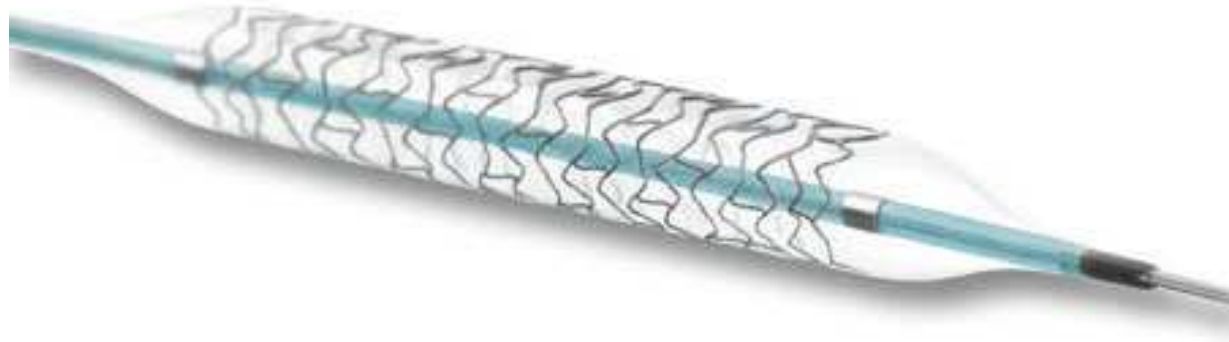



# Optimization Strategies for the Development of Vascular Stents.

Nils Götzen  
André Schoof



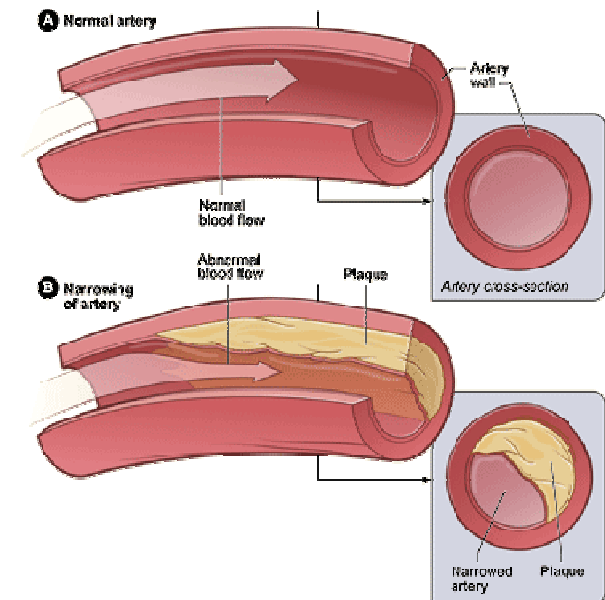
# Agenda

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- 
- A large, light-colored graphic on the left side of the slide, featuring the letters 'B' and 'C' in a stylized, 3D-like font. The 'B' is on the left and the 'C' is on the right, both appearing to be part of a larger structure.
- Introduction
  - Stent Development
  - Design Optimization
  - Optimization Strategy
  - Conclusion & Outlook

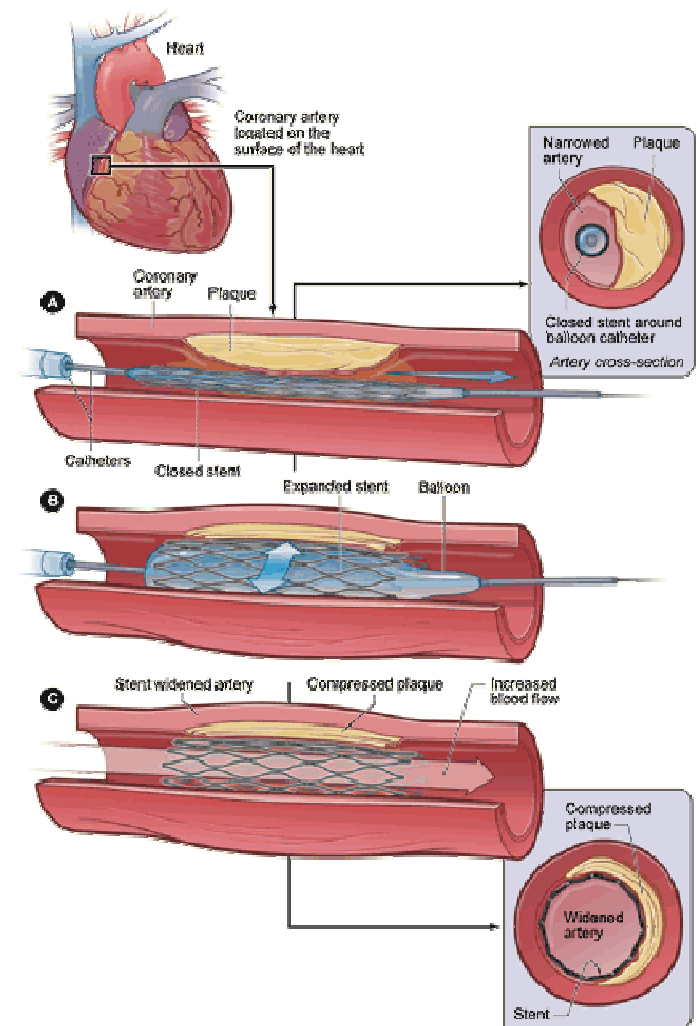
## Coronary Angioplasty With Stent Placement

