

Use of Random Fields to Characterize Brake Pad Surface Uncertainties

Dr. Ronaldo F. Nunes, Oliver Stump - Daimler AG
 Dr. Sebastian Wolff - Dynardo Wien



05. November 2015



Mercedes-Benz



Agenda

NVH Customer Requirements: Silent Brakes or Robust System ?

Lining Material Surface: Brake Noise Influence

New Workflow Proposal with SoS

Application to a Real Brake System

Summary/Future Development

NVH Customer Requirements: Silent Brakes or Robust System ?



Warranty chart



NVH Customer
Requirements

*Answer:
Our focus is to achieve
a NVH robust system
for the whole life cycle.*

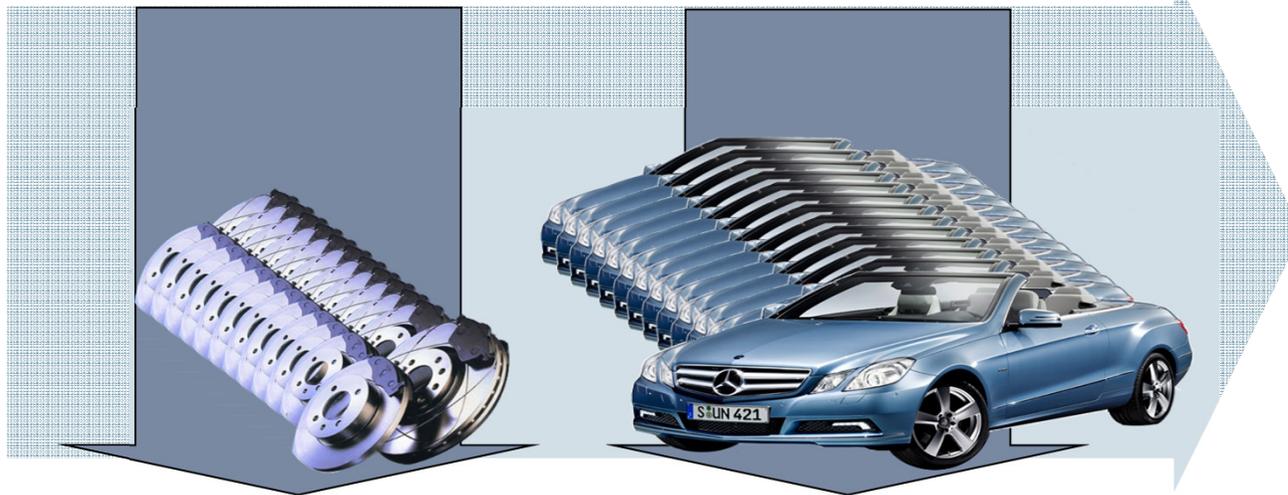
...you get ideal curves with constant slopes at low percentage values

Main Task: Silence Brake System to the Whole Life Process

Influence of the production dispersion

Influence of drivers and time

Problem



Production dispersion:

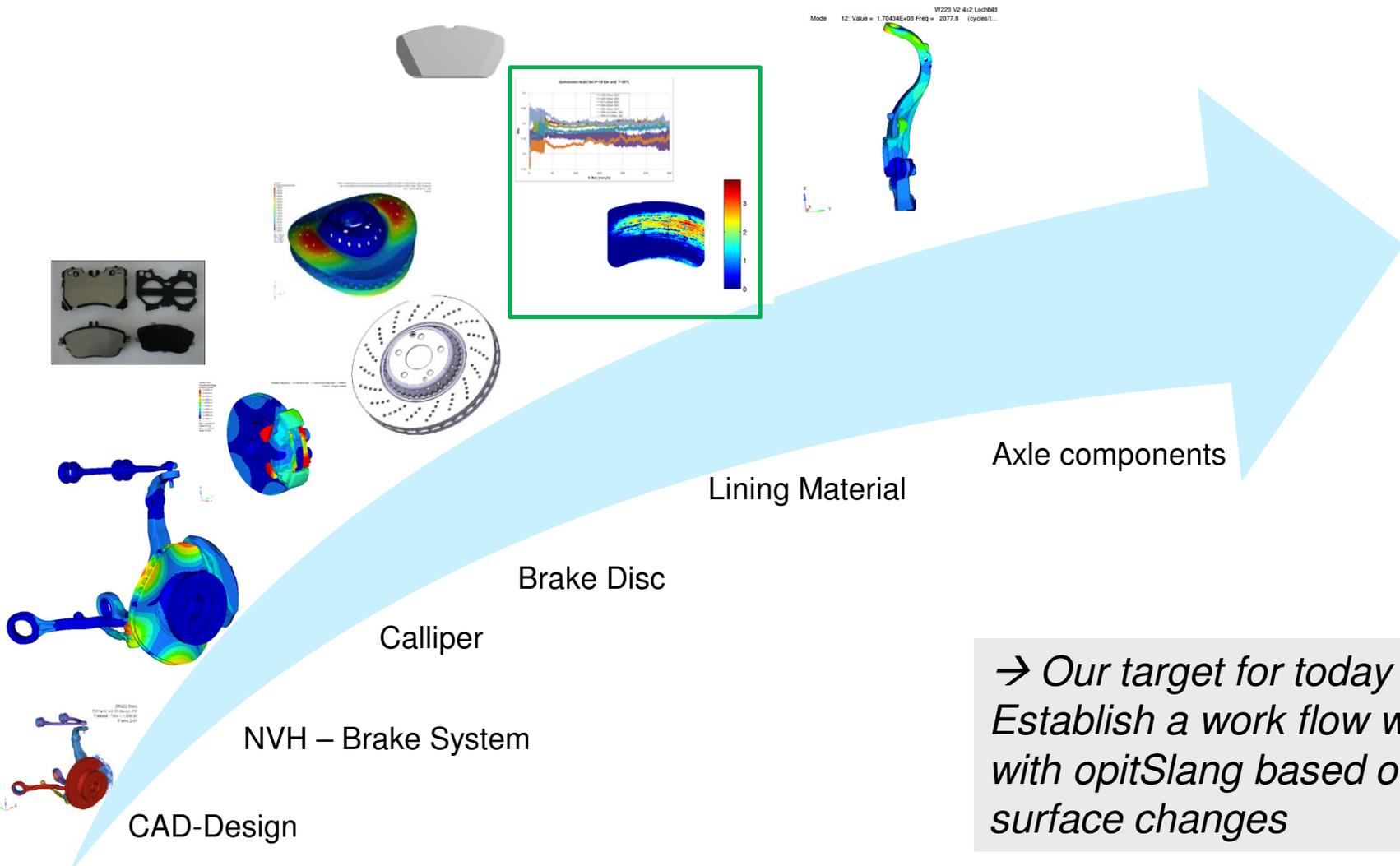
Geometry tolerances (Uncertain Parameters, friction coefficient, weight, etc.

Drivers and time:

Pressure, temperature, friction behaviour, fading, etc.

