

Agenda – Workshop

- Introduction Digital Twins
 - A working Digital Twin
 - Business models – Discussion
- Modules for the digital Twin
 - Data analysis
 - Simulation
 - Understand, Learn, Reasoning, Optimize
 - Surrogate models
 - How to build a digital Twin – Discussion
- „Wrap up“

Computer aided model

Of a ... object

For different purposes

Digital Twin – Benefits

...

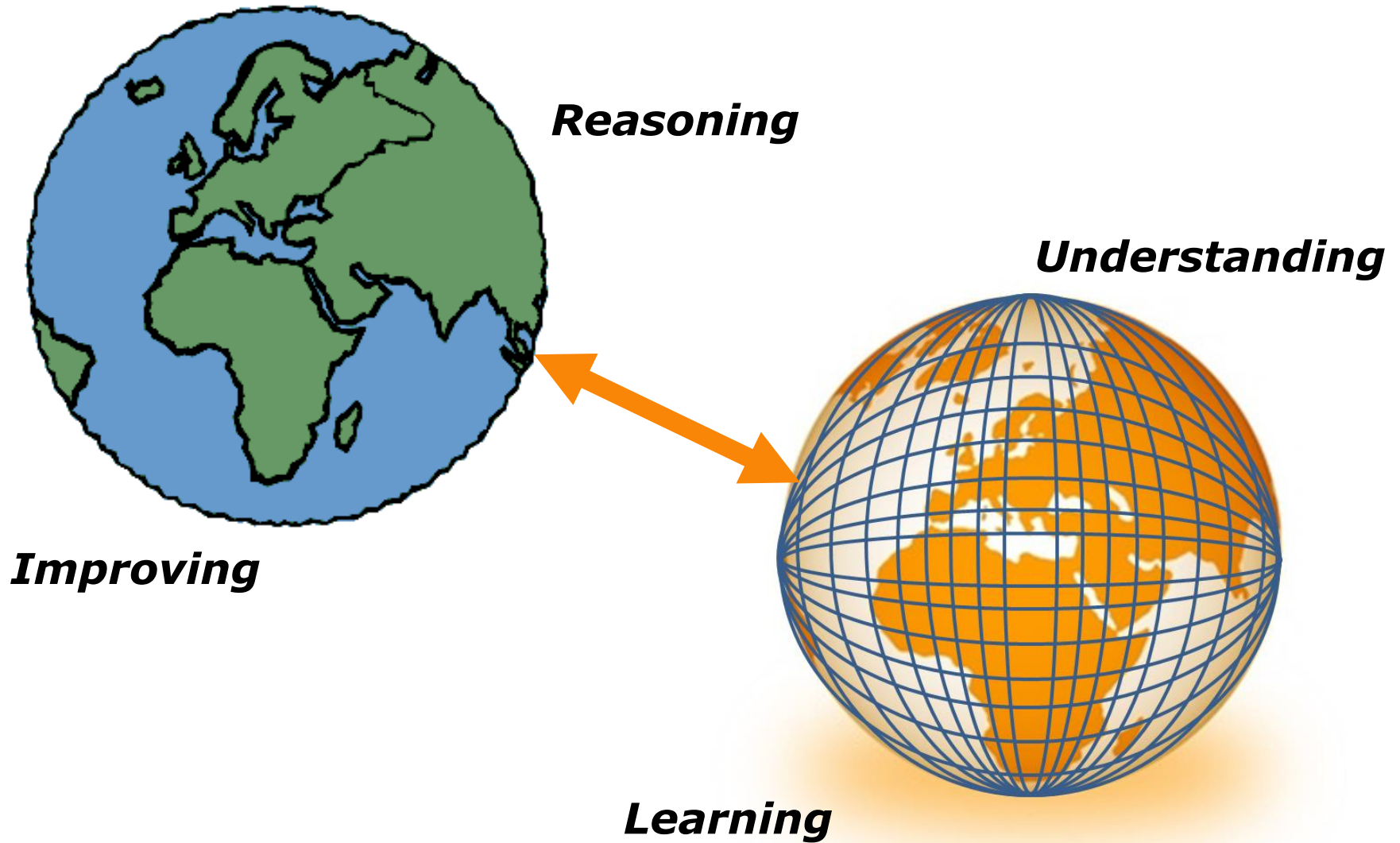
Understanding

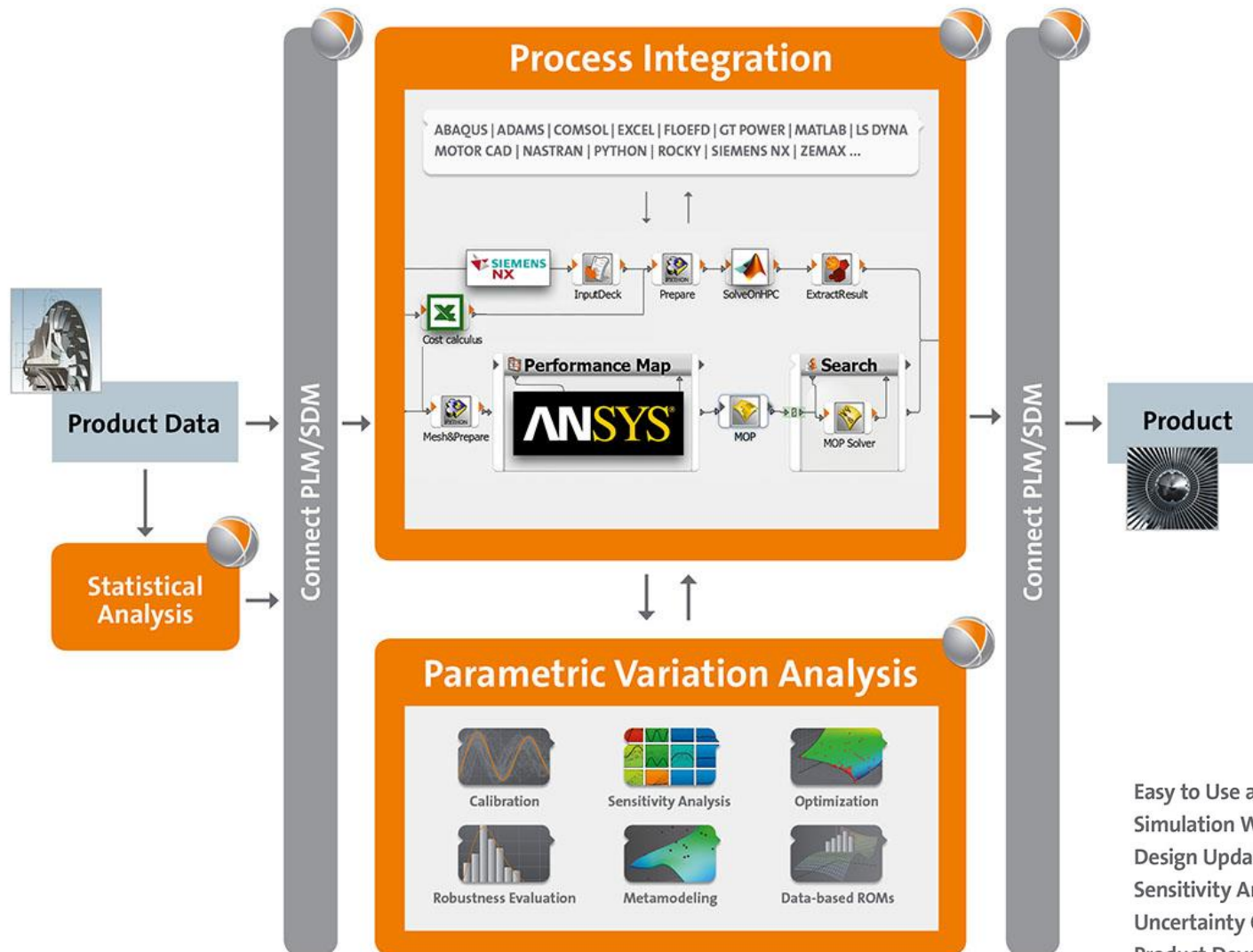
Learning

Reasoning

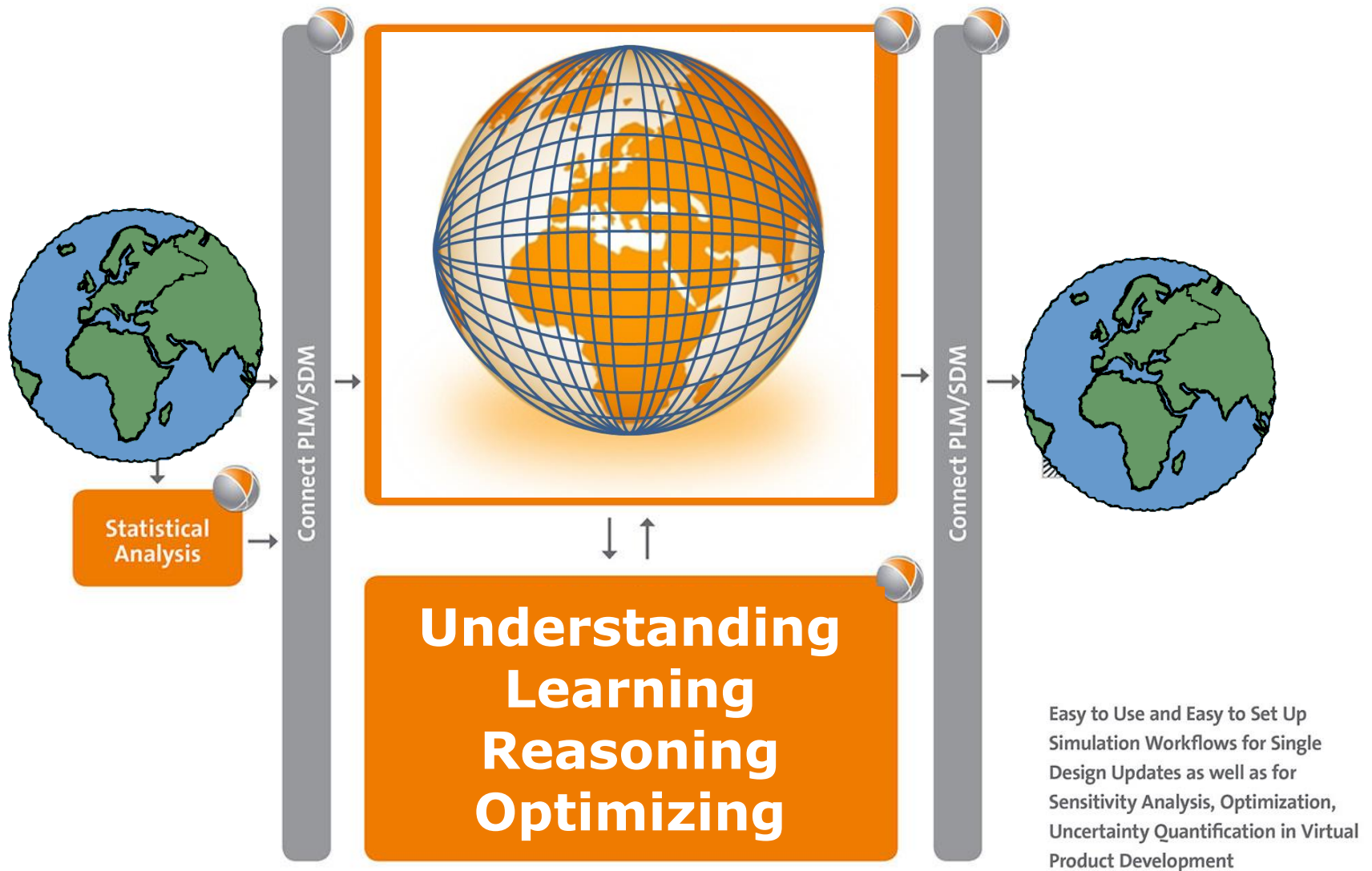
Optimizing

...