- Atherosclerosis is plaque build-up inside the coronary arteries
- most common type of heart disease
- leading cause of death in EU/US
- lifestyle changes & medicines effective treatment at early stage of the disease



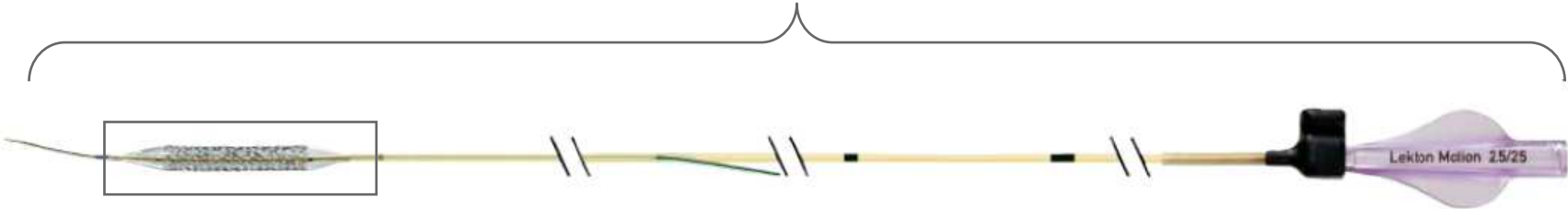
## Coronary Angioplasty With Stent Placement

- one of the most important achievements of the last years in interventional cardiology
- balloon is inflated to compress the plaque
- stent expands and attaches to the artery wall
- stent stabilizes opened vessel until the healing process has finished