→ Focus reliable prognostic of brake squeals relative to the production, time and drive conditions to the whole life process

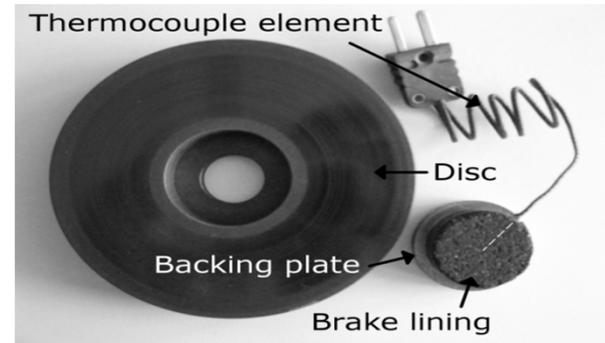
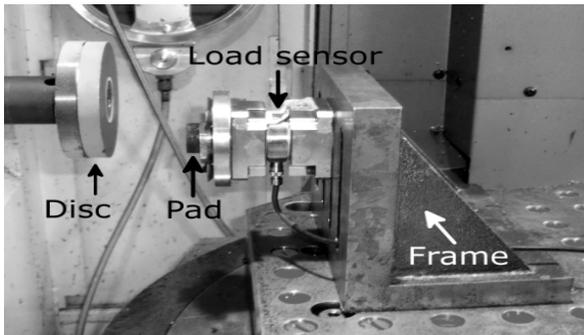
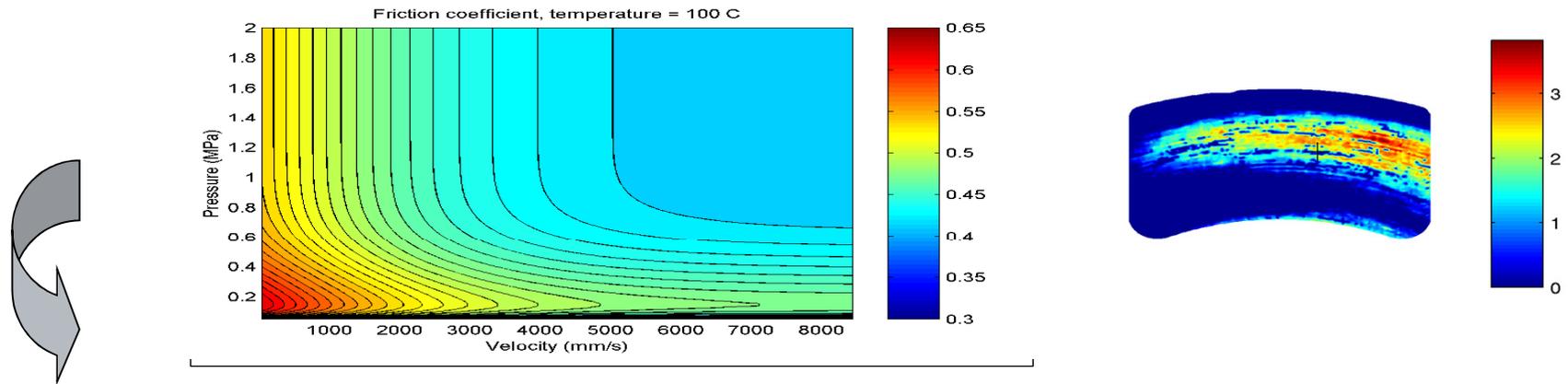
NVH – Brake Components Influence



Target: Robust Brake System to the whole life process

→ Our target for today is ...
 Establish a work flow with SoS combined with opitSlang based on lining material surface changes

Alternative 1: Integration of Friction Curve and Surface Change in the Simulation Model



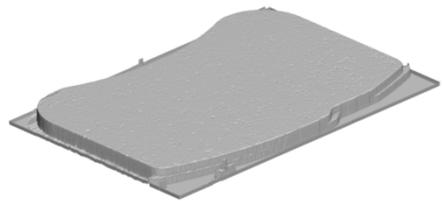
Source: 2012 Heussaff: Influence of the variability of automotive brake lining surfaces on squeal instabilities

→ Possibility to integrate the friction curve in the simulation model

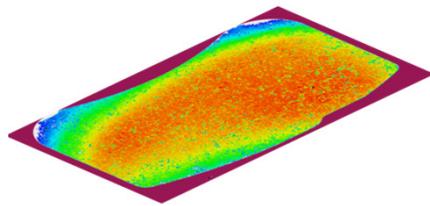
Alternative 2: Work flow SoS Combined with OptiSlang



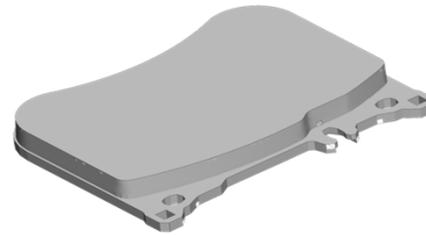
New Work Flow !



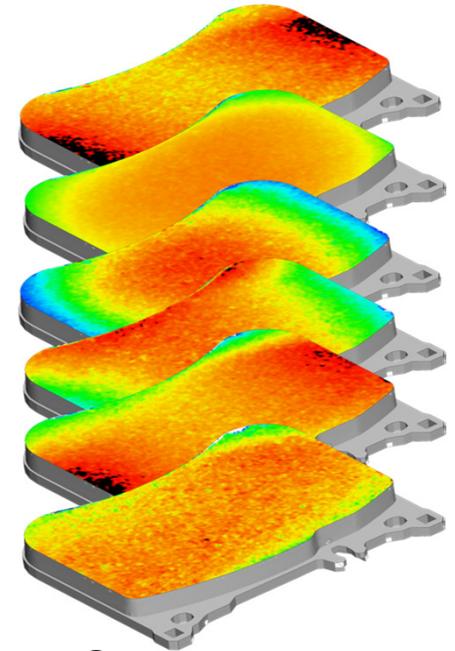
Laser scans of
brake pad
whole surfaces



Import of scan
data into SoS



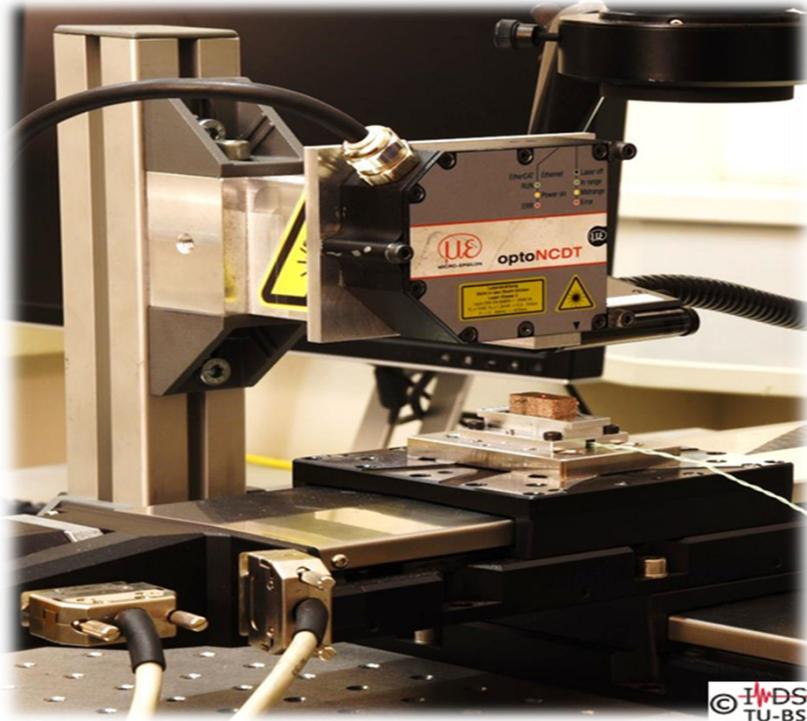
Map data onto
FEM model
surface and
create random
field model in
SoS