Easy to Use and Easy to Set Up
Simulation Workflows for Single
Design Updates as well as for
Sensitivity Analysis, Optimization,
Uncertainty Quantification in Virtual
Product Development



**Let's concentrate on
existing
real world counterparts**

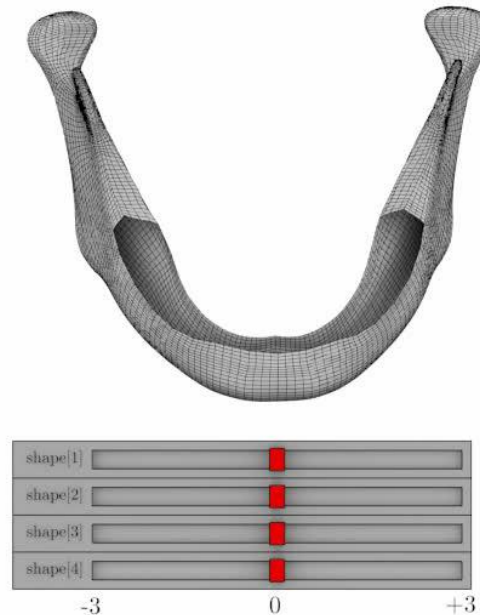
Data analysis

- Use from Webinar
- And other methods

Use case

Autoparameterization of geometric variations

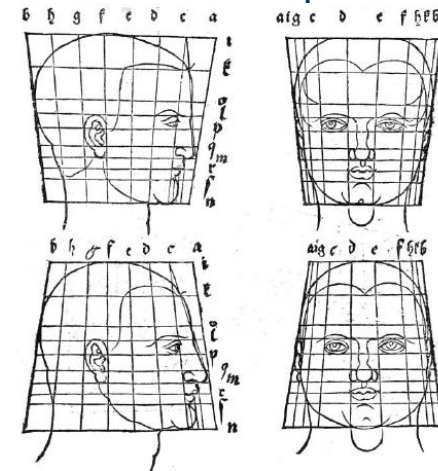
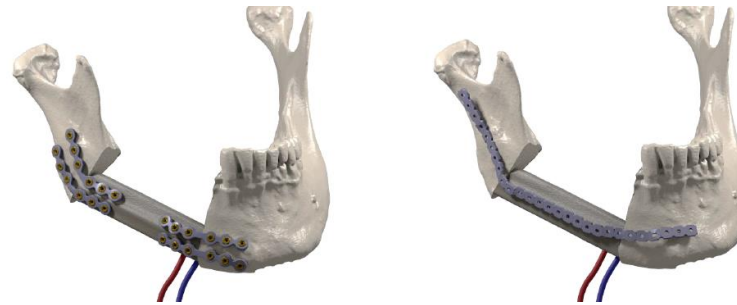
- Input: 60 Measurements of human mandible bones
- Task: Find an optimal parameterization of natural geometric variation patterns based on measurements



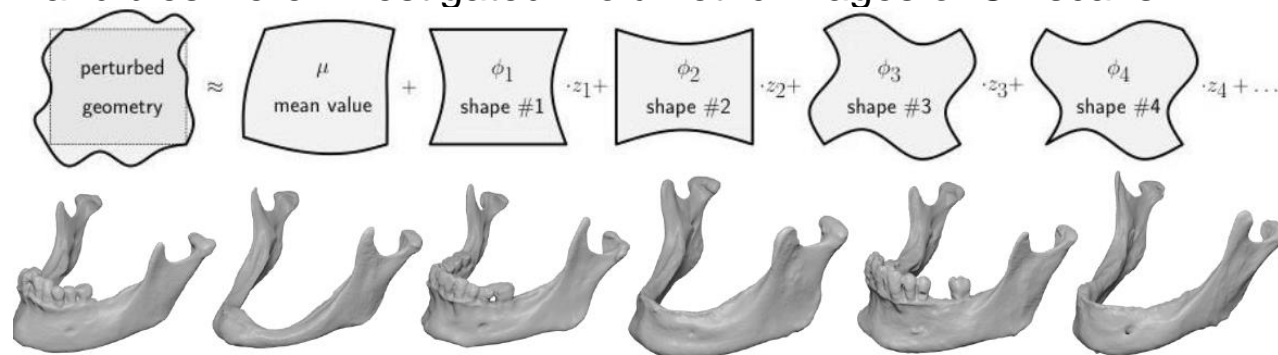
With courtesy of UK Aachen (Source: S. Raith, WOST 2015)

Identify shapes of Differences using SoS

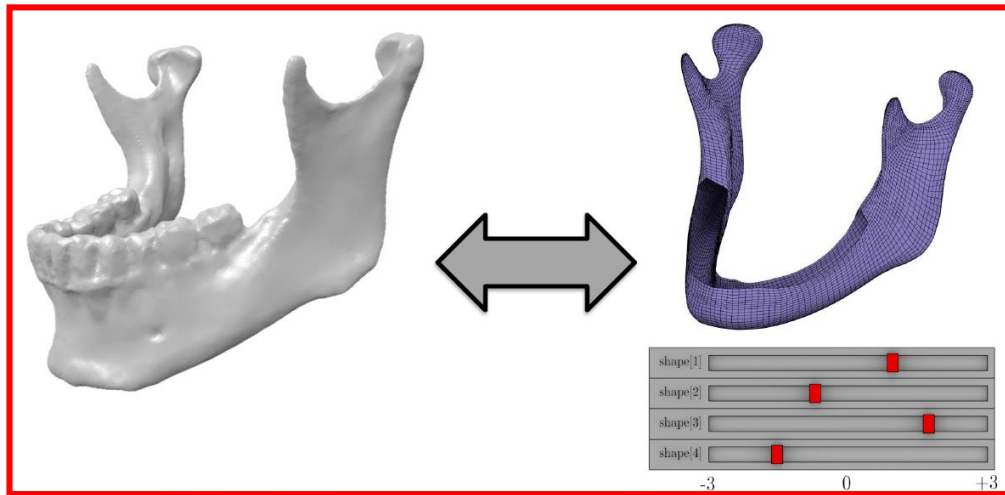
- Reconstruction with bone transplants
- **Problem:** Transplant bone shapes are predefined and don't match the mandible shape
-> could lead to fracture and other problems



