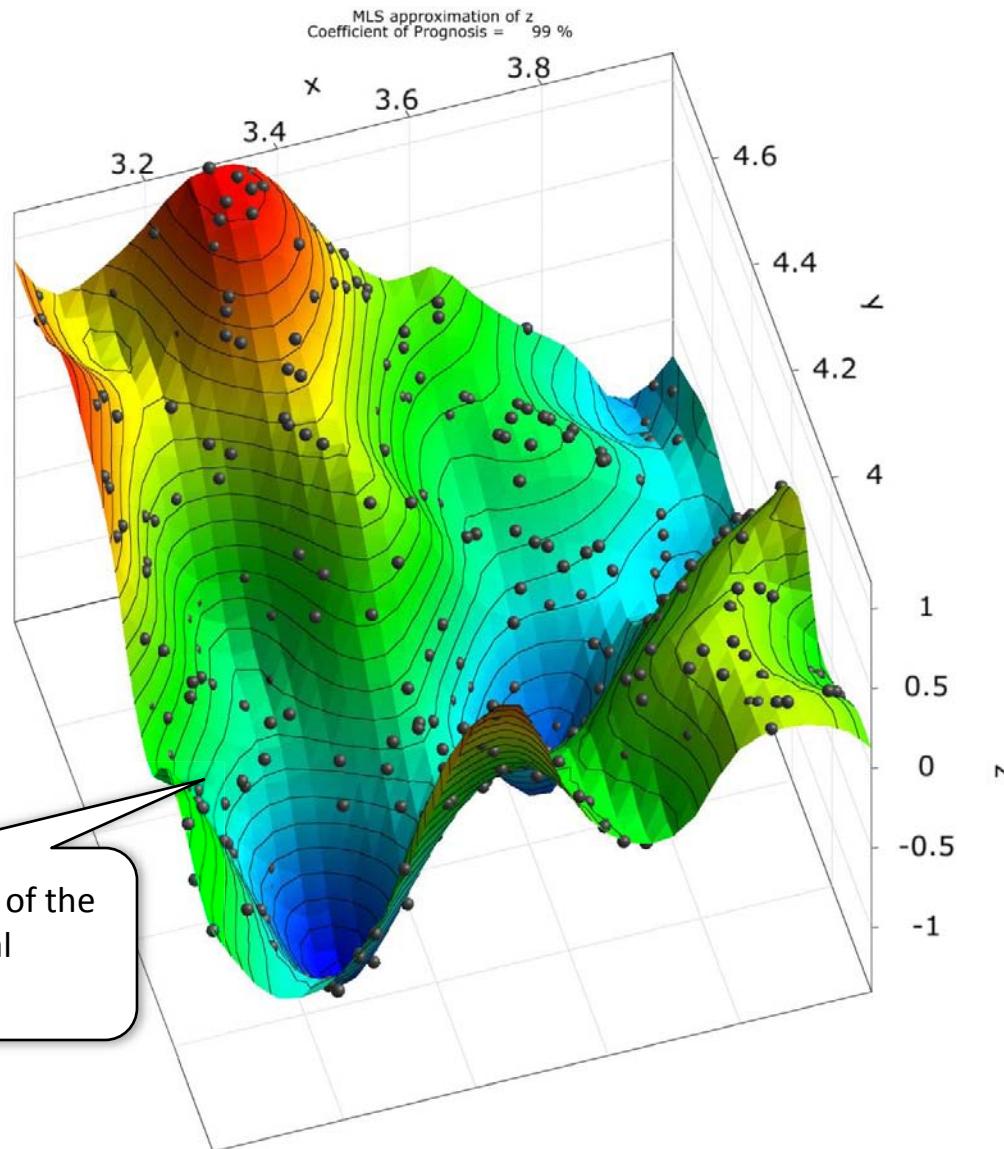
DoE scheme  
**Full Factorial**



DoE scheme  
**Adv. Latin Hypercube Sampling**

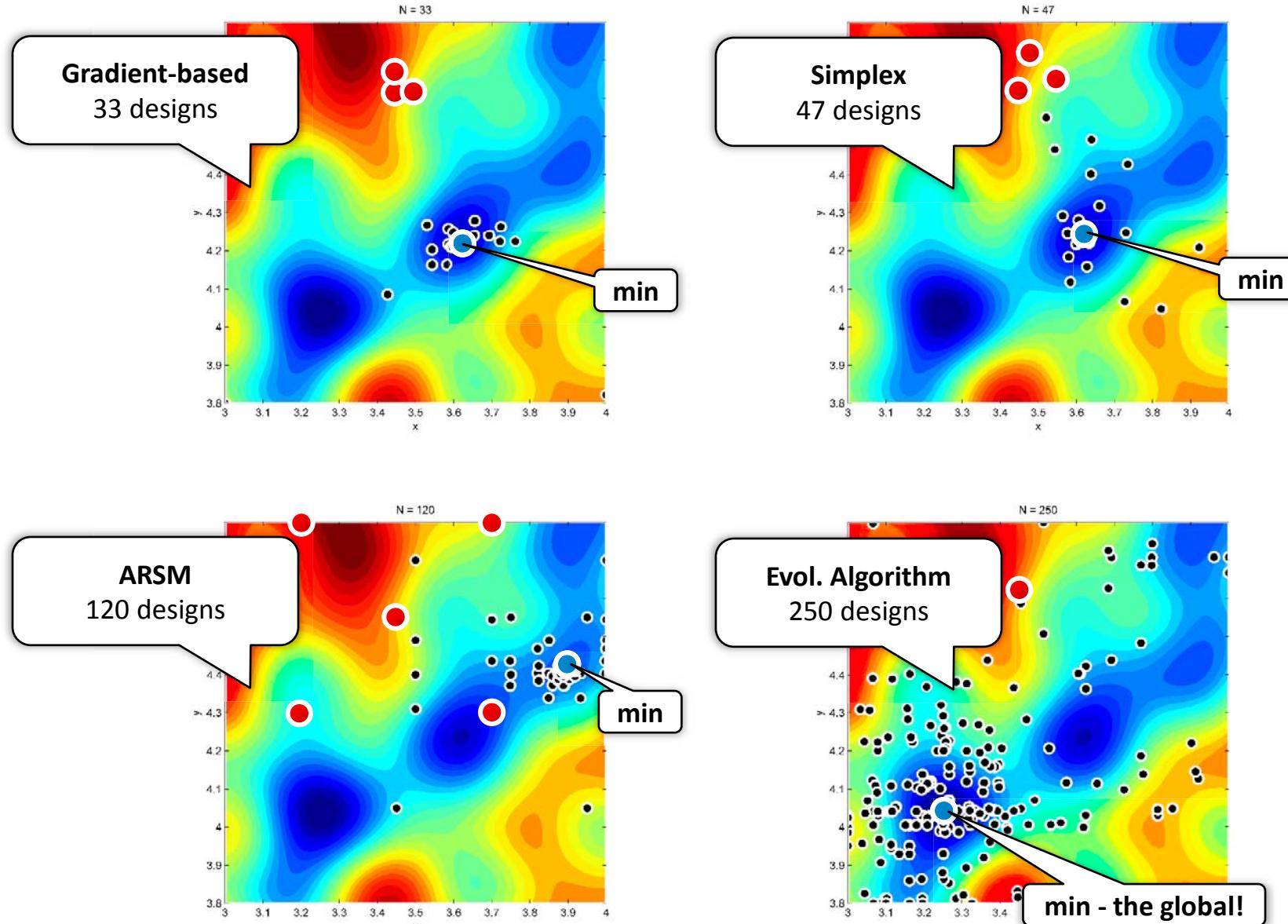


# Computational Landscape Above the tree tops – The M.O.P.



# Computational Landscape

## The optimisation methods visualised



# Cycling Time Trial

## The model and the optimisation problem

**model:**

$$F_d = m \cdot g \cdot \sin \alpha \quad \text{downward force}$$

$$F_f = \mu \cdot m \cdot g \cdot \cos \alpha \quad \text{road friction}$$

$$F_a = k_1 \cdot v^2 \quad \text{air drag}$$

---


$$F_p = F_d + F_f + F_a \quad \text{propulsion force}$$

---


$$P_r = \begin{cases} F_p \geq 0: = F_p \cdot v \\ F_p < 0: = 0 \end{cases} \quad \text{required human power}$$