Generate new
random
geometries with
optiSLang + SoS

IDS Topography Measurement Station

Topography Measurement



Measurement Station

- ❑ Laser Triangulation Sensor with 0.5 μm repeatability and max. 6 μm linearity deviation
- ❑ Contactless measurement of distance between specimen and sensor
- ❑ No destruction of the surface
- ❑ Moving the specimen on two linear stages with a positioning accuracy of 2 μm
- ❑ Measuring range of the height up to 10 mm

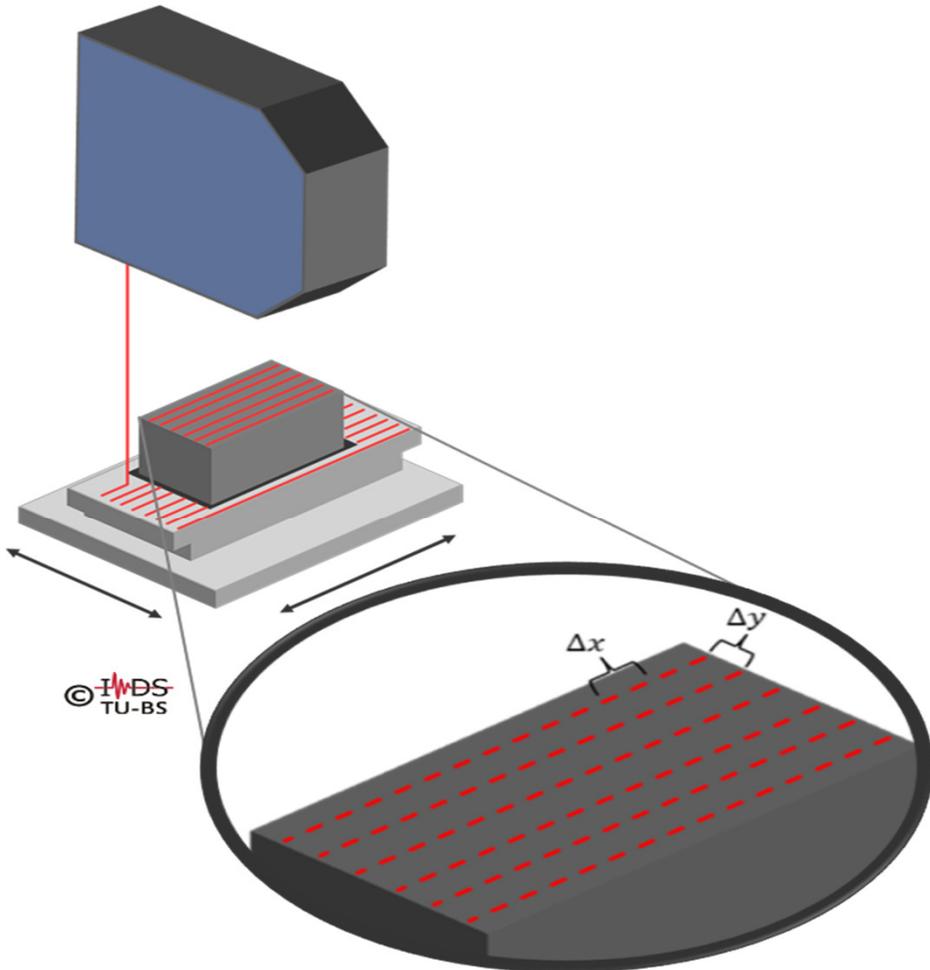
Detailed Information, see [1]

[1] Ostermeyer, G.-P.; Perzborn, N. and Ren, H., *Contactless Wear Measurement of Brake Pads*. In: EuroBrake 2013 Conference Proceedings

IDS Topography Measurement Station



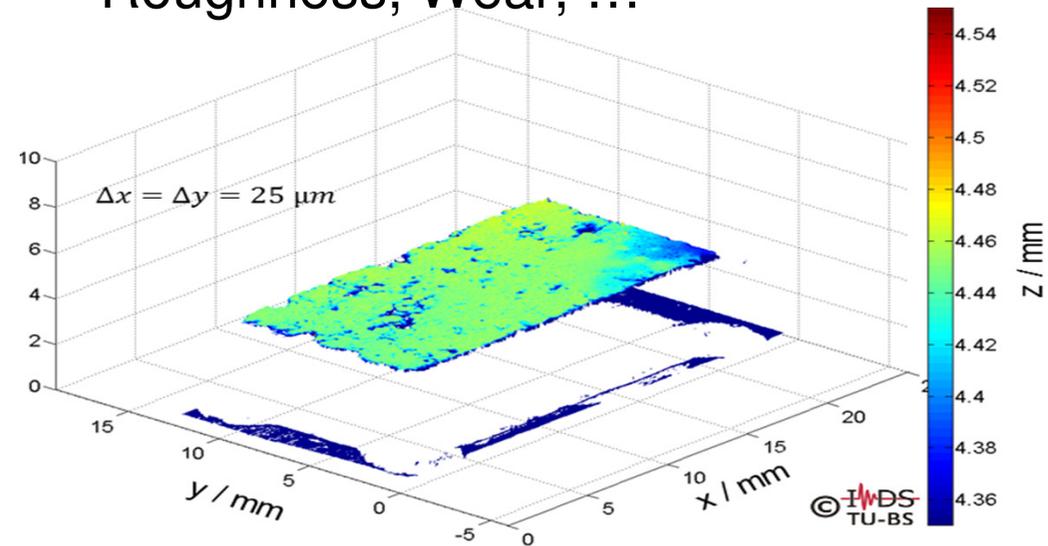
Topography Measurement



© IwDS
TU-BS

Measurement Procedure

- ❑ Measuring the topography by combining line profiles
- ❑ Lateral resolution up to $10\ \mu\text{m}$
- ❑ Usable to determine Contact Surface, Geometric Properties, Roughness, Wear, ...