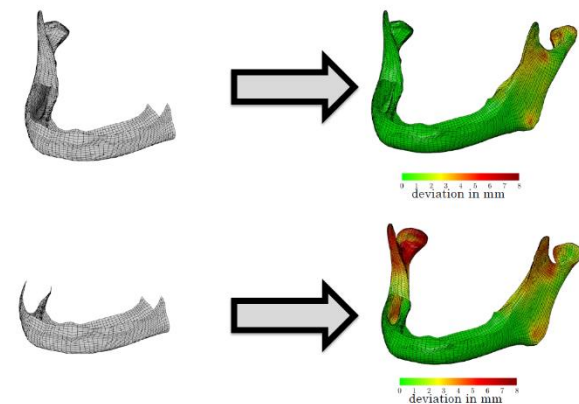
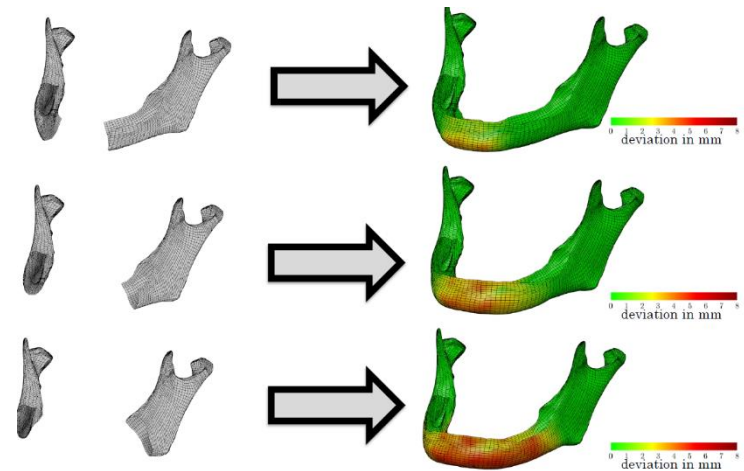
- 63 human mandibles were investigated: Volumetric images of CT scans



Identify shapes of Differences using SoS



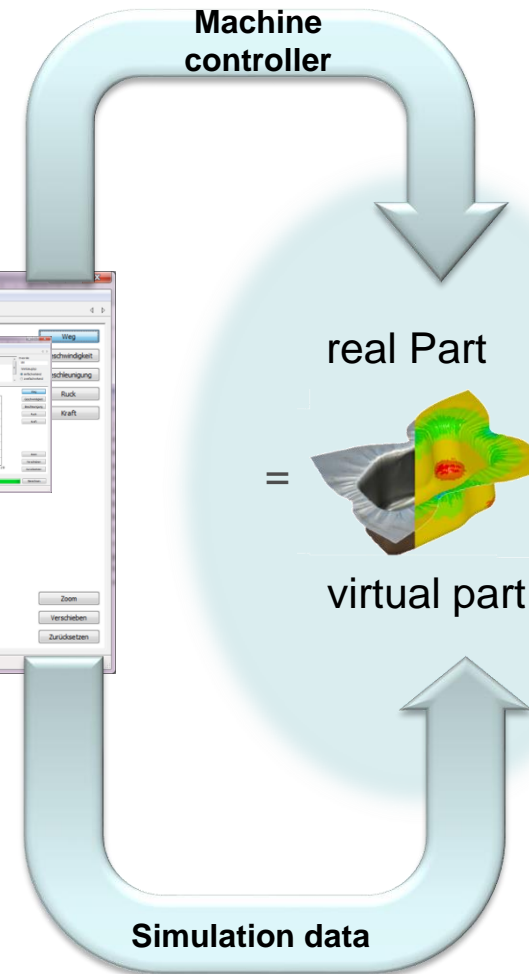
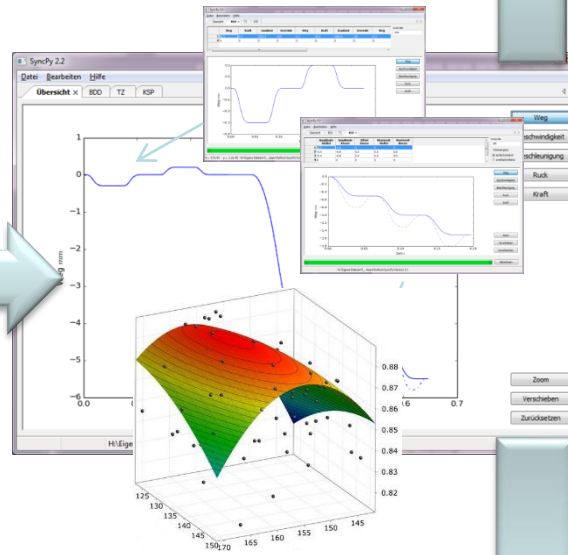
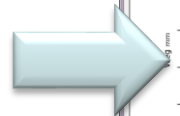
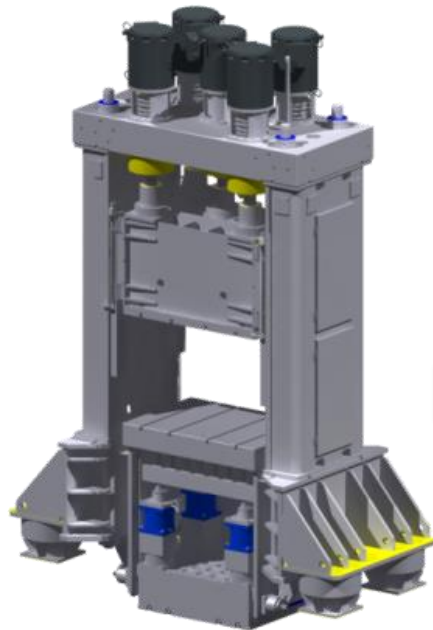
- Calculation of amplitudes that are suitable for best matches between standard geometry and actual mandible shapes



Machine control using metamodels

Process parameter:

- Amplitude
- time
- Force



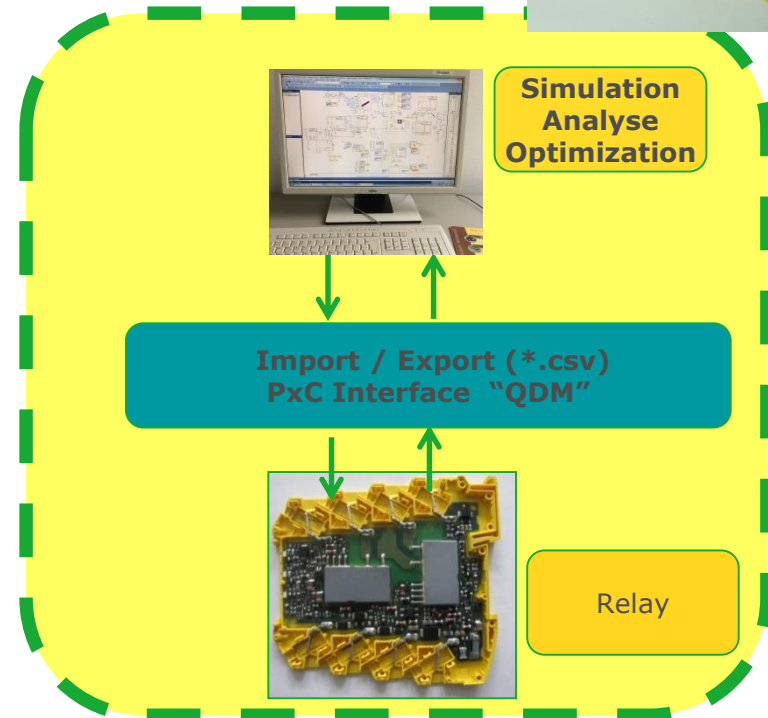
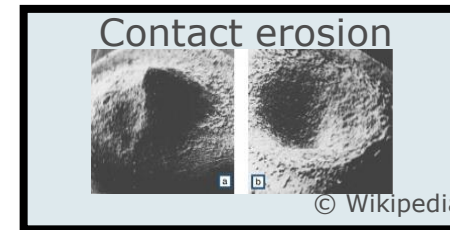
1. Calibrate simulation model with test results
2. Run sensitivity analysis in virtual world and generate MOP for machine control
3. Use MOP to control the dynamic process and optimize forming result online