## Stent System Assembly

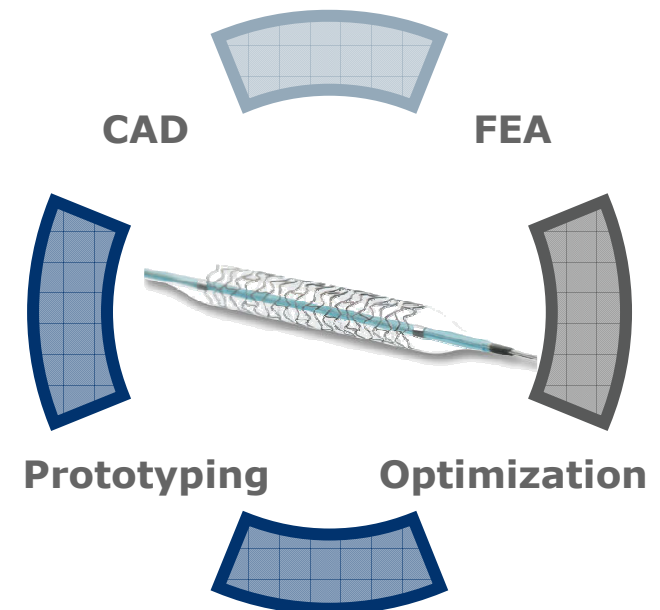
Stent-Delivery-System



Stent mounted on Delivery System

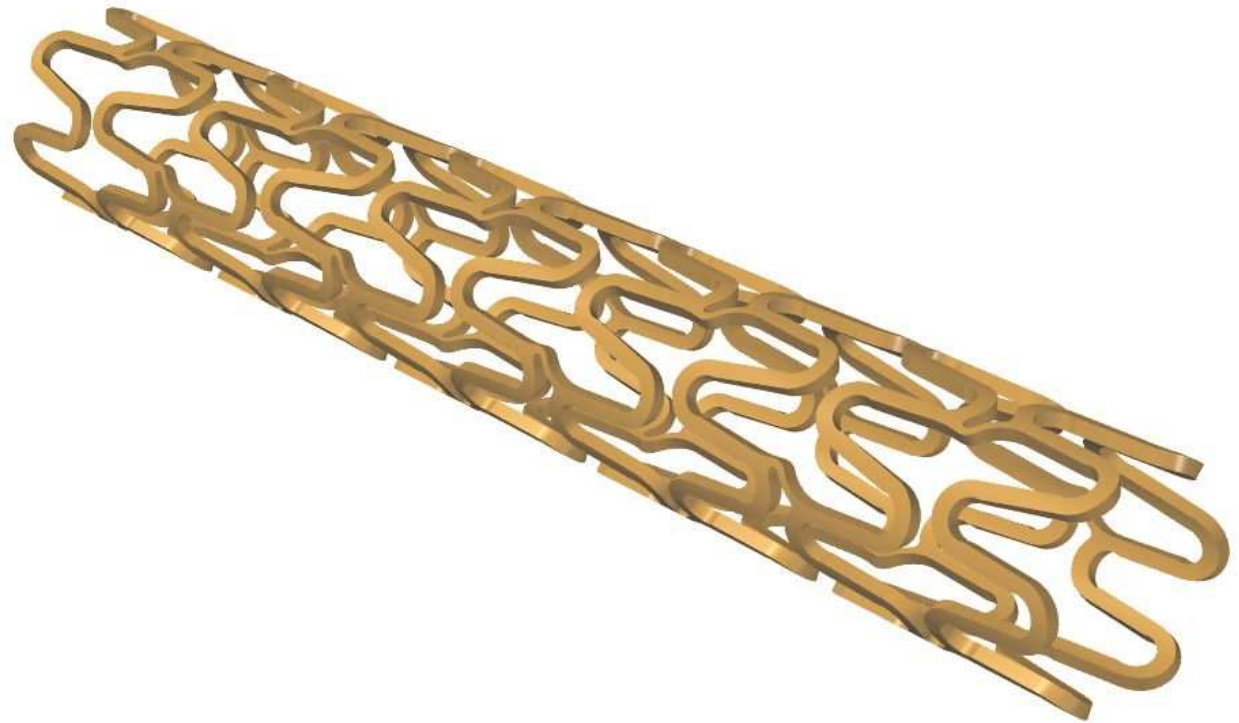
## Design Development Circle

- closely integrated CAD + FEA is used from the early development phase on
- parametric CAD geometry
- numerical evaluation
- parameter analysis + optimization
- prototyping + experimental evaluation



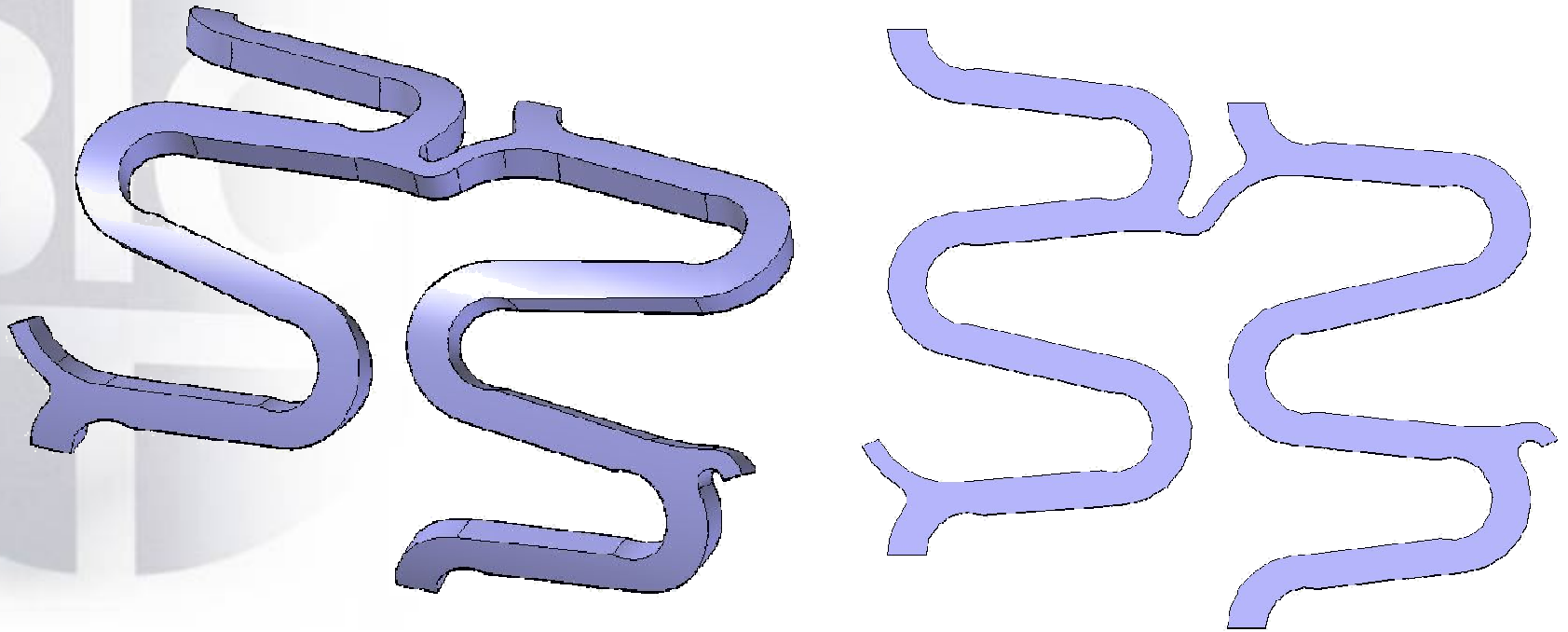
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## From 3D to 2D and back again



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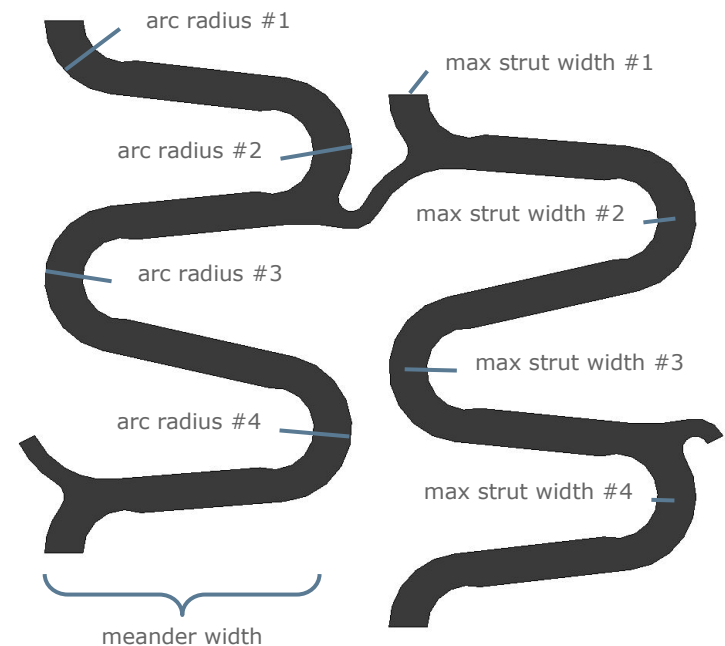
## From 3D to 2D and back again