IDS Topography Real Measurement

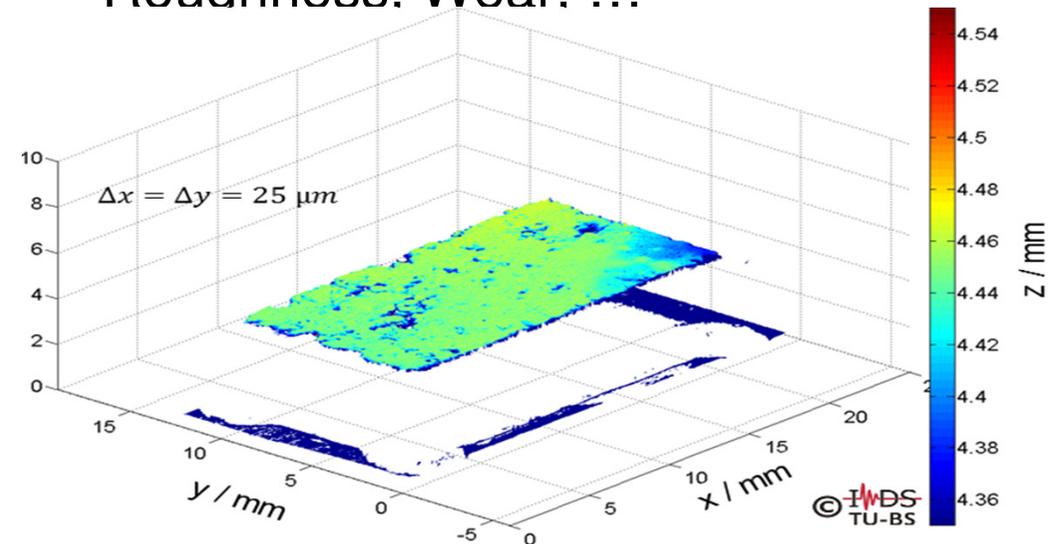


Topography Measurement

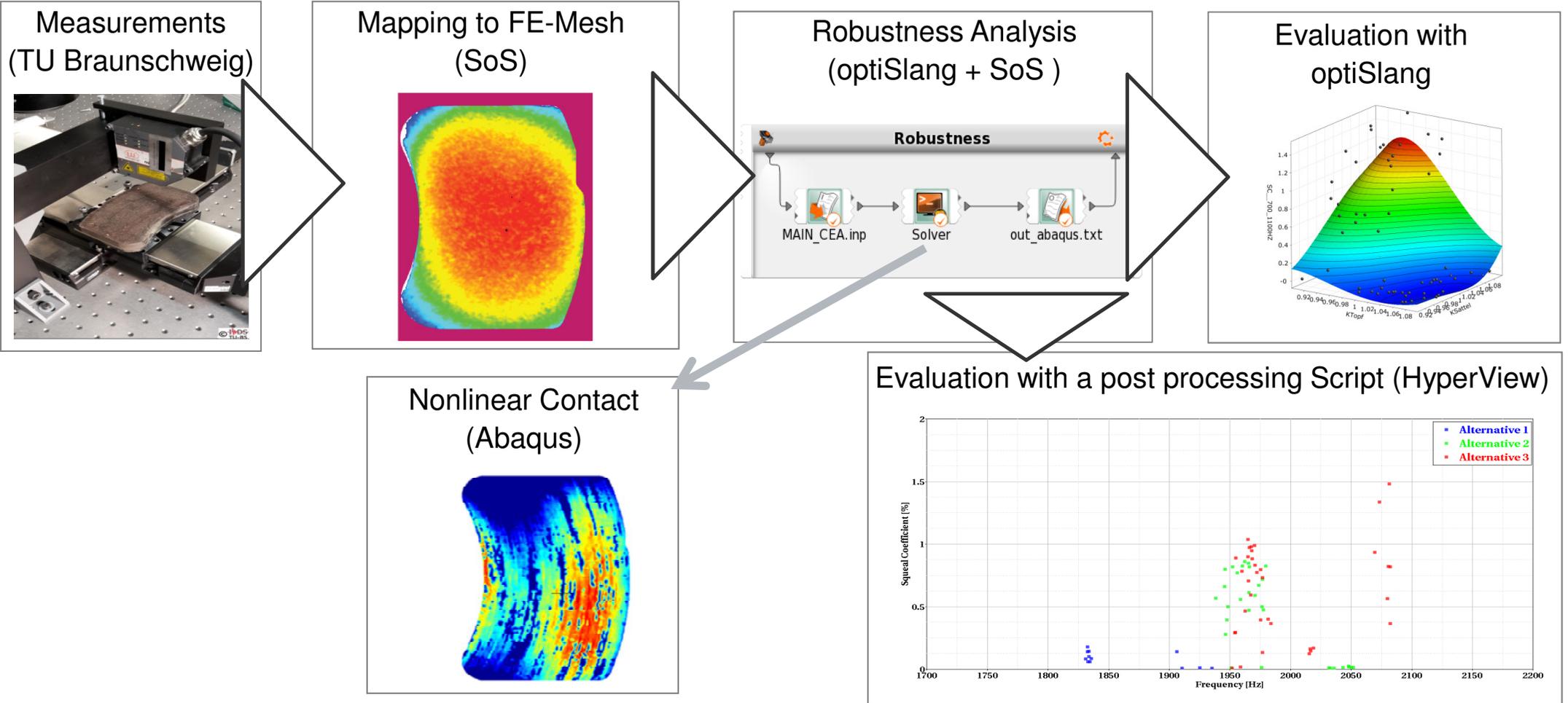


Measurement Procedure

- ❑ Measuring the topography by combining line profiles
- ❑ Lateral resolution up to $10\ \mu\text{m}$
- ❑ Usable to determine Contact Surface, Geometric Properties, Roughness, Wear, ...



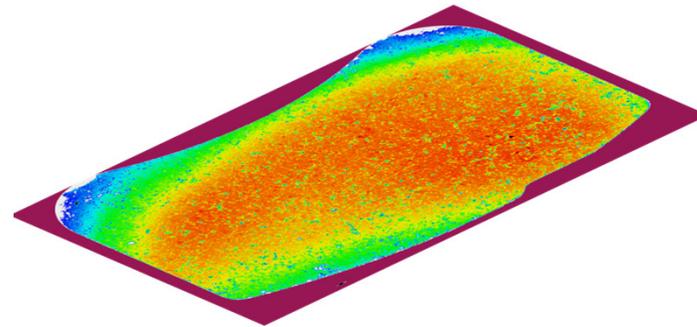
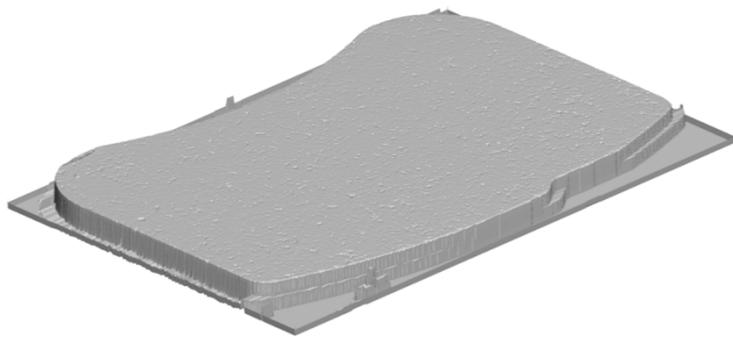
Workflow



