CUNCIC presented at the 16th Weimar Optimization and Stochastic Days 2019 | Source: www.dynardo.de/en/library

Deep Gaussian Covariance Network

Machine Learning based on Probabilistic Intelligence

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Overview machine learning algorithms



What should a machine learning algorithm be capable of?

• Maximum flexibility



Requirements

- Maximum flexibility
- Good generalization



- Maximum flexibility
- Good generalization
- Scalability

batch size = 4



- Maximum flexibility
- Good generalization
- Scalability
- Automatic design space reduction

PAM for L = 0.99(K-fold)



PAM = Predictive accuracy of meta model

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- Robust against noise and outliers



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- Non-stationarity



- Maximum flexibility
- Good generalization
- Scalability
- Automatic design space reduction
- Robust against noise and outliers
- Non-stationarity
- Easy to use

No user settings / hyperparameters!

Deep Gaussian covariance network

Deep Gaussian covariance network - \mathcal{DGCN}



Example non-stationary length-scales

True function locally adapted



Example non-stationary length-scales

Stationary \mathcal{GP} model



Example non-stationary length-scales

Non-stationary \mathcal{DGCN} model







Stationary \mathcal{GP} with constant noise:



Non-stationary \mathcal{DGCN} with point dependent noise:



Automatic outlier avoidance with dynamic noise level (\mathcal{DGCN})



Automatic outlier avoidance with constant noise level (\mathcal{GP})



Scalability

- + \mathcal{DGCN} can use batch / online learning for high scalability.
- Training on CPU / GPU or even distributed on clusters.



Creep strain estimation (1/4) - problem description

- Creep strain of a material depends on the temperature and pressure history over time \rightarrow expensive to simulate.
- 300 simulations were used to train a *DGCN* model. This model should be utilized for probabilistic assessments with about 14,000 evaluations.
- The results of 31 finite element nodes in the rotor center over 34 time steps (1,054 outputs) should be analyzed \rightarrow correlation over space and time.



Creep strain estimation (2/4) - one example



Creep strain estimation (3/4) - visual validation



- DGCN=Deep
 Gaussian Covariance
 Network
- XGB=XGBoost
- DTR=Decision trees
- RF=Random forest
- NN=Neural network

Algorithm	MMAPE with PCA	MMAPE without PCA
\mathcal{DGCN}	1.71	
XGB	36	31
RF	289	253
DTR	396	1265
NN	218065	121321

Table 1: Comparison of \mathcal{DGCN} , neural networks (NN), random forests (RF), XGboost (XGB), decision trees (DTR) with PCA and without PCA for 21 test cases of the creep strain approximation. The mean MAPE (MMAPE) metric in [%] over all 21 multi-output sequences are estimated.

ECG anomaly detection (1/3)



ECG anomaly detection (2/3)



ECG anomaly detection (3/3)



Test data with anomaly

Bayesian optimization

The ability to adapt locally to the design space makes \mathcal{DGCN} particularly suitable for adaptive sampling methods like:

- Expected improvement (EI) for single or multi-objective optimization (not contrary).
- Expected volume improvement (EVI) for multi-objective Pareto optimization.
- Variance based global model improvement (Var).

Expected improvement



EI - Rastrigin example (1/3)



EI - Rastrigin example (2/3)

EI - Rastrigin example (3/3)

Surface based on model



EI - avoidance of unfeasible areas

Expected volume improvement

$$EI_{hyp}(\boldsymbol{x}_{*}) = \int_{\boldsymbol{y}\in\overline{HV}} I_{hyp}(\boldsymbol{x}_{*})PDF_{\boldsymbol{x}}(\boldsymbol{y})d\boldsymbol{y}\prod_{i=1}^{n_{con}}\Phi\left(rac{\hat{y}_{i*}}{\hat{s}_{i*}}
ight)$$



Expected hypervolume improvement - example









Beam example (1/3)

- \cdot 7 parameters (b_1 , b_2 , h_1 , h_2 , L, E, ho)
- \cdot 5 constraints (stress, reaction force, Eigenfrequency, Δs , m)
- \cdot 2 objectives ($\Delta s, m$)
- Solved via FEM



Beam example (2/3)

Optimization via EA (N = 10,000) on MOP / \mathcal{DGCN} models trained with 100 samples, reference EA on FEM simulation (N = 900).



Beam example (3/3)

Adaptive optimization via AMOP (N = 436) / BO+DGCN(N = 55/220), reference EA on FEM simulation (N = 900)





- Electronic chip design optimization.
- 5 optimization parameters.
- 30 dependent parameters.
- Increase cooling performance.
- Decrease pressure loss.

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Reliability-based tolerance optimization of an insulin pen



- Total of 40 stochastic model parameters.
- Failure defined as higher than 1% misdosing.
- Tolerance field is to be maximized.
- Reliability-based stochastic design optimization on *DGCN*.
- 90 training samples.
- Optimization with FEM approx. 7,000 calculations.



^a70 designs with Form for validation

• (Image) Regression.



- (Image) Regression.
- (Image) Classification.



- (Image) Regression.
- (Image) Classification.
- Sequential dependent output.



- (Image) Regression.
- (Image) Classification.
- Sequential dependent output.
- Multi-output.



- (Image) Regression.
- (Image) Classification.
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- Multi-output.



- (Image) Regression.
- (Image) Classification.
- Sequential dependent output.
- Multi-output.
- Confidence interval of prediction.



- \cdot (Image) Regression.
- (Image) Classification.
- Sequential dependent output.
- Multi-output.
- Confidence interval of prediction.
- Gradients of prediction.



- \cdot (Image) Regression.
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- Big data (image based on a single workstation).



- \cdot (Image) Regression.
- (Image) Classification.
- Sequential dependent output.
- Multi-output.
- Confidence interval of prediction.
- Gradients of prediction.
- Big data (image based on a single workstation).
- No adjustments to be made by the user.



 Bayesian optimization (expected improvement).



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- Sensitivity analysis (even for correlated input parameters).



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- Adaptive sampling.



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- Bayesian optimization (expected improvement).
- Sensitivity analysis (even for correlated input parameters).
- Adaptive sampling.
- Robust design optimization.
- Reliability analysis.
- Reliability-based robust design optimization.



Integration in optiSLang & Outlook

Integration status in optiSLang: MOP

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Integration status in optiSLang: optimization

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Implemented in optiSLang:

- + \mathcal{DGCN} for scalar outputs.
- Bayesian optimization (EI / EVI / Var) for scalar outputs.

Next possible steps within optiSlang:

- Support for field and sequential dependent output.
- RDO-based Bayesian optimization.

Methodological future developments in *STOCHOS*:

· Optimal control of running processes via reinforcement learning.

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