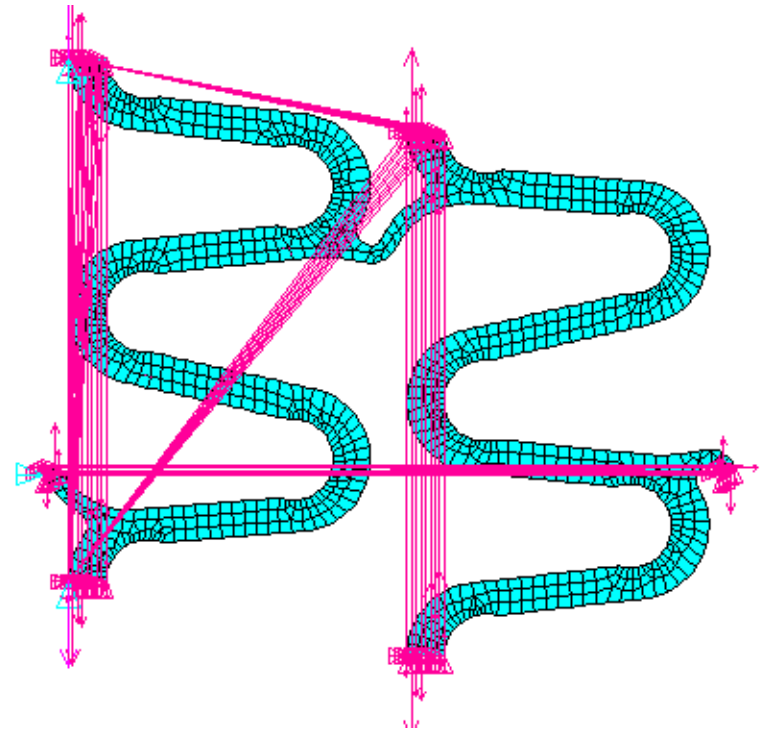
## Strategy – CAD

- parametric geometry model with Solid Edge
- independent design features are important for minimum of cross-correlation
- geometry parameters
  - meander width
  - outer crown arc radii
  - inner crown arc radii
  - strut widths
  - strut angle
  - offset values etc.



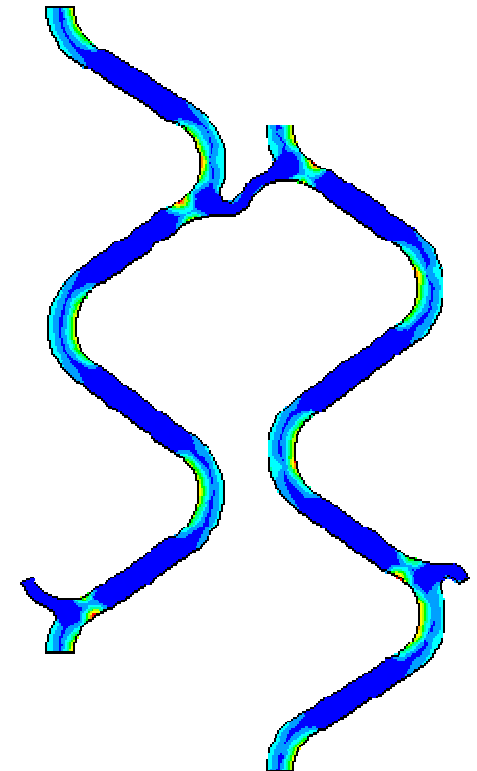
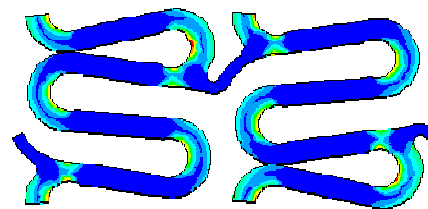
## Strategy – FEA

- FE model generation in ANSYS Workbench (WB) bi-directional interface with Solid Edge
- cyclic BC with CEs (APDL scripts)
- non-linear 2D Solution
  - non-linear material model
  - large strain kinematics
  - contact modeling



## Load Steps

- crimping – radial compression (mounting on balloon)
- dilatation – radial expansion (balloon expansion)
- recoil – radial spring back
- compliance – radial reaction force
- 18 load steps
- run time: ca. 2-4 min.