Step 1

Import laser scan data into SoS

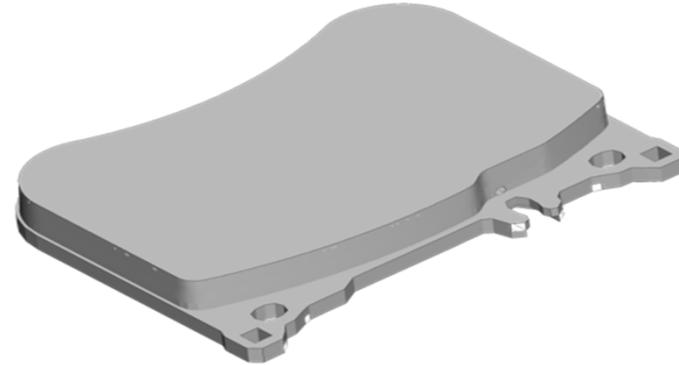
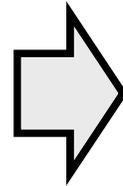
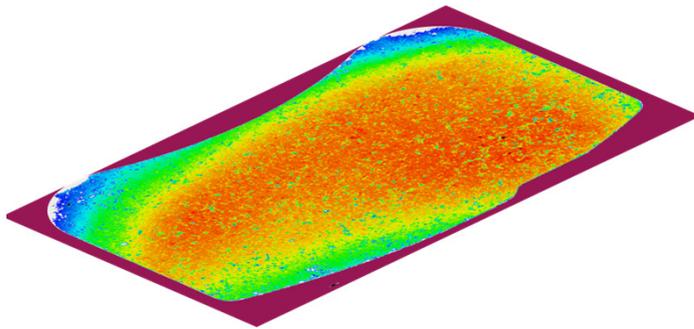
- ❑ Laser scan data: 1.2 million measurement points on a 2D grid
- ❑ 40 real measurements
- ❑ Import of grids with variations in Z position in terms of a scalar field "Deviation"
- ❑ Visualization of the deviation as color plot in SoS
- ❑ Further: Rotation, Translation and scaling (units!) in SoS



Step 2

Mapping of measured data onto FEM mesh

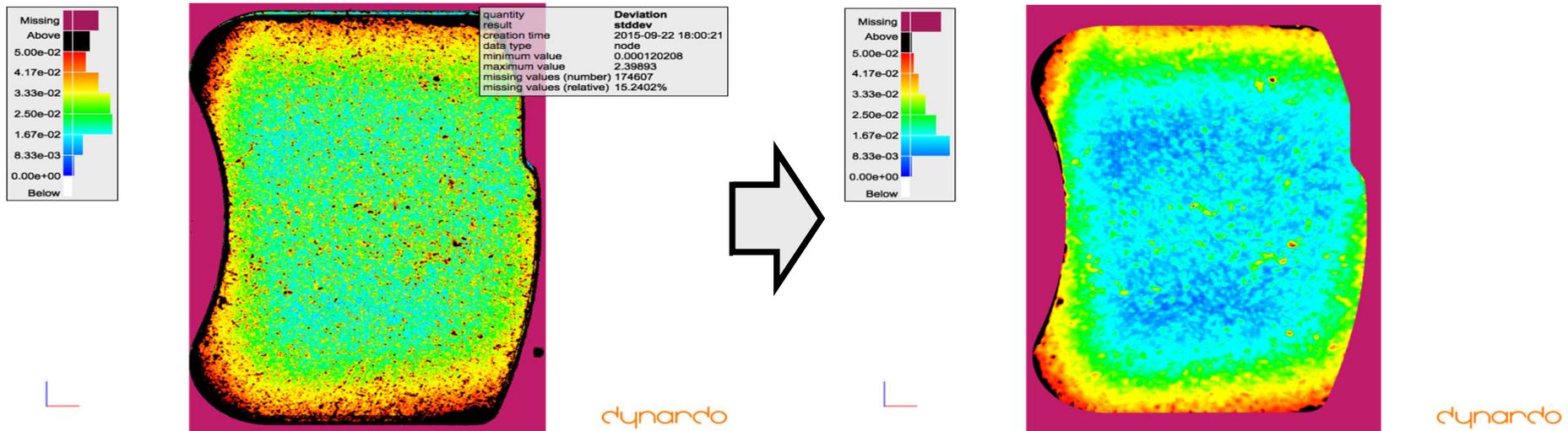
- ❑ FEM mesh of break pad: 118558 nodes, 405971 elements,
- ❑ Abaqus INP file format, target surface defined by node set
- ❑ Projection along predefined direction (y axis)



Step 3

Mapping of measured data onto FEM mesh

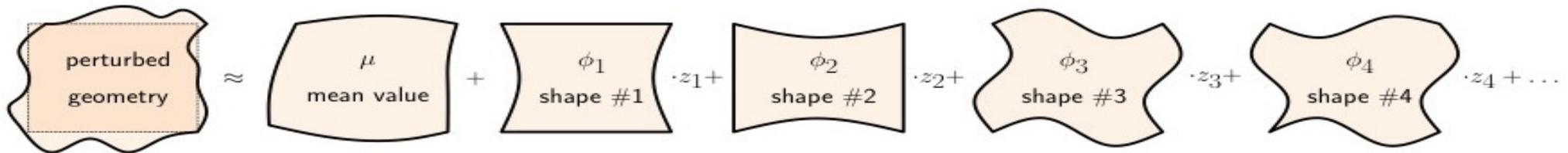
- ❑ Loss of information due to data mapping!
- ❑ Reason: Rough spatial resolution of FEM nodes vs. small distances of laser scan points
- ❑ Nearly no differences in statistical mean
- ❑ But: Averaging effects in standard deviation (i.e. spatially very local effects)



Random field model

Approximate a random design with

- mean value + linear combination of deterministic “scatter shapes” multiplied with random coefficients



Accurately resembles

- Statistical moments (mean, standard deviation...)
- Spatial correlations (anisotropic, inhomogenous...)

Accuracy:

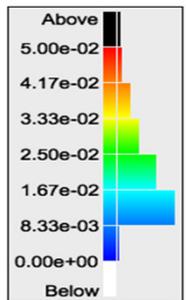
- ~30 random numbers to approximate statistics of measurements with 99% accuracy
- Only 10 random numbers for 90% accuracy

