

Optimization of a magnetically prestressed valve actuator

16. Weimarer Optimierungs- und Stochastiktage 2019

07.06.2019

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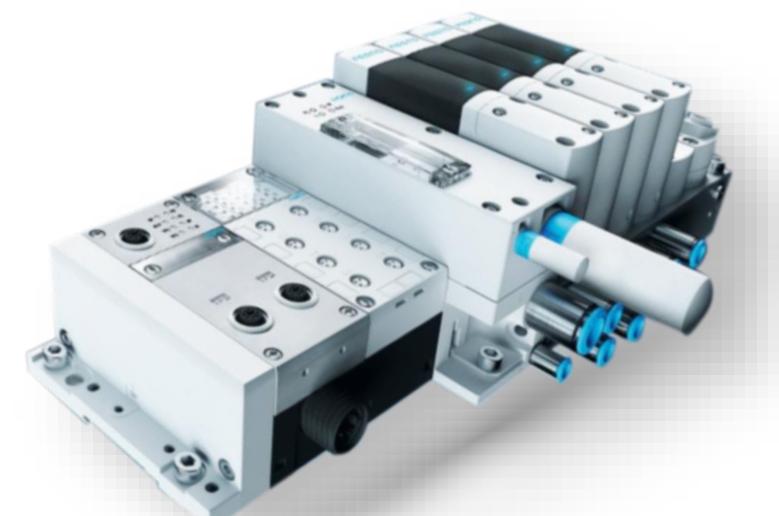
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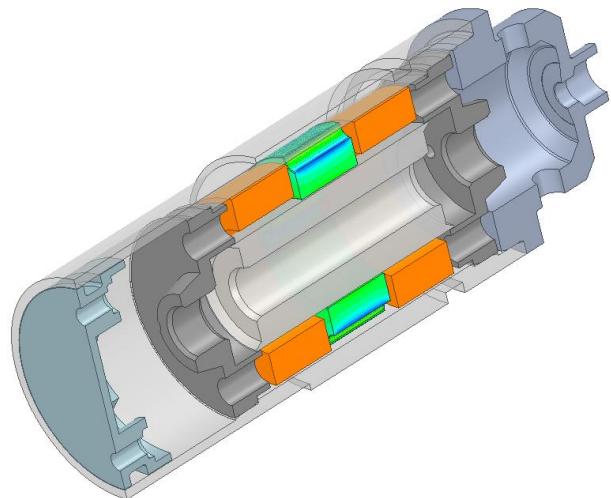
Agenda

- **Motivation and Target**
- Electromagnetic field simulation
- Workflow
- Sensitivity study
- Optimization
- Results and Perspective

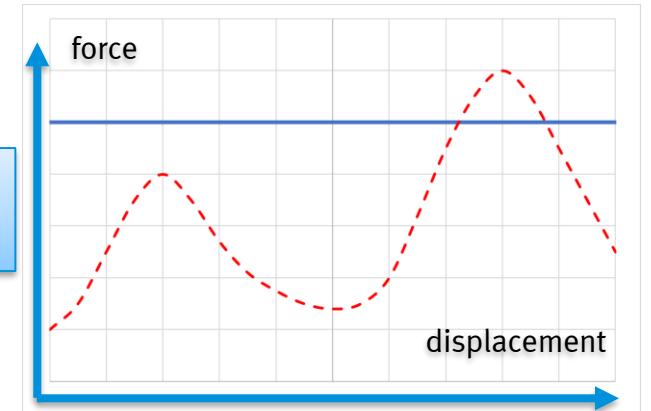


What is the point?

- **Target**
 - Development of an actuator for a proportional valve
 - Straight force-displacement curve
- **Implementation by**
 - Polarized magnet system
- **Challenge**
 - High non-linearities in material behaviour
- **Until now**
 - Experience based parameter studies
- **Procedure**
 - **Systematic, parameter based optimization using Ansys optiSLang**