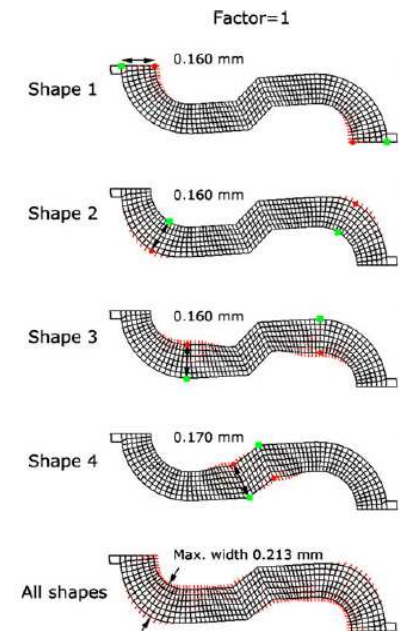
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## Strategy – FEA

- Script based post-processing in WB
- output parameter definition
  - equivalent plastic strain at arc radii
  - strain distribution in arcs
  - radial compliance
  - self contact forces
  - overall min. strut width
- export of WB to optiSLang project

## Review

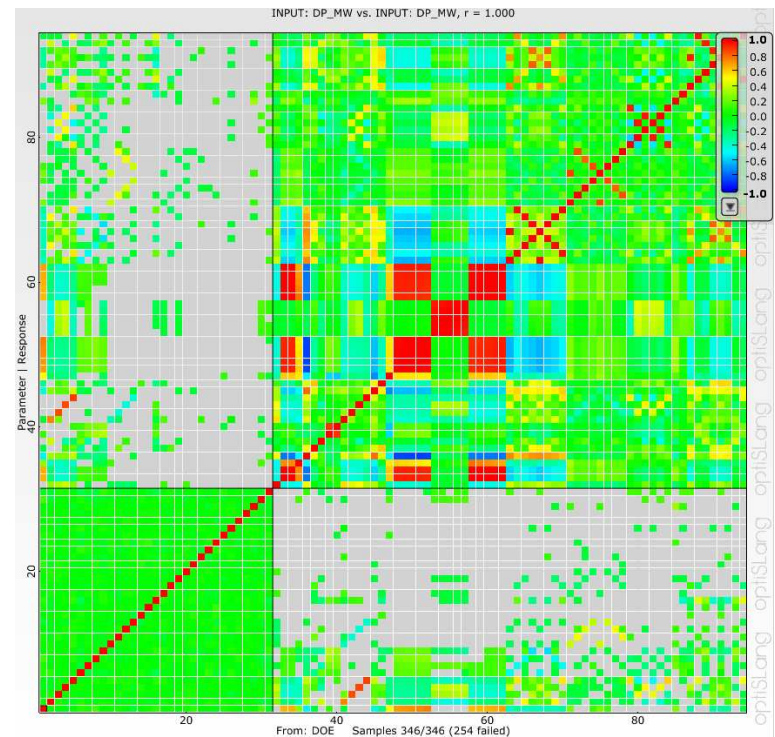
- in the past: optimization as “trial and error approach”
- sensitivity analyses of design parameters using WB Design-Xplorer – limited success
- recently few true optimization studies were published
- using parametric modeling in ANSYS Classics & RSM approach
- or mesh-morphing as modeling tool with ARSM approach
- reduced dimensions in design space



Source: Li, N., Zhang, H., Ouyang, H., 2009, Finite Elements in Analysis and Design  
Wu, W. et al., 2010, Annals of Biomedical Engineering

## Strategy – optiSLang – DOE

- prior to DOE, input parameters: 31 ; output parameters: 63
- definition of BCs & objective function
- objective function
  - compliance +
  - compliance range +
  - strain distribution (4x) +
  - mean contact forces +
  - var contact forces
- latin hypercube sampling
- $N = 600$  (wall clock  $\approx 12\text{h}$ )
- parameter range  $\approx \pm 20\%$