Random field model: Accuracy

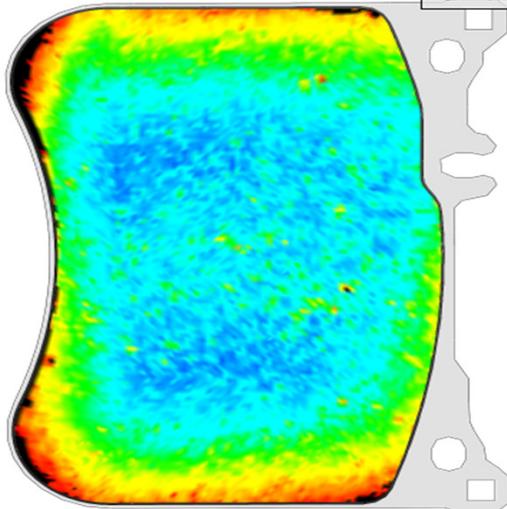


Left: Standard deviation in FEM model

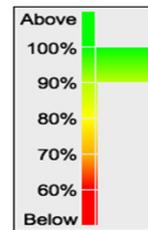
Right: Accuracy in %



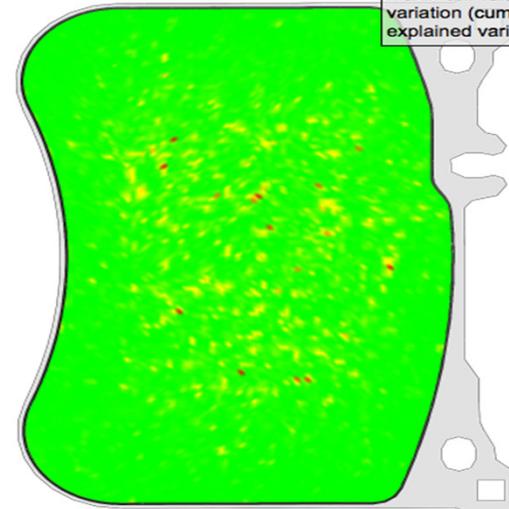
| | |
|---------------|---------------------|
| quantity | Deviation |
| result | stddev |
| creation time | 2015-09-22 17:11:16 |
| data type | node |
| minimum value | 0.00496535 |
| maximum value | 0.215483 |



dynardo



| | |
|------------------------|---------------------|
| quantity | Deviation |
| result | variation |
| creation time | 2015-09-22 17:11:16 |
| data type | node |
| minimum value | 52.9672% |
| maximum value | 99.9984% |
| variation (cumulative) | 99.2738% |
| explained variation | 99.2738% |



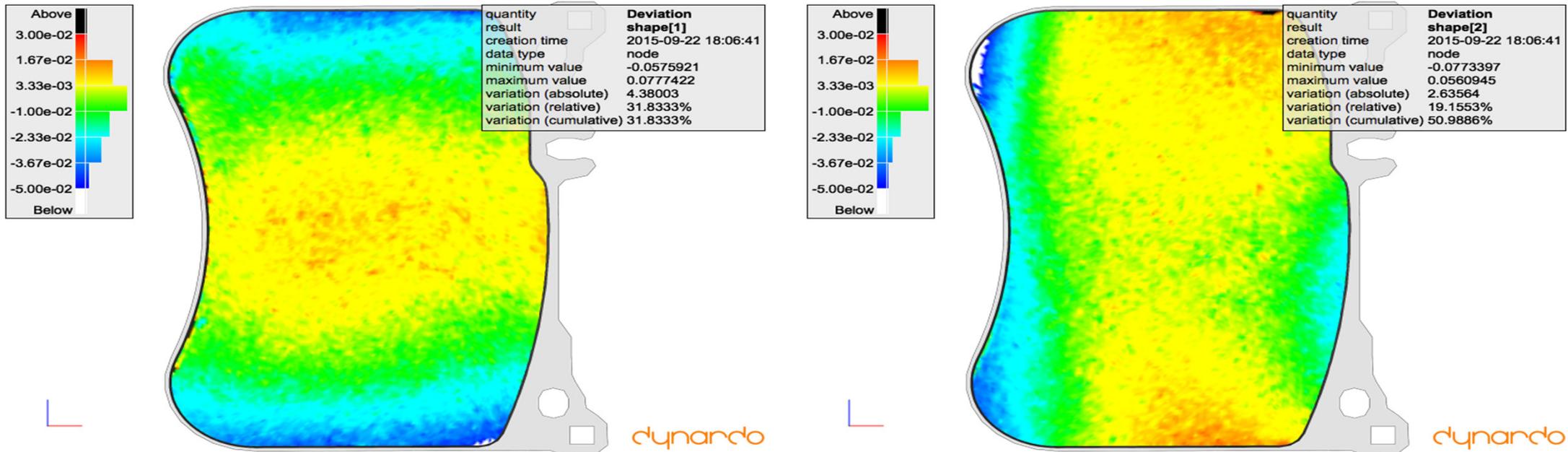
dynardo

Random field model: Scatter Shapes



Left: Shape #1 (31.8% Variation)

Right: Shape #2 (19.1% Variation)

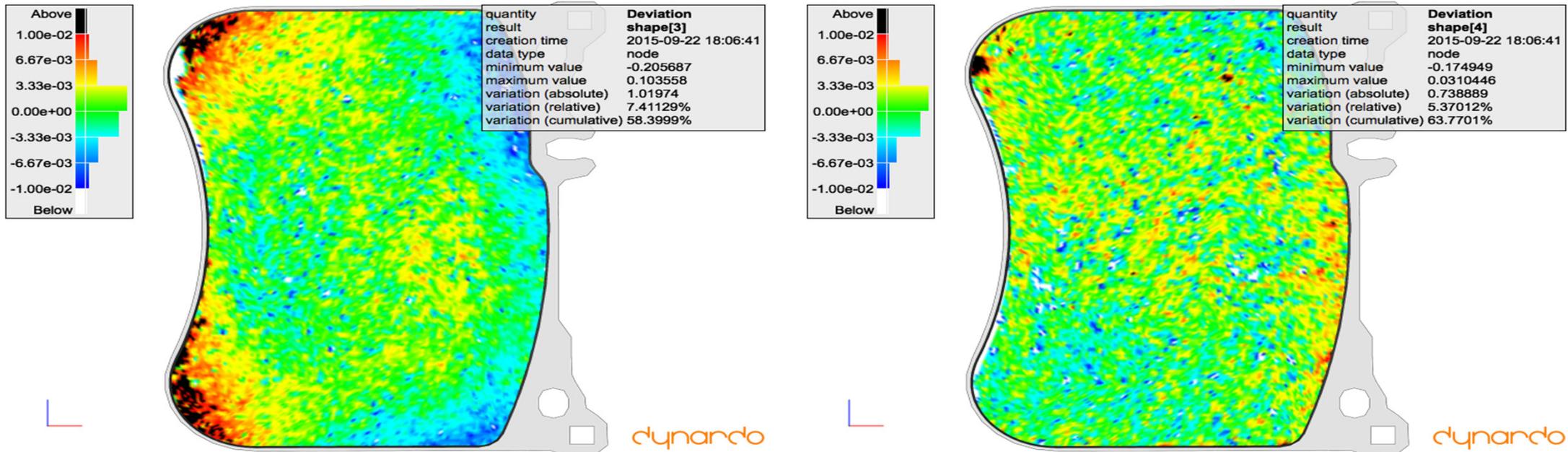


Random field model: Scatter Shapes



Left: Shape #3 (7.4% Variation)