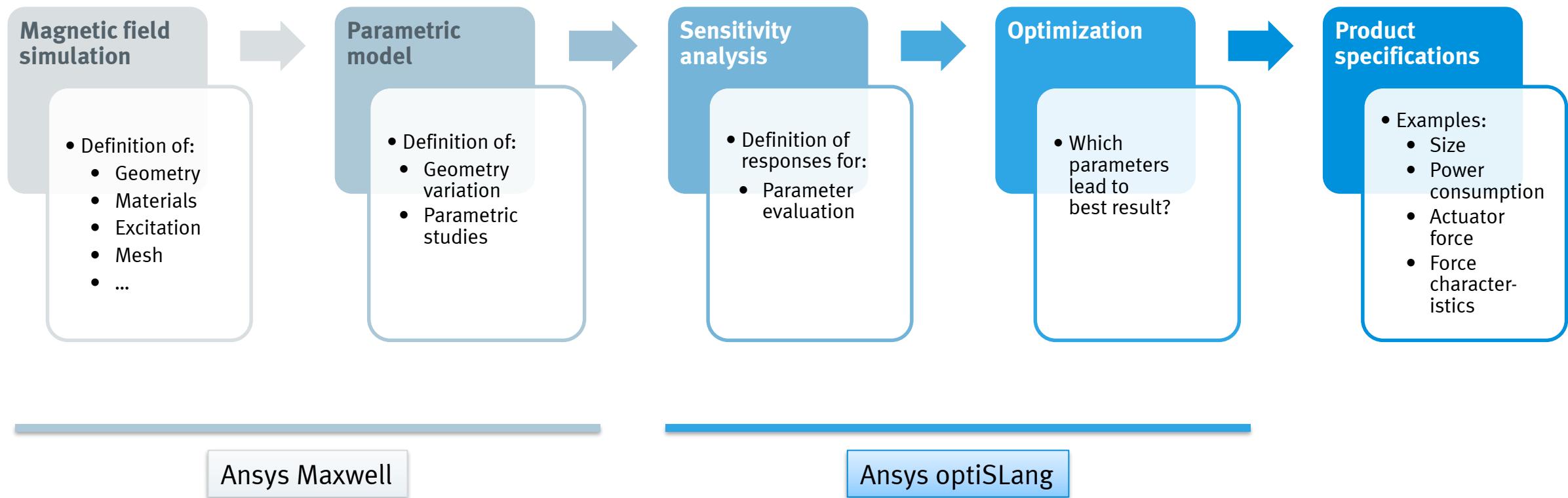


$F = F(i)$
Current dependent



$F \neq F(s)$
Not stroke dependent

Systematic, parameter based optimization



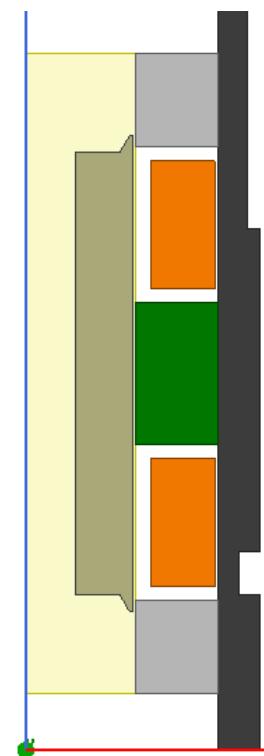
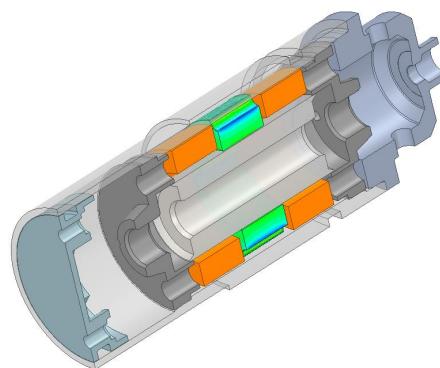
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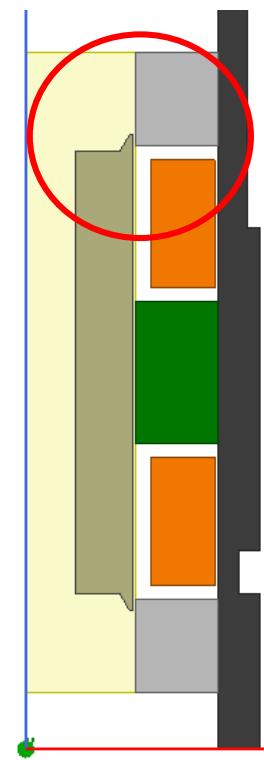
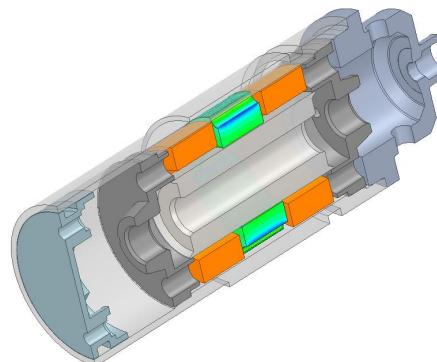
Modelling the magnetic circuit

- Rotationally symmetrical
- 2D-transient model
- **One signal for each design**
 - Force vs. Time
 - Force vs. Displacement



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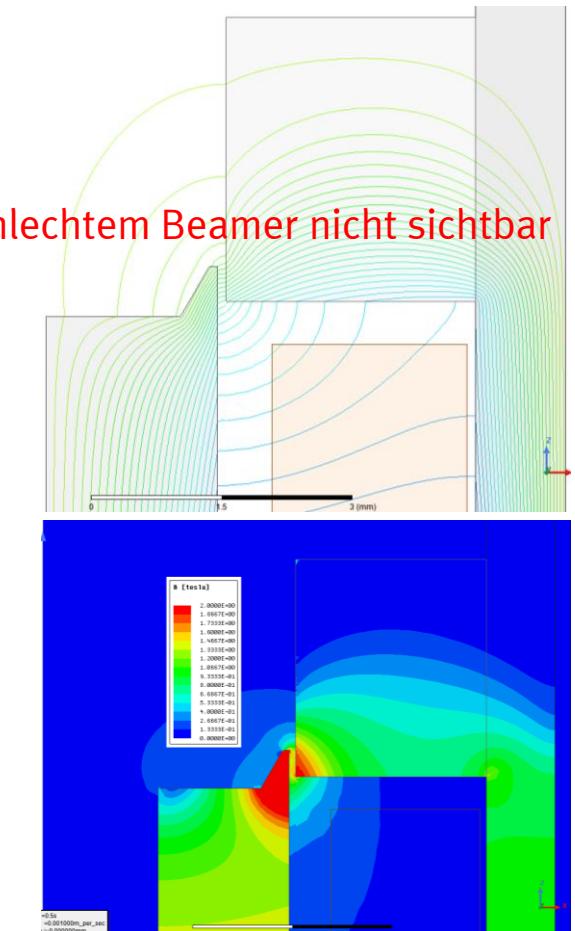