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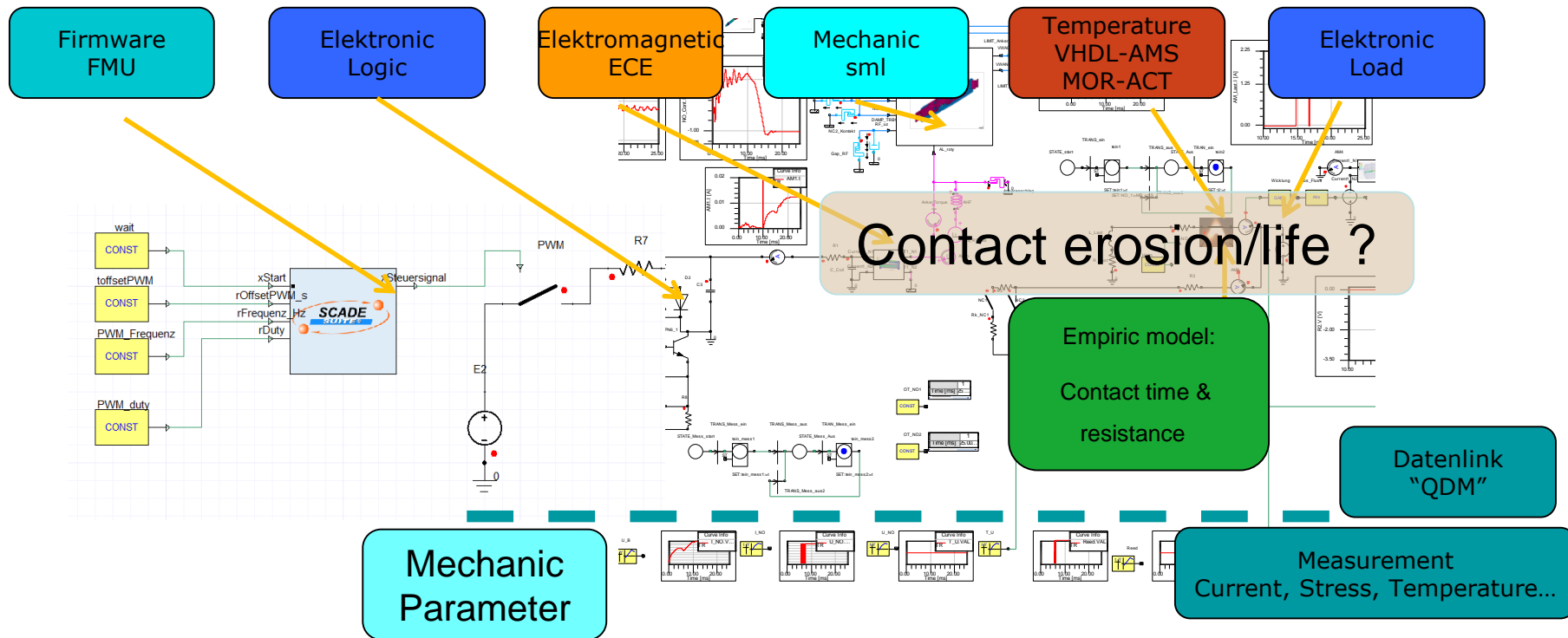


digital twin of a Relay

- Relay is safety critical
- Life of Relay is driven by contact erosion while safety shutdown
- Relay operate in harsh environment, because of housing no inside measures possible
- Today relay needs to be replaced when a 10% probability of end of life is estimated (very conservative)
- From possible measures of "relay in use" like current, voltage, temperature a „digital twin“ should track the remaining life
- With working digital twin remaining life and replacement cycle can be tracked and optimized



Relay Simulation model in Simplorer



System simulation model was build.

To be used for digital twin contact life and mechanical parameter need to be identified automatically.

by courtesy of     

Contact life of the Relay with data based ROM's



splitting postprocessing/database import version 6.0.0
Designs were imported from: D:\lightwin\Modul\MOP\MOP-UP-AC15_MOP-UP_Allgemein.omdb

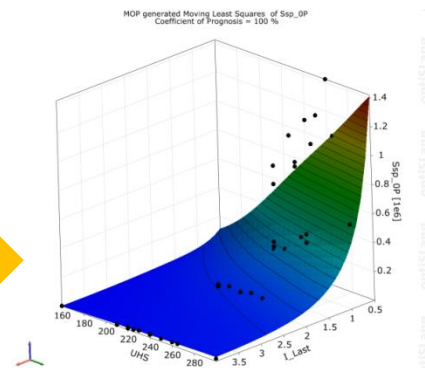
Reference	Success	I_Last	Temp	UHS	t_Prel_S	Ssp_50P
Reference	X	0.5	20	220	4.57	

Designs	Success	I_Last	Temp	UHS	t_Prel_S	Ssp_50P
01	X	2	20	240	0.56	0.000000
02	X	2	20	220	1.10	0.000000
03	X	2	20	200	1.25	0.000000
04	X	2	10	230	1.85	0.000000
05	X	2	10	240	0.56	0.000000
06	X	2	10	280	0.82	0.000000
07	X	2	10	220	0.4	0.000000
08	X	2	10	240	0.24	0.000000
09	X	2	80	240	0.57	0.000000
10	X	2	80	260	0.56	0.000000
11	X	2	80	230	1.24	0.000000

Relay values for

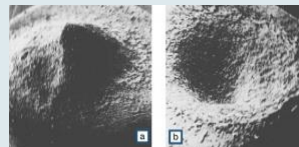
- Load
- Environmental conditions
- failure rate

Excel Add-In



MoP

Contact erosion



© Wikipedia



FMU

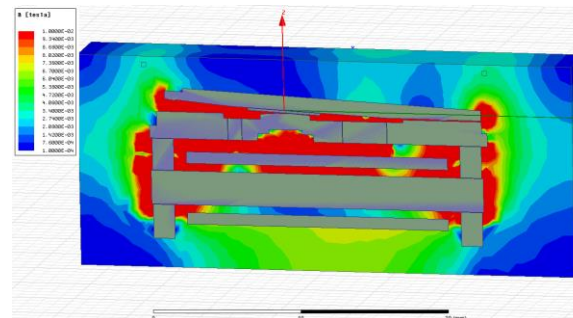
Measurements in the window of operation give the data base to approximate contact erosion and life.

by courtesy of 

Mechanical Parameter of relay in action cannot be measured in field!