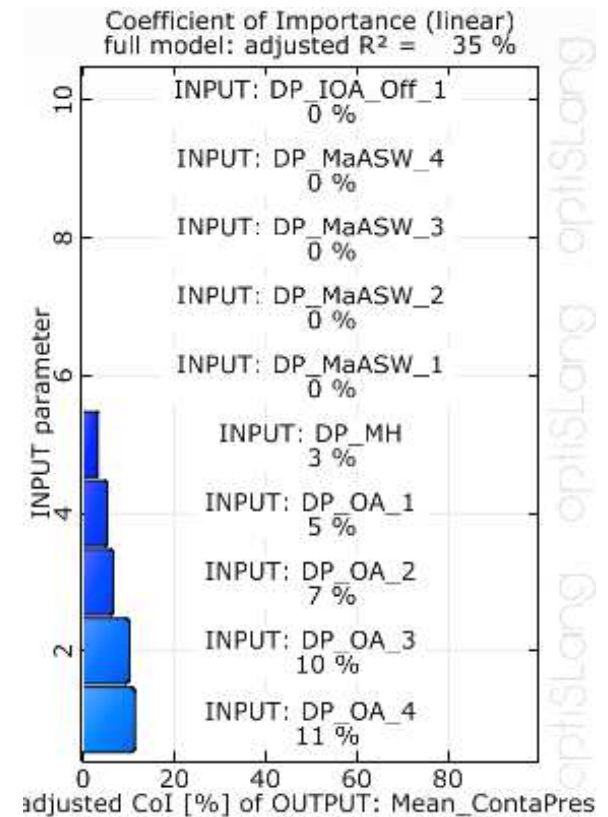
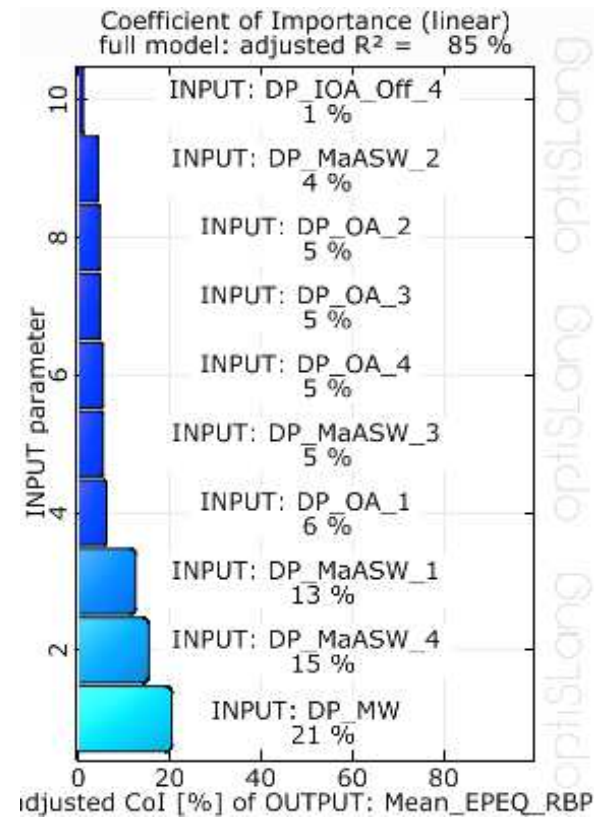
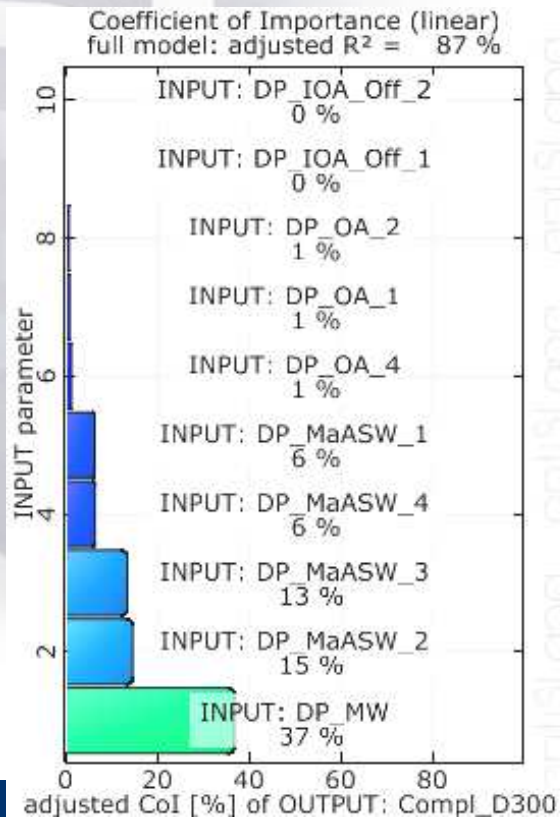