Working principle:

- Reluctance based principle comes with non-linearities
- Saturation and stray fields

BUT:

- Key to get current proportional force displacement curves
- **Optimization focuses on cone geometry**



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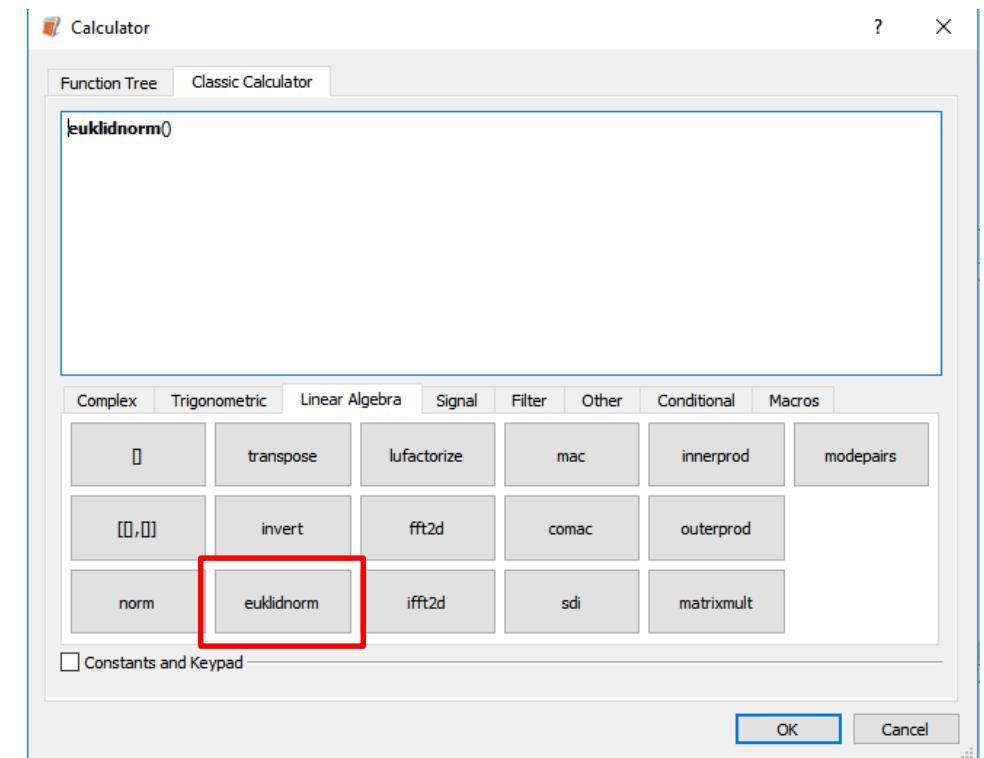
Sensitivity study and optimization need scalar values

1. Mean value of force-displacement curve:

- $\text{mean}(\text{SIGNAL})$
- „Force_mean“

2. Value describing profile of force-displacement curve:

- $\text{euclidianorm}(\text{SIGNAL} - \text{REFERENCE_SIGNAL})$
- $\text{mean}(\text{SIGNAL})$ is used as REFERENCE_SIGNAL
- matching of the signals for values $\rightarrow 0$
- „Force_profile“