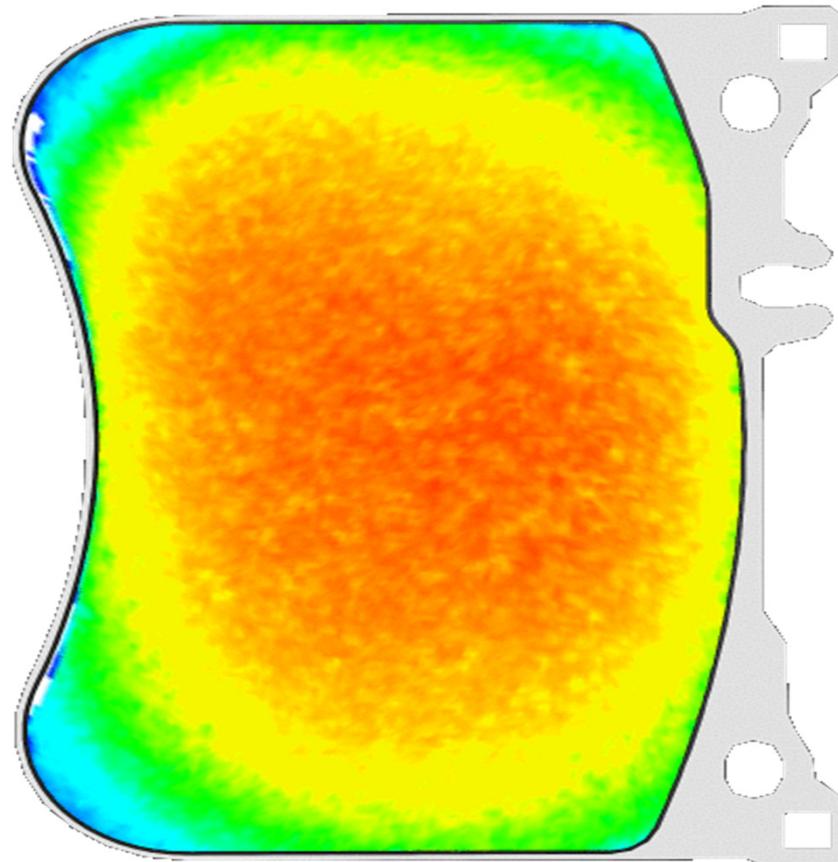
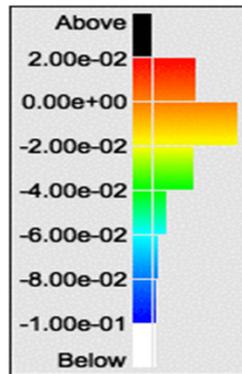
Right: Shape #4 (5.4% Variation) – already with many local effects



Random field model



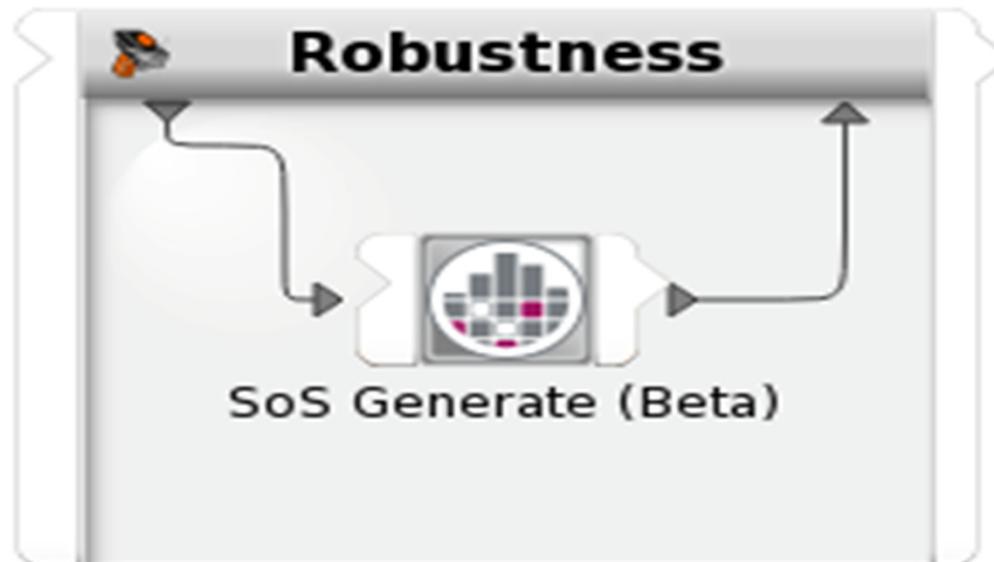
Video shows some possible realizations of the random field



dynardo

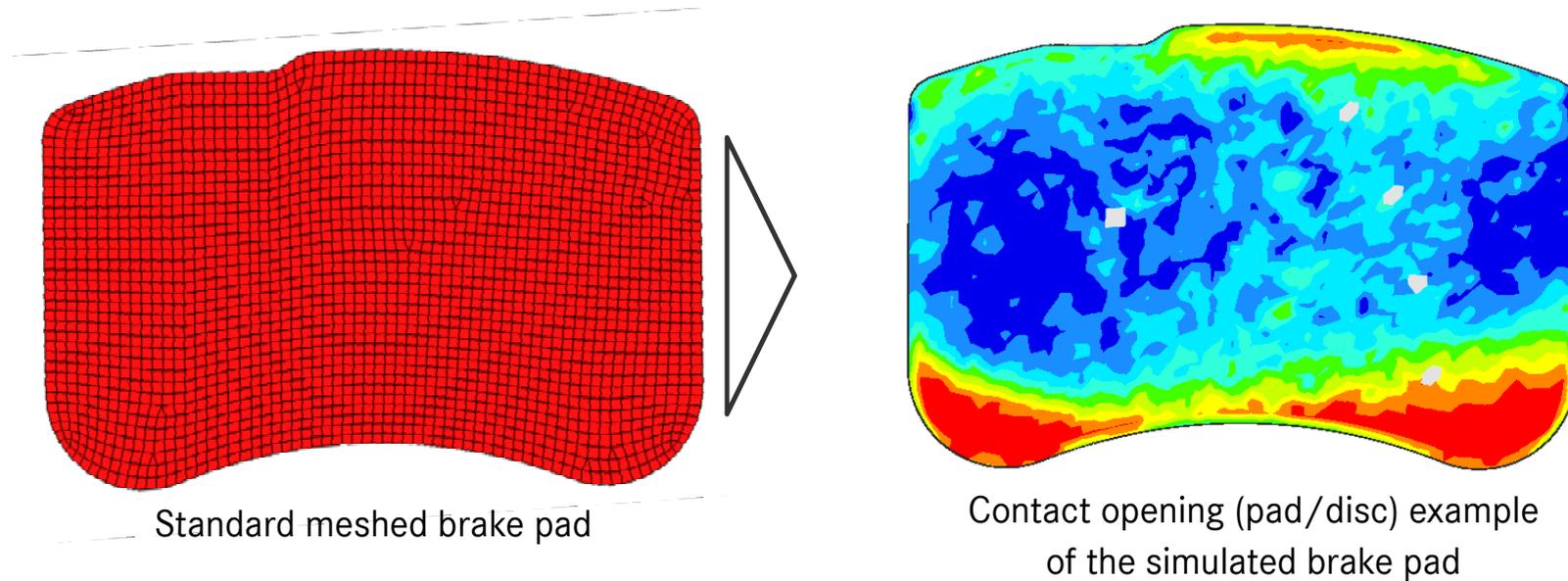
Simulation of new random designs

- ❑ Use optiSLang to generate 100 new random designs
- ❑ SoS will be started in Batch mode by optiSLang
- ❑ Depending on desired accuracy: Use 5, 10 or 30 random parameters to generate geometric imperfections