## Strategy – optiSLang – DOE

compliance

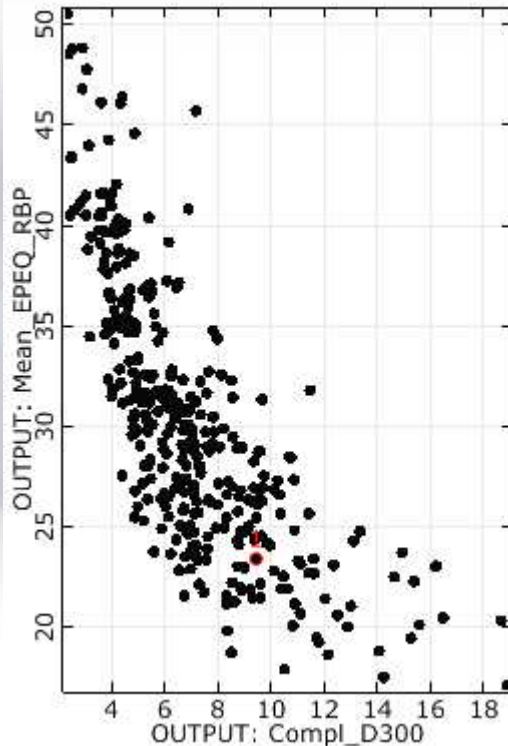
pl. strain

contact pressure

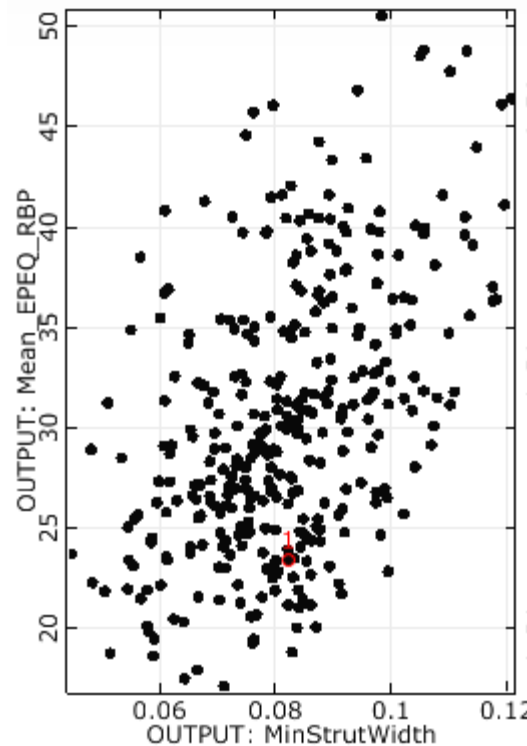


## Strategy – optiSLang – DOE

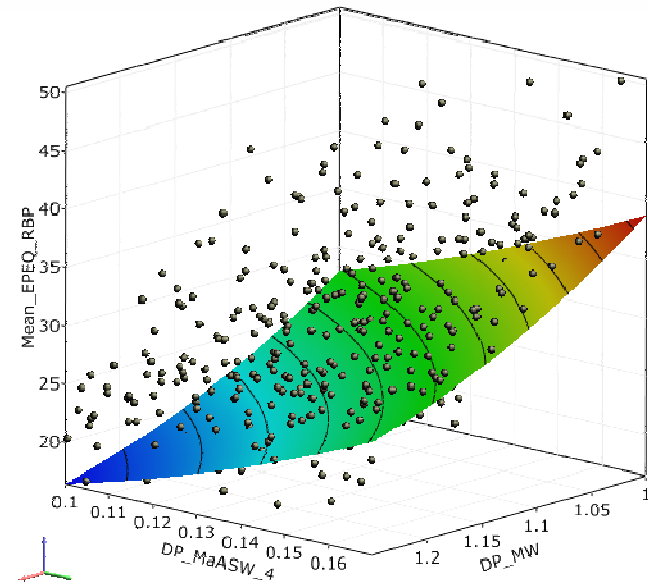
max. plastic strain  
vs. compliance



max. plastic strain  
vs. strut width

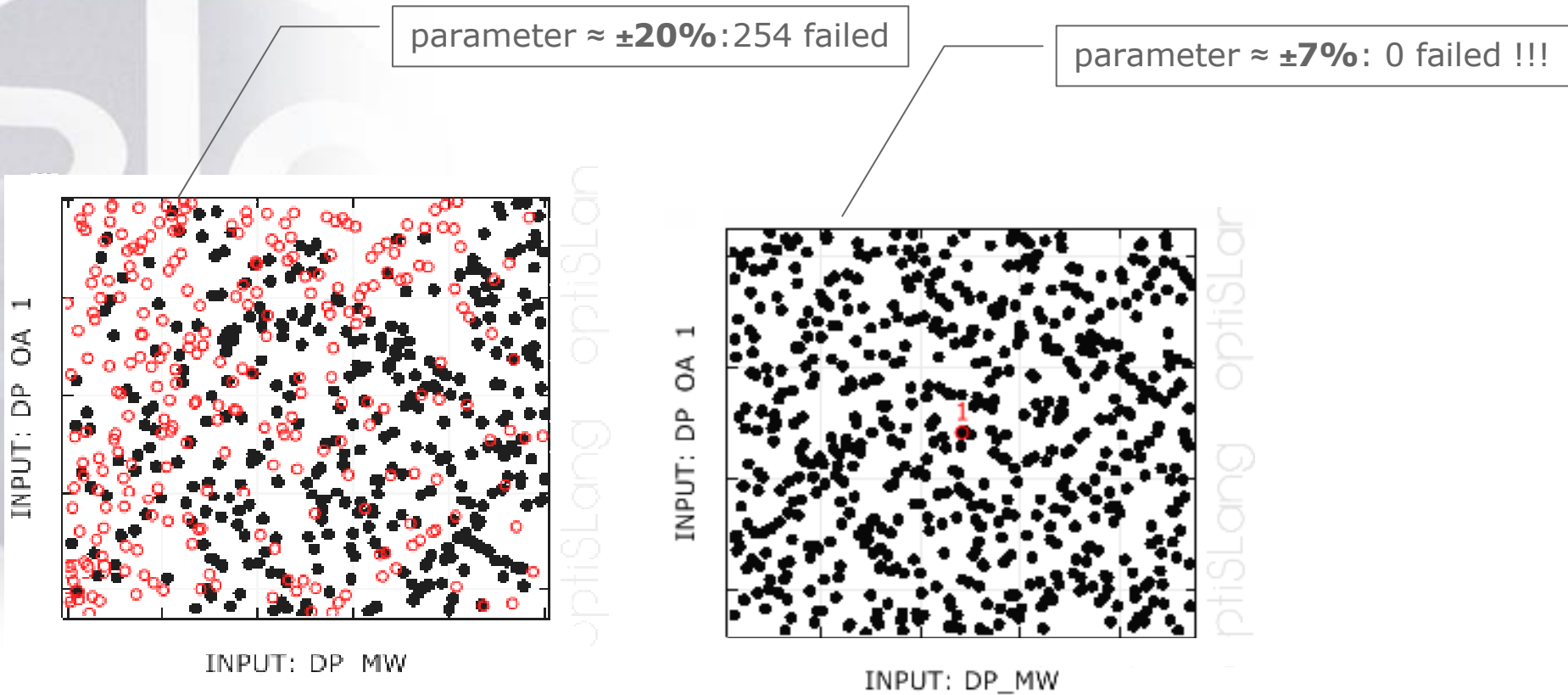


max. plastic strain vs.  
strut width & meander width





## Strategy – optiSLang – DOE



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## Strategy – optiSLang – ARSM