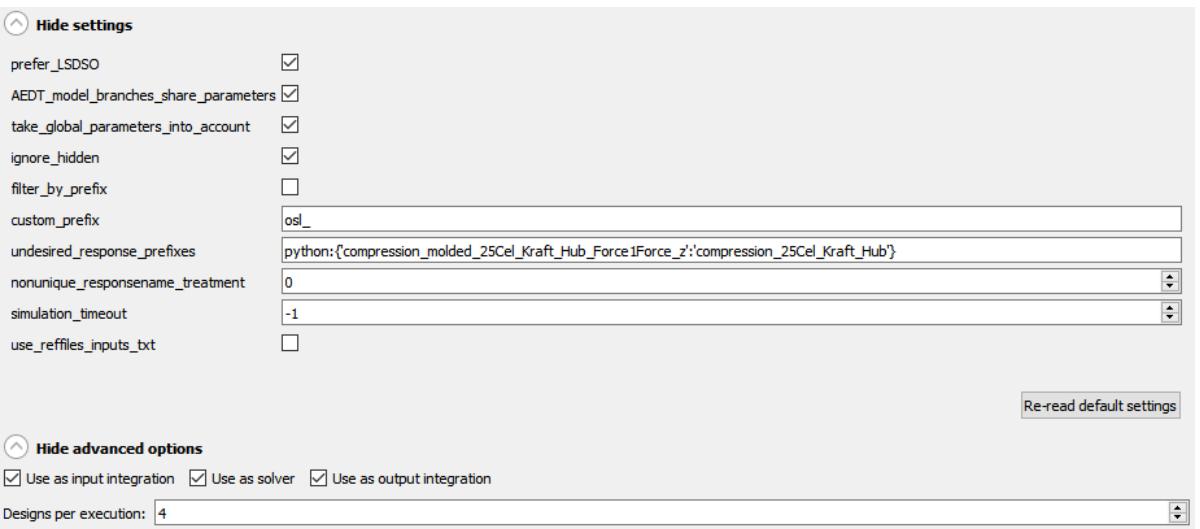
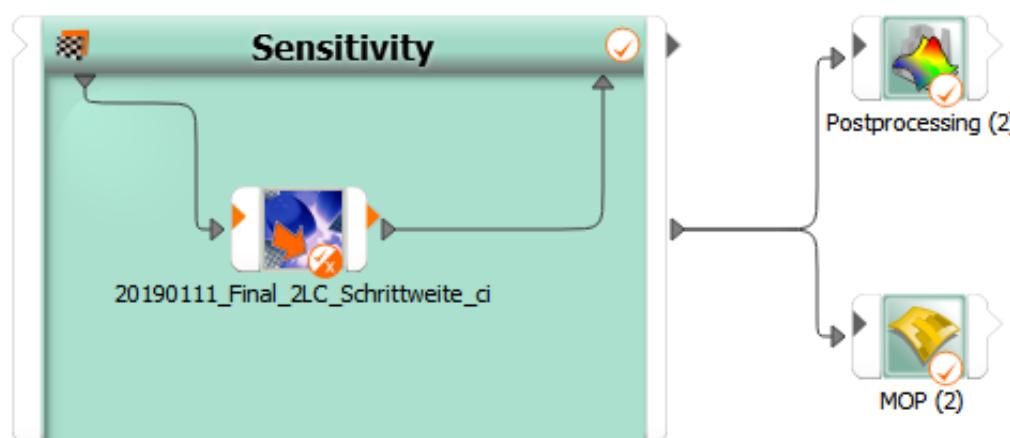


Custom Integration of Ansys Electronics Desktop

LSDSO – Workflow in V7.2.0

- No external configuration files
- No input-files for AEDT
- No extraction of results out of result files
- LSDSO settings located in AEDT-node

Comfortable way to set up workflows for optiSLang driven parameter studies in AEDT



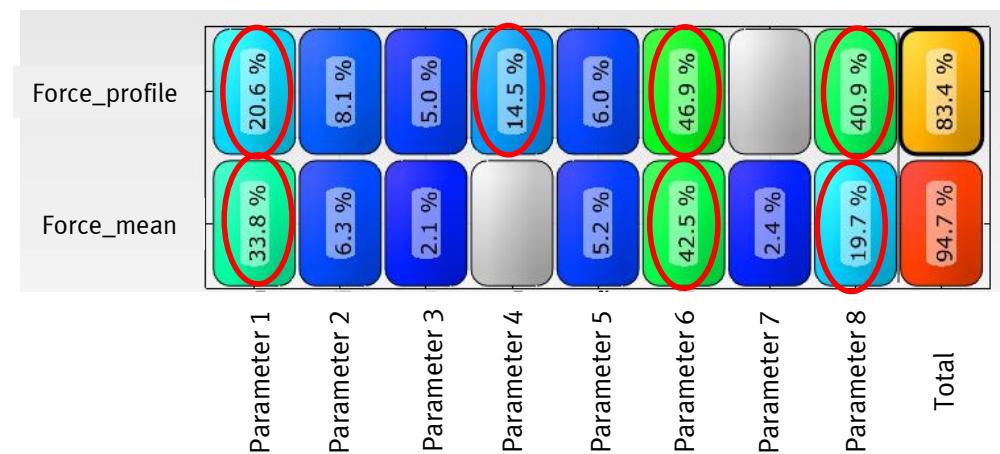
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Understanding the system

- „Coefficient of Prognosis“ matrix
 - CoP as a measure of the quality for the MOP
 - Dependence between input parameters and the responses
 - Reduction of the input parameters
 - Influence only valid within the given parameter range



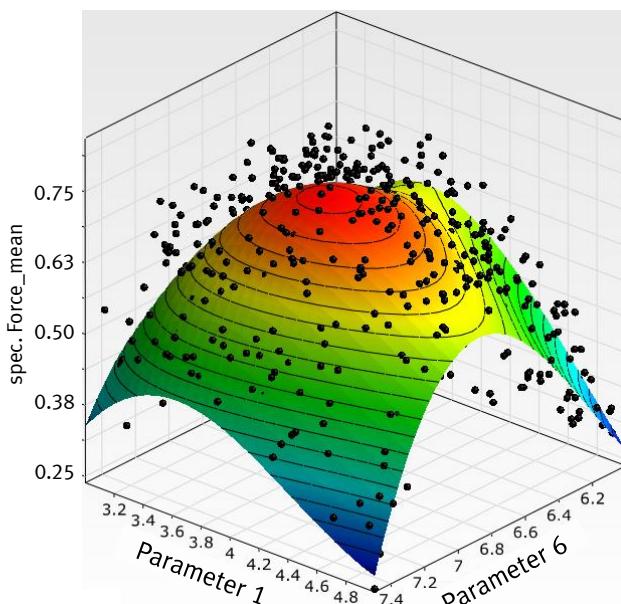
Conclusion:

- „*Force_profile*“ dominated by 4 parameters
- „*Force_mean*“ dominated by 3 parameters

The system behaviour in detail

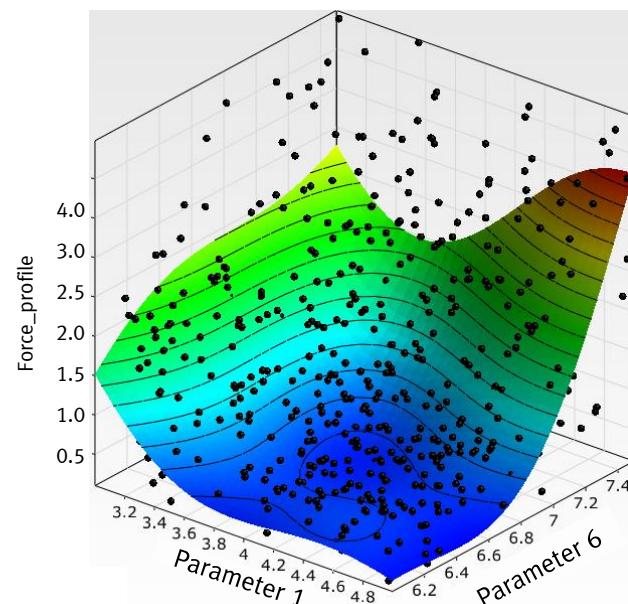
„Force_mean“

- Two main parameters
- **Distinct maximum**



„Force_profile“

- Strong influence of two main parameters
- Caused by saturation effects
- **Check validity of responses!**



- Maximum force dependent on two main geometry parameters
- Force profile dependent on cone geometry
- Separate the two cases