---


$$rf = C_1 + C_2 \cdot P_r^3 \quad \text{rate of fatigue}$$

---


$$f = rf \cdot t \quad \text{fatigue}$$

**objective:**

$$v_{avg} \rightarrow max!$$

**“maximise  
average velocity!”**

**constraint:**

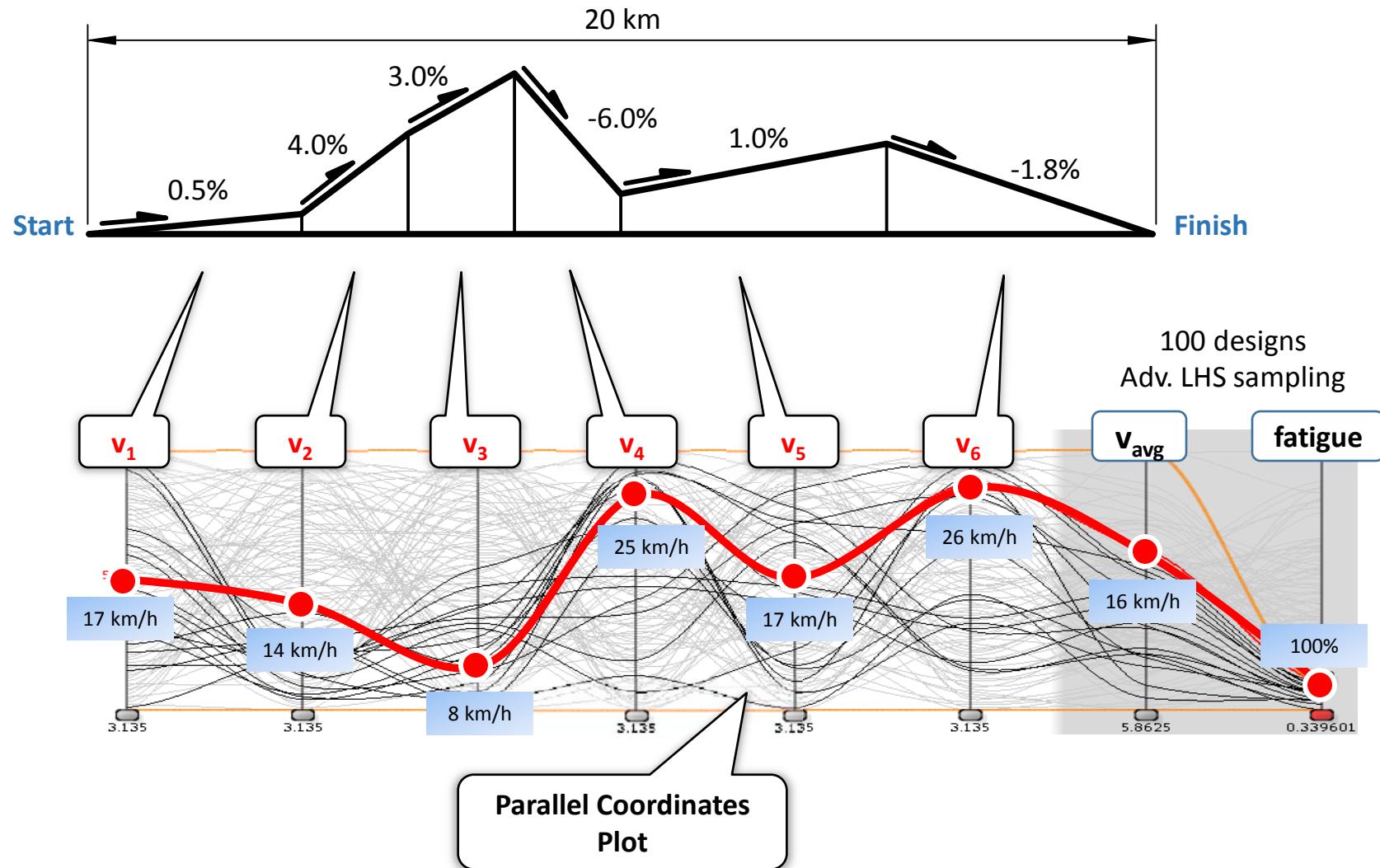
$$f_{AB} = \sum_{i=1}^{N_{sec}} f_i \leq 100\% \quad$$