Identify mechanical parameter (throw) from magnetic field.



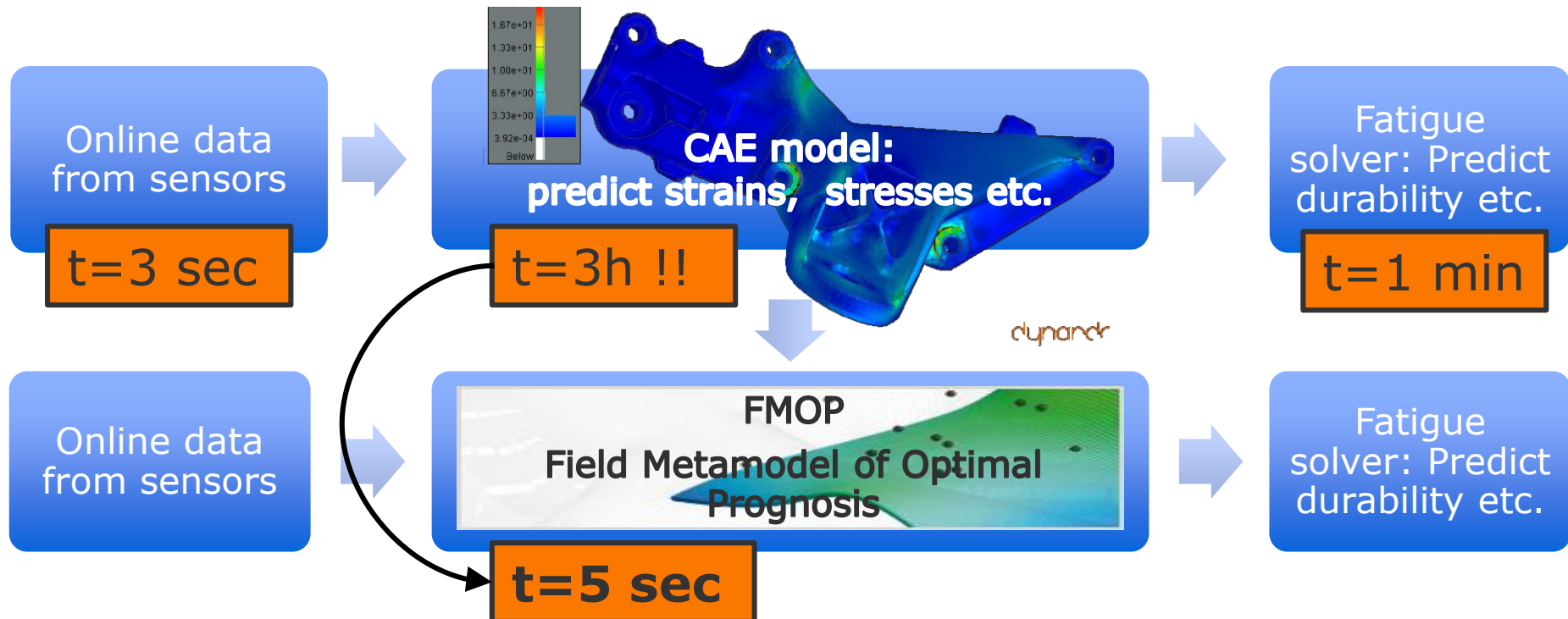
by courtesy of 

„Echtzeit“

- „All machines: Stopp“
 - Rules, Codes, ...
 - Possible maintenance intervalls
 - Possible measurement intervalls
 - Decision processes
 - Approval processes
 - ...
-
- ➔ Which decisions are influenced by the twin?
 - ➔ When and how fast has the twin to help?

Real-time approximation of FEM solutions

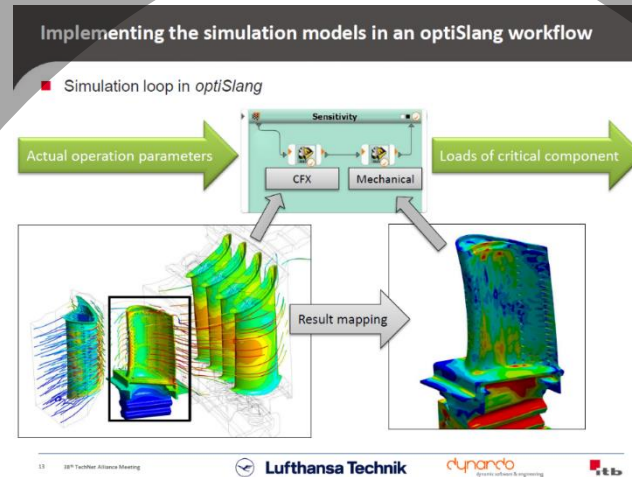
Decisions in embedded devices with sensor data



- **Replace** expensive parts of the CAE model by high-accurate meta models
- FMOP/SoS **approximates stress, strain, displacements** etc. for **EACH FEM NODE**; needs DOE to create data driven models
- FMOP is fast and needs little memory, suitable for large-scale systems

With courtesy of MAGNA (Image source: R. Lampert, International FEMFAT User Meeting 2016)

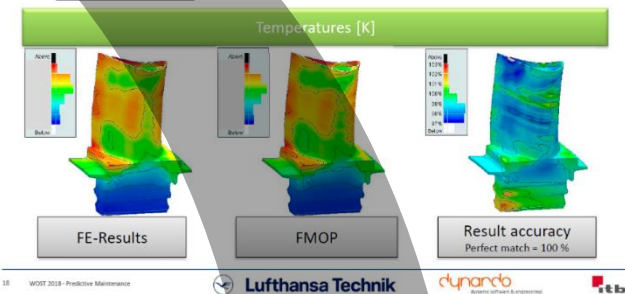
1 selected DOE sample runs 15 hours at HPC cluster.