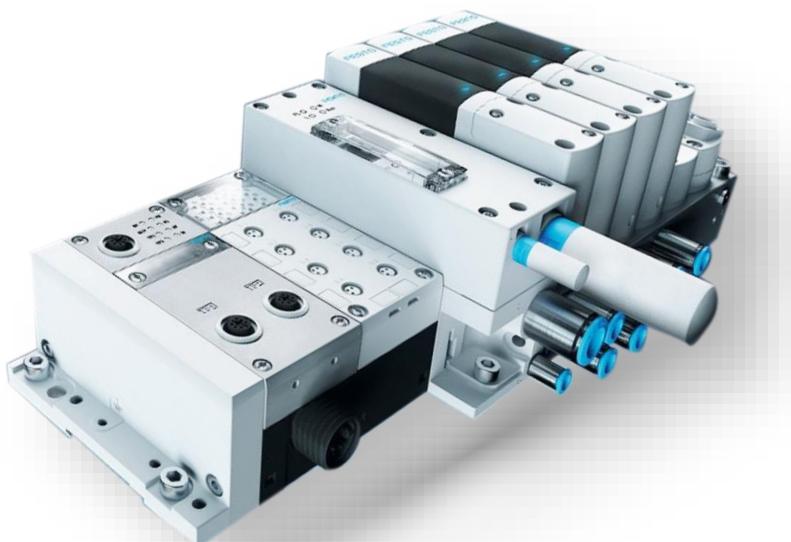
Main parameters are defined



Optimization of cone geometry

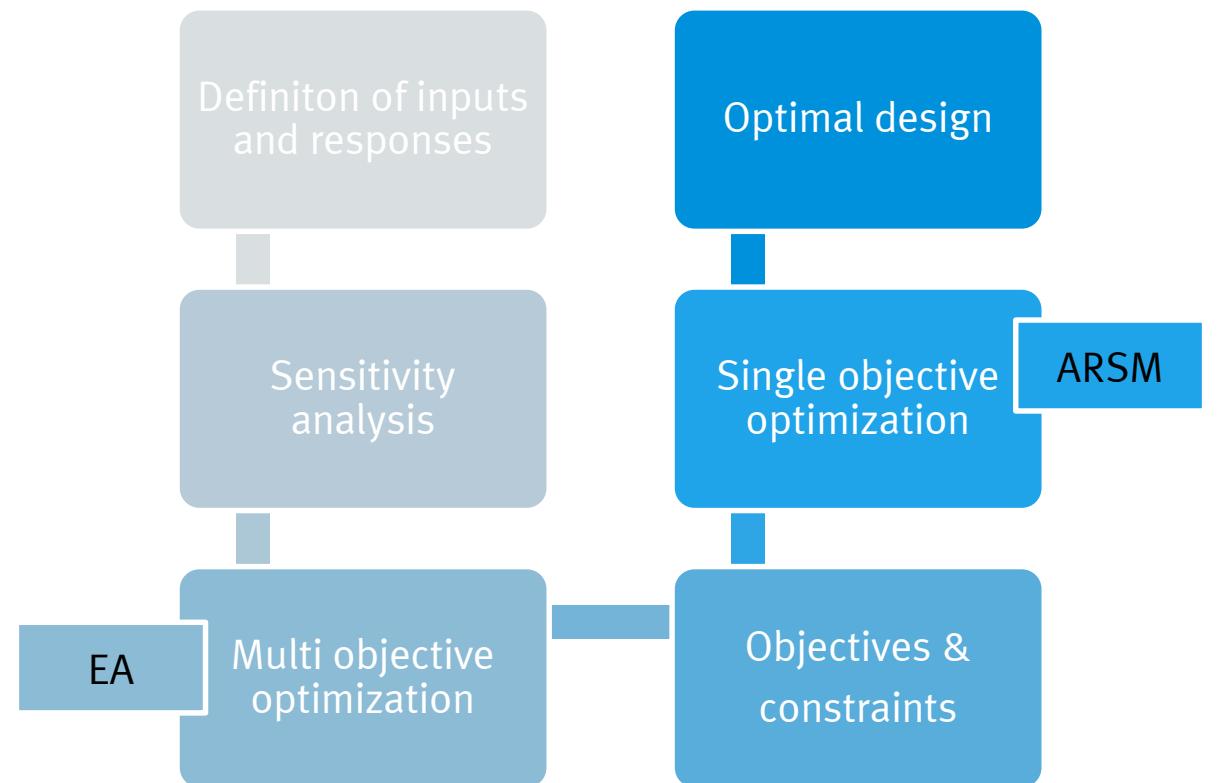
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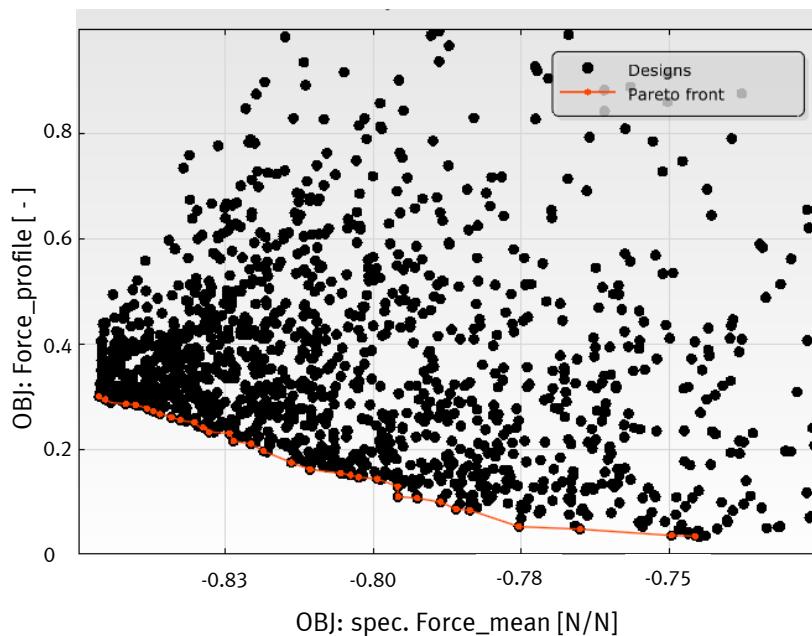


Optimization sequence of cone geometry

- Two main objectives
 - Maximum force vs. appropriate force-curve
- Multi objective optimization
 - Objective vs. Objective
 - Target is a compromise between the objectives
 - Pareto-front as decision base for constraints
- Single objective optimization
 - Objective vs. Constraint
 - Leads to optimal design depending on chosen objectives