- initial parameter are selected based on COI (DOE)
- 1<sup>st</sup> loop:
  - design parameters:
    - meander width
    - max. arc strut width (4x)
    - arc radii (4x)
    - radius offset (4)
  - $\pm 20\%$  parameter range
  - GA/NLPQLP
  - 20 iterations
  - up 10h wall clock time per ARSM loop (300-600 simulations)

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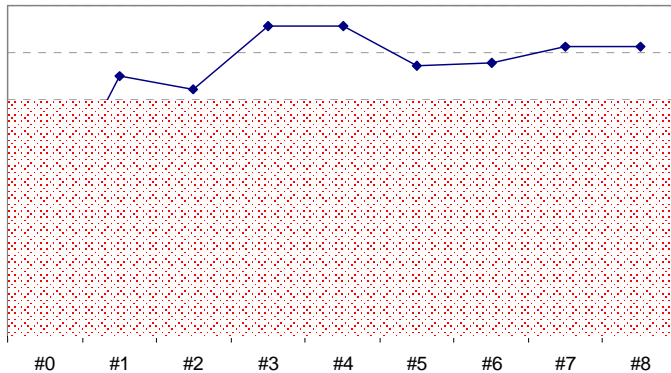
## Strategy – optiSLang – ARSM

- following loops (up to 8 loops):
  - start design = best design from previous loop
  - design parameters = combination of few initial and new parameters
  - less important variable will be replaced by new ones
  - parameter range will be reduced stepwise down to  $\pm 3\%$
  - 20-30 iterations

## Strategy – optiSLang – Results

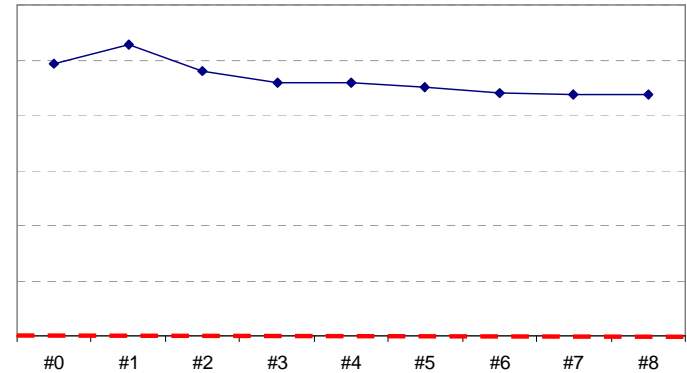
### Boundary Conditions

Minimum Strut Width

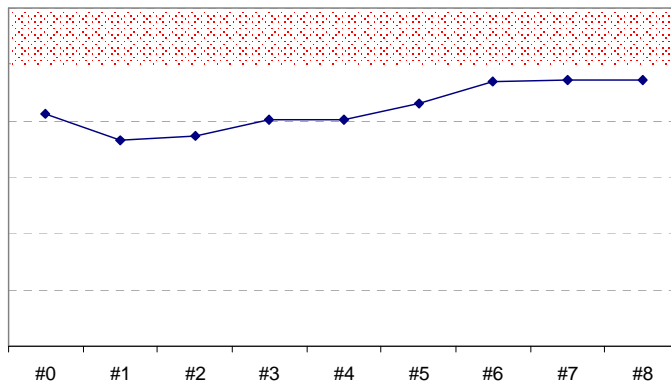


### Objective Terms

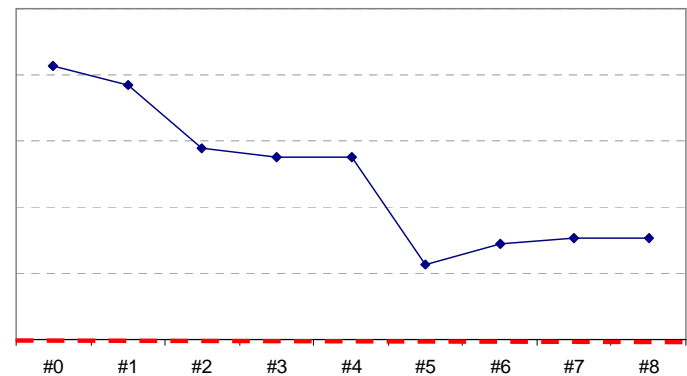
Radial Compliance



Plastic Strain



Inhomogeneous strain distribution



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## optiSLang

- 1 year intense usage & experience of optiSLang at Cortronik Stent Development
  - proofed to be very successful and highly effective
  - confidence with new tools & algorithms
  - new challenges in terms of model generation (stability) & formulation of objective function
- 
- extended usage planned – robustness analyses
    - include geometrical variance (production tolerance)
    - include scatter of material properties (elongation fracture)

Vielen Dank

