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Simplified method to predict structural properties of cardio-vascular stents based on Design of Experiments (DOE)



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Table of contents

Introduction

- Anatomy, diseases, TAVI and biomechanics
- Stent attributes and development process

Method

- CAD, FEA
- Statistics

Results

- Validation with experiments
- Statistical model and MOP

Discussion



Introduction anatomy and diseases

- Aortic valve with aortic stenosis (calcified leaflets)
- Insufficient valve opening during systole (decreased blood flow)
- Increased muscle activity in the left ventricle



Severe Aortic Stenosis

Source: Health Care Utah



4

Introduction TAVI (Transcatheter Aortic Valve Implantation)

- Patients suffering from aortic stenosis
- Not suitable for conventional open heart surgery
- Minimal invasive approach (commonly transfermoral)
- First-in-man in 2002 (Alain Cribier)

Todays market leaders:

Self expanding (Medtronic) or balloon expandable (Edwards)





CoCr Frame

G. Webb, 2012



5

Introduction Biomechanics

- TAVI stents in vivo loads:
 - → radial loads

 (pulsatile vessel movement)
 → multi-axial loads
 (resulting from closed valve)





ISO Norm 5840-3



Introduction Radial force

- TAVI stents (Nitinol) require radial force to
 - \rightarrow allow immediate release from catheter
 - \rightarrow provide anchorage to annulus and prevent migration
 - \rightarrow avoid paravalvular leakage



Experimental radial force setup



Typical radial force curve for a Nitinol stent showing the loading and unloading plateau



Introduction Fatigue Resistance

- TAVI stents require
 - \rightarrow fatigue resistance (at least 400 mill. cycles)





Introduction Classic Design Process

- (1) Idea \rightarrow CAD design concept
- (2) Parametric CAD model
- (3) Finite Element model with boundary conditions
- (4) Results for product life cycle loads
- (5) Evaluation and next Design Loop



Time and cost intensive



http://www.leapaust.com.au



9



Design of Experiments and statistical modelling are suitable tools to estimate structural properties of stents

and accelerate the initial design phase





Method

- Most stents show a closed cell design (diamond cells)
- Whole structure can be reduced to a single diamond cell
- Diamond cell consists of at least 2 identical struts
- Main loading modes (radial loads) can be simulated with one cell



CoreValve stent



Diamond shaped stent structures (Dordoni et al. 2015)





 Parametric CAD model of single strut with design variables (Solid Edge ST6)

SBK=Strut width at knot; SBM=Strut width in the middle; WS=Wall thickness; SR= Strut radius at the knot; SL=Strut length





Method FEA Ansys Workbench 14.5

- Parametric FEA model created with Workbench 14.5
- 3D model with solid 185 elements, Nitinol material
- Rigid shells with nonlinear contact





Method Workflow Optislang 4.1.2

- Design of Experiments DOE (Advanced Latin HyperCube) with 75 Design points
- Subsequent MOP (Meta-Model of Optimal Prognosis)

Input Parameters		
🖃 🚾 Static Structural (B1)		
🛱 P20	DS_WS	0,47
🛱 P23	DS_SBK	0,3
🛱 P24	DS_SR	0,15
🛱 P22	DS_SL	5,4
ι <mark>ρ</mark> Ρ21	DS_SBM	0,24







 Image: Static Structural (B1)

 Image: P19
 my_fsum4

 Image: P18
 my_fsum3

 Image: P17
 my_fsum2

 Image: P16
 my_fsum1

 Image: P15
 my_ampl

FEA Model





Method Load Cases

- Single cell initially expanded and shape setted (heat treatment)
- loaded and unloaded from 29mm to 5.4mm diameter
- Cyclic loading of a circular annulus (diameter change of 4.5%) simulating one cardiac cycle
- Evaluation of radial force and strain amplitude





Crimp shells and expanded stent model

crimped stent model



Method Evaluation Radial Force

 A stent could be regarded as a row of springs allowing to sum up the radial forces of each diamond cell and for all segments



my_fsum1 = -18,78 + 5,423 DS_SL + 19,2 DS_SR - 86,99 DS_SBK - 21,13 DS_SBM

my_fsum2 = -12,65 + 4,608 DS_SL + 22,1 DS_SR - 104,85 DS_SBK - 18,71 DS_SBM

my_fsum3 = -4,47 + 1,760 DS_SL + 8,95 DS_SR - 45,48 DS_SBK - 6,48 DS_SBM

my fsum4 = -4,75 + 1,773 DS SL + 6,79 DS SR - 43,24 DS SBK - 5,81 DS SBM

my_ampl = 0,004999 - 0,000831 DS_SL - 0,00109 DS_SR + 0,005522 DS_SBK + 0,004700 DS_SBM



Results Validation

Comparison of experimental and numerical model



	Exp. vs FEA	Exp. vs Stat
	Delta	Delta
	[%]	[%]
RRF 26mm	-2.88	10.80
RRF 23mm	-1.92	5.84
COF 26mm	5.73	-11.66
COF 23mm	6.36	-9.90
mean (abs)	4.22	9.55





Results Validation+Prediction

Comparison of experimental and statistical model



	DS_SL	DS_SBK	DS_SBM	DS_SR
Zelle	[mm]	[mm]	[mm]	[mm]
Α	6.3	0.3	0.2	0.08
В	7	0.31	0.2	0.08
Zusatz				
Boundaries	max	max	max	max
	8	0.4	0.27	0.06
	min	min	min	min
	4	0.28	0.18	0.12



	Exp. vs FEA	Exp. vs Stat
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Results radial force

Response surface for the radial force fsum3 = COF23mm

SBK=Strut width at knot; SBM=Strut width in the middle; WS=Wall thickness; SR= Strut radius at the knot; SL=Strut length



Highly accurate nonlinear model CoP = 96%



Results strain amplitude

Response surface for the max. strain amplitude

SBK=Strut width at knot; SBM=Strut width in the middle; WS=Wall thickness; SR= Strut radius at the knot; SL=Strut length





Highly accurate nonlinear model CoP = 97%



Results MOP example



- MOP surface allows prediction of design points on the response surface
- Approach is less errorous than linear regression models



Discussion

- Design of experiments (DOE) is a powerful tool to create statistical meaningful (well distributed) results data sets
- Linear regression provides a fair model for a priori prediction
- A simple Excel based prediction tool was developed allowing a priori prediction of structural properties in less than 1 minute
- MOP approach delivers highly nonlinear and accurate response surfaces
- MOP might be a preferable tool to predict **accurate** design outcomes

Conclusion

 Initial design phase can be accelerated by simplified statistical prediction models which deliver a fair estimation of mechanical stent behavior



Future perspectives



- Multi-Axial loads can be applied to single diamond cell like they appear in hart valve stents
- This allows tuning designs to different loading modes (radial, axial, bending, torsion)



Statistical modelling





Old Greece?



Statistical modelling





Thank You for the attention



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