- FMOP in *Statistics on Structures*

FMOP_VALIDATED
Statistics on Structures
4.90 GB

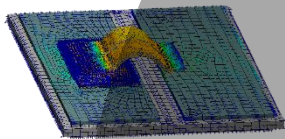
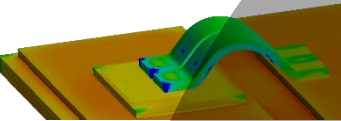
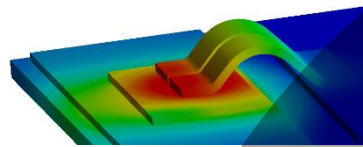
File includes the FE-results of the validation points for direct comparison



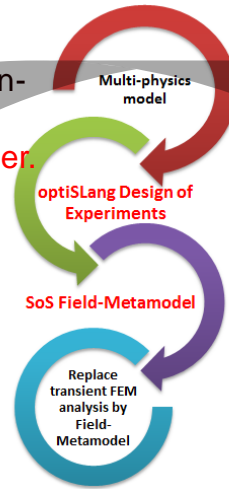
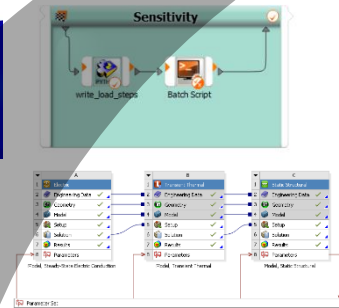
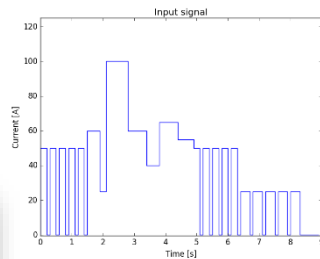
- Shared library and ANS C interface for usage in C++, Python, Matlab, Twin builder
- One flight forecast evaluation runs in seconds

A DOE of relevant loading is created and is calculated with high fidelity ANSYS based non-linear electric-thermal-mechanic simulation.

9 seconds of loading runs 1 day at HPC cluster.

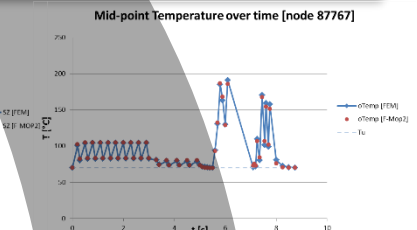
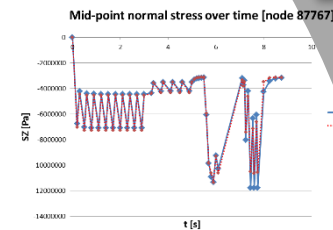
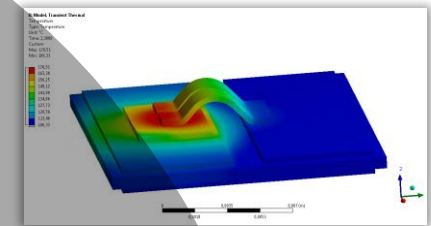


Parametric Signal represent possible electric loading of ECU unit



Excellent approximation quality for transient temperature and contact stresses!

BOSCH SoS Custom Algorithm



Field ROM ready for system simulation, digital twins

- Shared library and ANS C interface for usage in C++, Python, Matlab, Twin builder, optiSLang

Faster than real time: 9 seconds of loading run in 6 seconds using Field ROM.

Scalar ROM's

ROM's based on scalar input and scalar output values

FMU/FMI/DLL based integration

From ANSYS Solver ...

From DX

From optiSLang

From any external source providing FMU/FMI/DLL interfacing

Signal ROM's

ROM's based on inputs or outputs as time depended (transient) or frequency depended ROMS

DLL based integration

From ANSYS Solver ...

From optiSLang/SOS

Data (sensor) & CAE solver agnostic

(Note: Dynardo has successfully done for MATLAB Simulink, same procedure should work for twin builder, DLL/API can be provided to test)

Field ROM's

ROM's based on inputs or outputs as 2D (surface) or 3D (volume) field data

DLL based Integration

From ANSYS Solver

From optiSLang/SOS

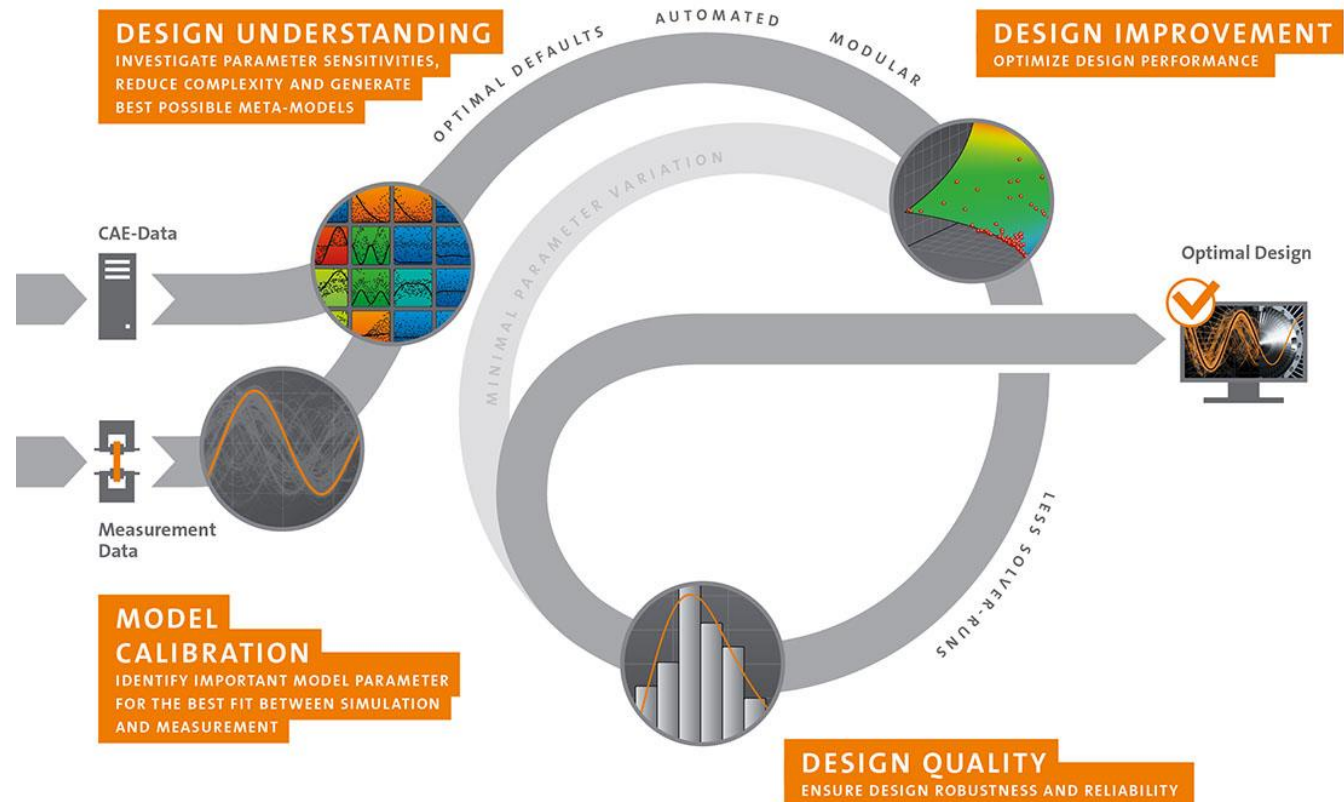
Data (STL, foto,..) & CAE solver agnostic