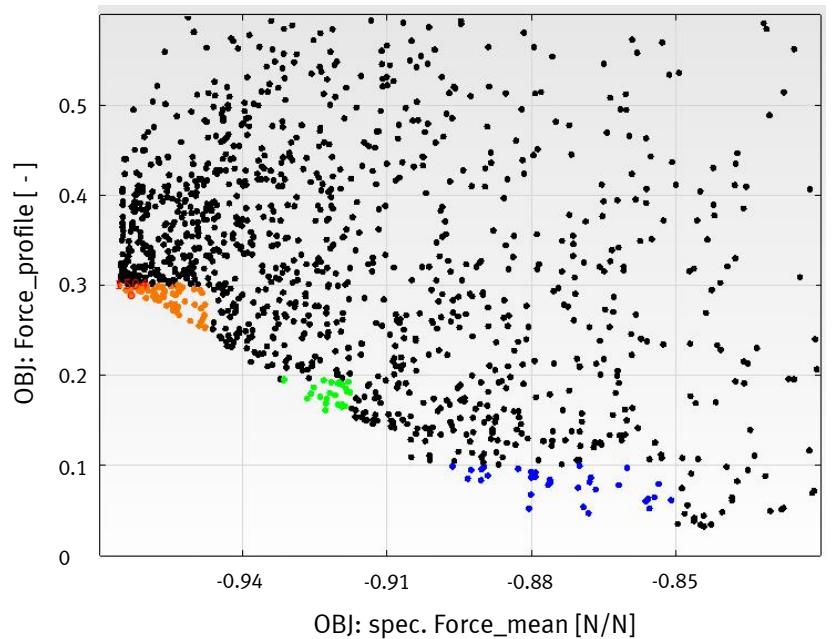


Multi objective optimization



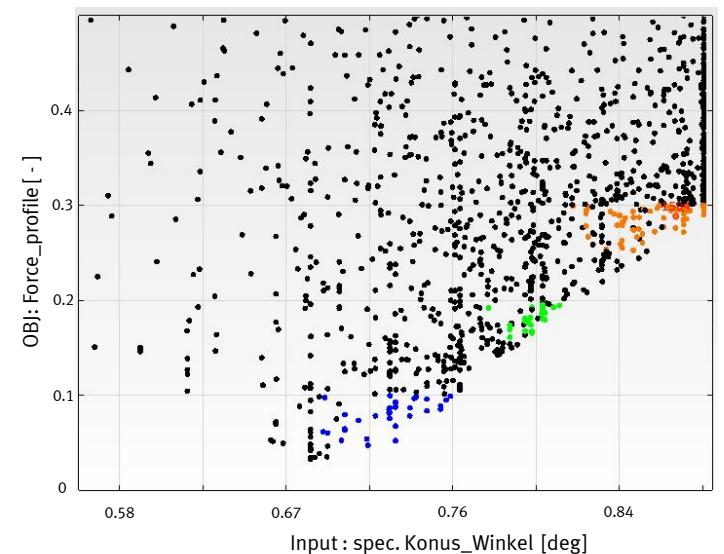
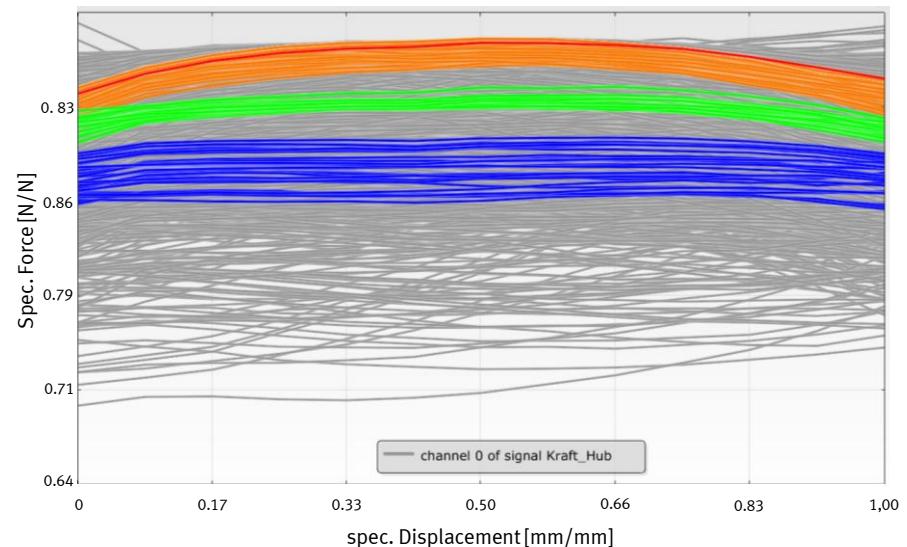
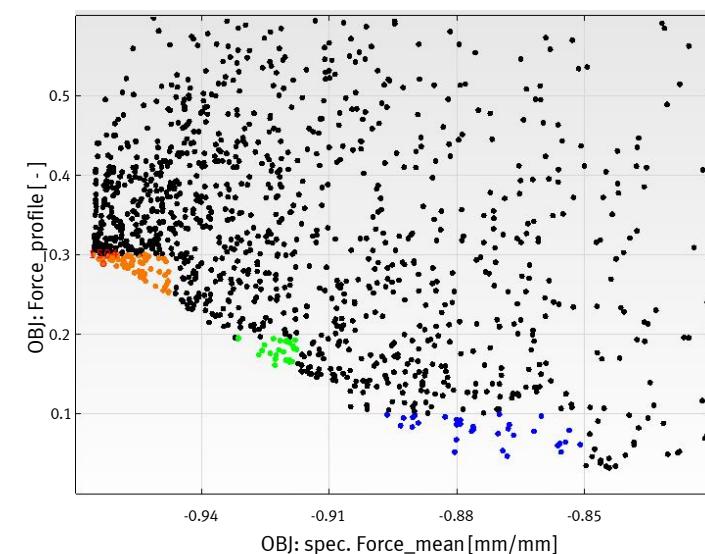
Use colors to visualize
different areas