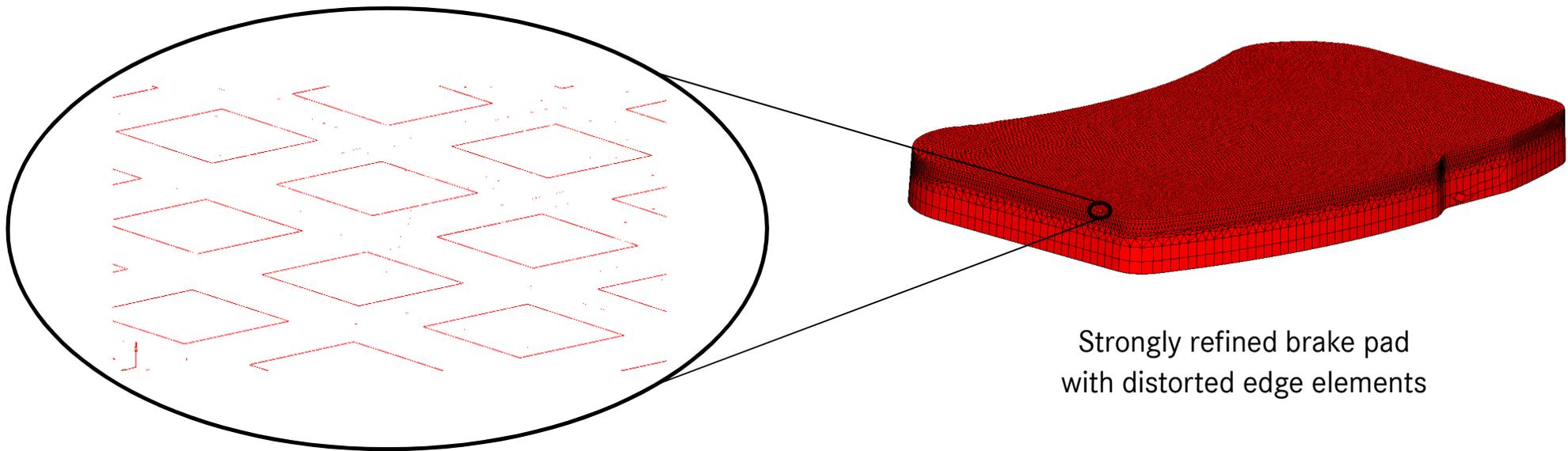
Surface changes influence nonlinear contact finding

- ❑ Well-known behavior:
 - Instability is strongly influenced by the pad / disc contact
- ❑ Presented workflow enables **simulation of the measured and mapped brake pad** and **the generation of new, correlated surfaces**
- ❑ Mapping is dependent on the refinement of the mesh



Challenges with Random Generated Surfaces

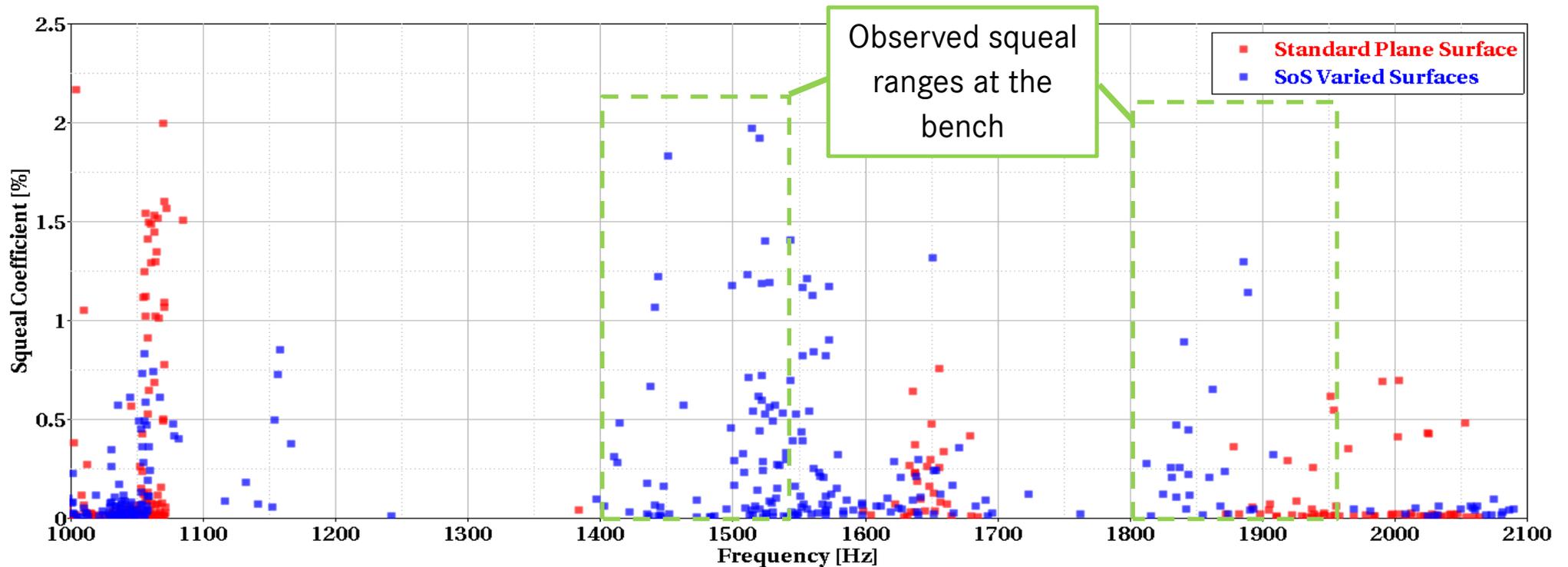
- ❑ Mesh quality must be observed
- ❑ Especially with edge extrapolation, mesh elements can easily be distorted
- ❑ Workflow implementation for the refined meshes is still work-in-progress



Strongly refined brake pad
with distorted edge elements

Example Robustness Analysis Result

- ❑ Standard Robustness analysis consists of 100 random designs
- ❑ New Analysis adds random surfaces to the same random designs



- Higher instabilities occur with a slight change in frequency
- The frequency at ~1 kHz decreases (→ frequency not observed at bench tests)
- Mode shapes and contact conditions have to be evaluated carefully



Summary/Future Development

- ❑ Automatic positioning of measurements along the reference grid
- ❑ Improvements to random field model being used:
 - Non-Gaussian random fields to capture measured statistics more accurately (Non-Gaussian random field amplitudes and Non-Gaussian field realizations)
 - Enforcement of lower and upper value bounds of field realizations (mostly due to numerical requirements)