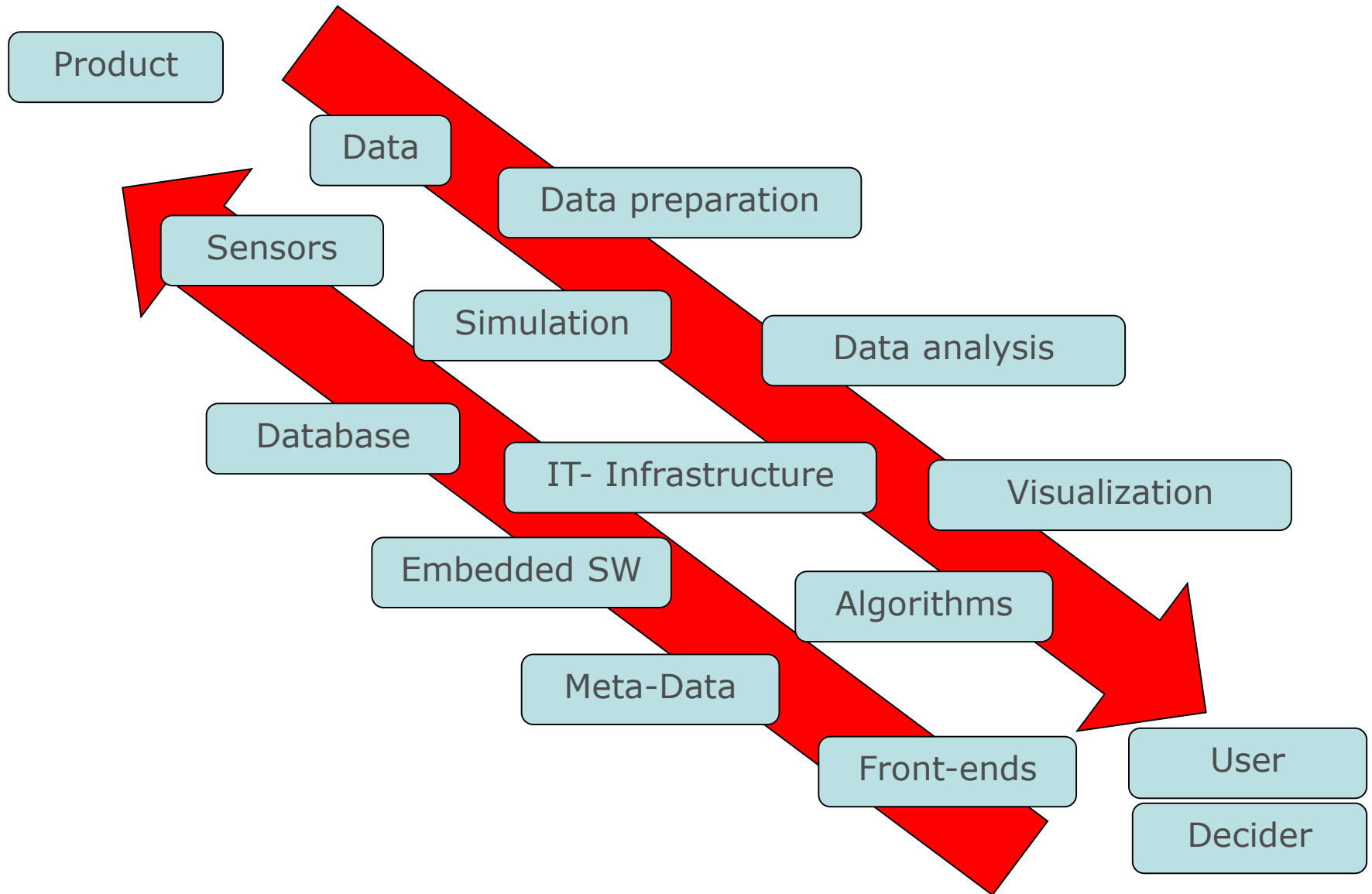
(Note: Dynardo has successfully done for MATLAB Simulink, same procedure should work for twin builder, DLL/API can be provided to test)

- Calibrate

- Understand
- What if
- Optimize
- Verify

Workflow of Virtual Product Development Using Calibration, Sensitivity Study, Optimization and Uncertainty Quantification to Result in Optimal and Robust Designs





User of Digital Twin is

- No optiSLang expert
- No Sensor expert
- No Simulation expert
- No Data analysis expert

➔ Need user friendly interface

Operator needs

- Maintenance improvement of DT
- Standard process
- Traceable processes

➔ PLM/SPDM

All

- No installation of all tools
- No licenses, ...
- No time to install, .. maintain

➔ Central (Web-)interface

- Do you have a running Twin?
- Where can you/your customers consider Digital Twin's help?
(*where is it just „nice technics“?*)
- Which (sensor-) data do you already measure, store, „manage“ in system, ...
- Which modules do you have already?
- Which additional technical issues to be have considered
- Who has to be involved?
- What is a possible roadmap?