**“total fatigue accumulated over all  
track sections less than 100%!”**



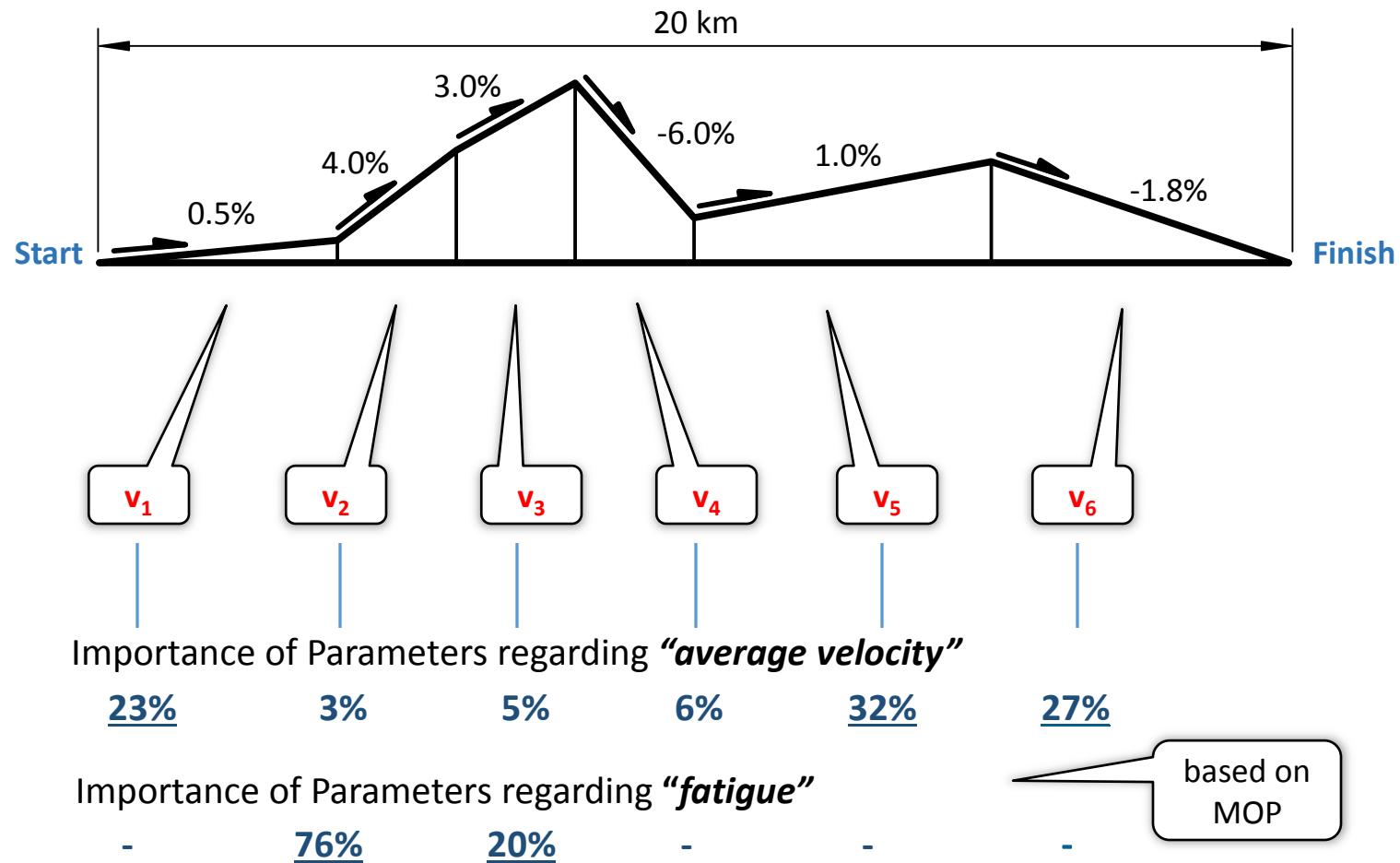
# Cycling Time Trial

## Making sense of the design parameters



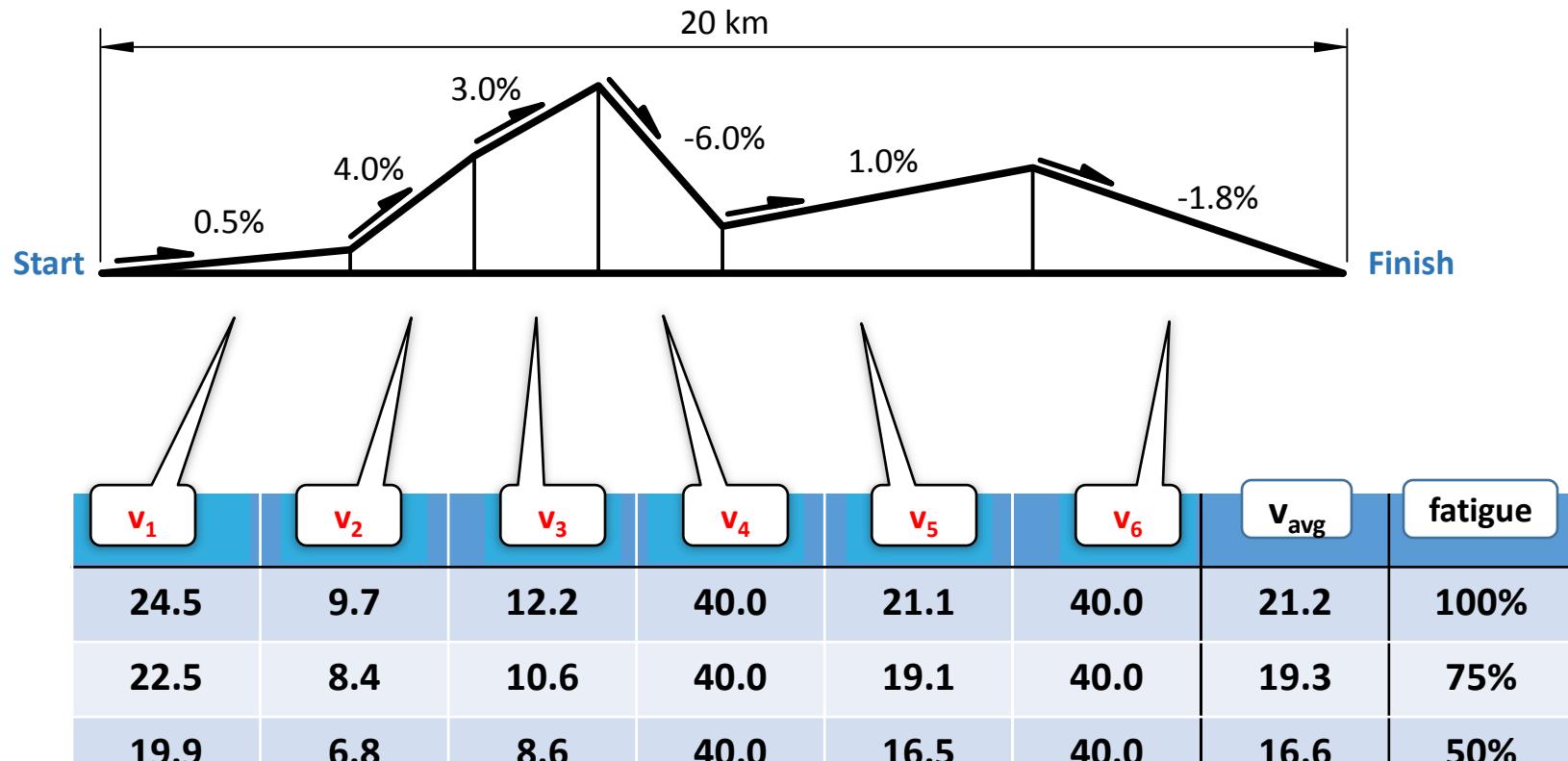
# Cycling Time Trial

## Making sense of the design parameters



# Cycling Time Trial

## The optimal race strategy



by the way: 40 km/h  
is the limit of my  
comfort zone

Farewell  
Get in touch. We do love optimisation!

**Ernst-Abbe-Hochschule Jena**

**Department SciTec**

[frank.dienerowitz@fh-jena.de](mailto:frank.dienerowitz@fh-jena.de)