Cluster analysis



Cluster analysis

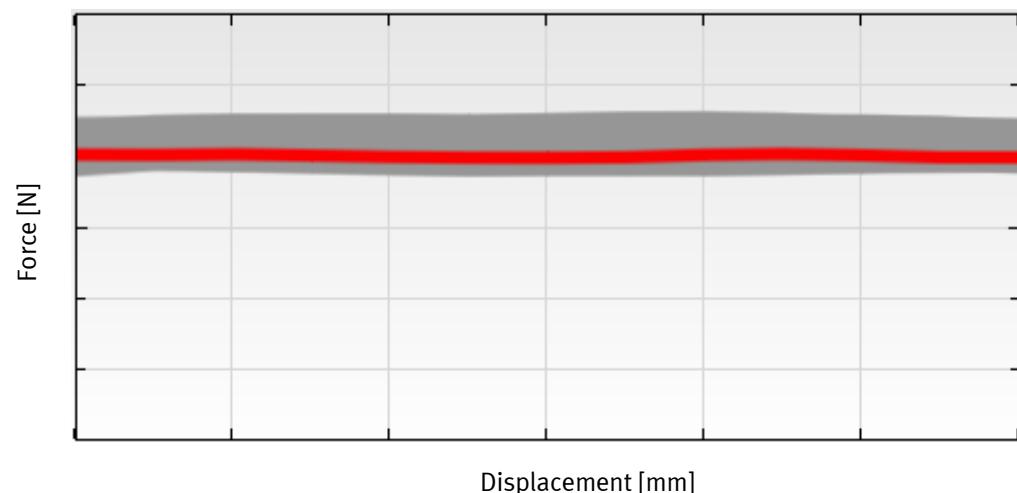
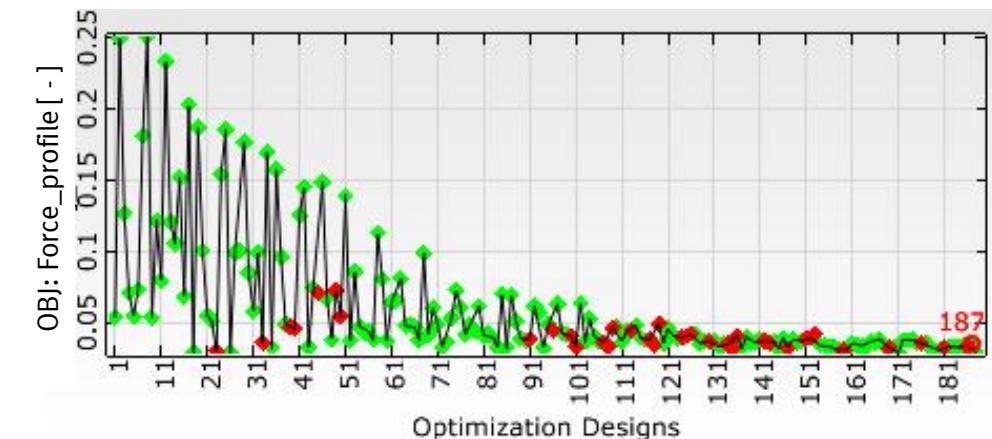
- Cluster analysis of the pareto front designs helps to understand the mapping between inputs and defined objectives
- Compromise between objectives highlighted by manual selection
- **Colored clusters are useful for defining start designs for single-objective optimization**



Single objective optimization using ARSM

- Colored clusters from multi-objective optimization used as start design
- Local search possible
- Fast convergence after 188 designs
- Several optimal designs, each for the chosen target objectives**

Approximation	Quadratic approximation for small amount of variables	
Order:	<input type="radio"/> quadratic	
DOE method:	D-optimal quadratic	
Start range:	0.1	0.1 - with start design → Local search
Computational aspects		
Minimum iterations:	5	
Maximum iterations:	20	
Minimum range:	1e-06	



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What is the conclusion?

Results

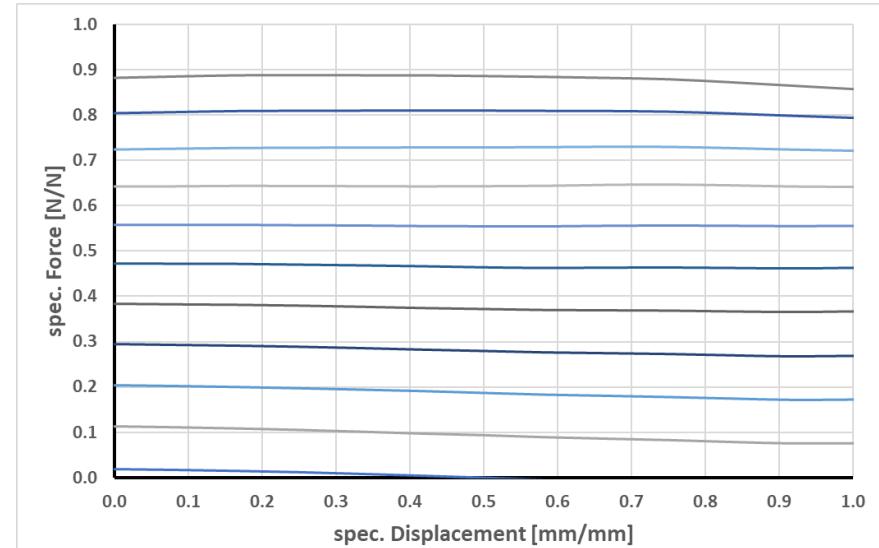


- Sensitivity analysis gives understanding of system behaviour
- Influence on responses depends on input parameter range
- Multi-objective optimization allows manual choice objectives and constraints
- Serves as start designs and enables local search for single-objective optimization
- Systematic approach guarantees reliable results.
- Increased force by about 35%
- Force-displacement curves show only current dependencies

Perspective



- Comparison of simulation results with measured data used as reference curves
- Model calibration



Thank you for your attention

Any questions?

Special Thanks to:

Mr. Markus Stokmaier for support

