

Design for Reliability Approach for Ensuring the Solder Joint Reliability of eWLB Packages in Automotive Radar Applications Using ANSYS optiSLang and ANSYS Mechanical

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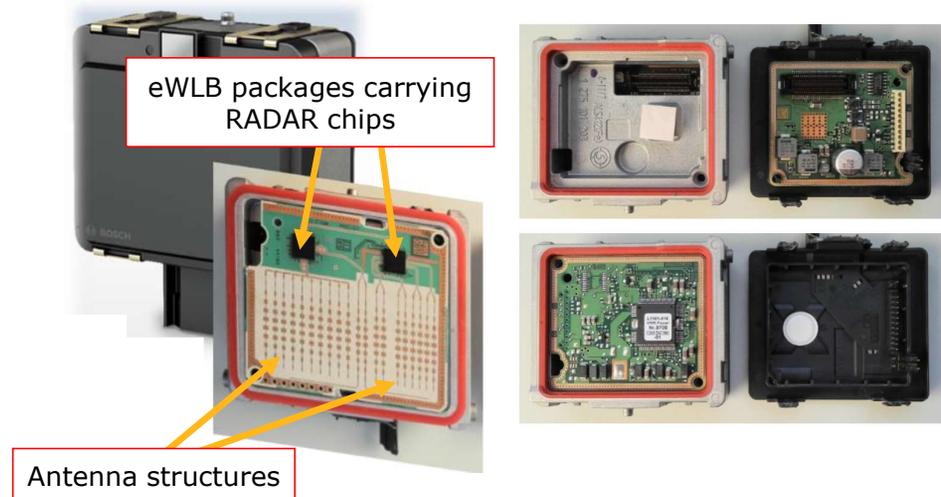
17th Weimar
Optimization and
Stochastic Days 2020 June 25 – 26, 2020
Virtual Conference

Ansys / DYNARDO



Agenda

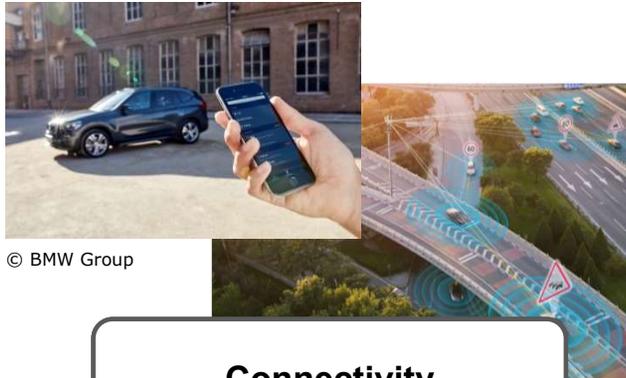
- Design for Reliability: Challenges and Motivation
- Results from WOST2019
- Comparison with Measurements
- Simulations for Three Cases and Metamodels of Optimal Prognosis (MOP)
- Reliability Analyses based on MOP
- Conclusion



Design for Reliability: Challenges and Motivation

Trends influencing reliability requirements

Courtesy of Ulrich Abelein
(Infineon Technologies AG)



© BMW Group

Connectivity



© Audi AG

Autonomous Driving



Urbanization



E-mobility

Design for Reliability: Challenges and Motivation

Contributing factors

Courtesy of Ulrich Abelein
(Infineon Technologies AG)



Table 45: Description General part
Operating situations

Operating situation	Vehicle parked	Charging cable inserted	High-voltage battery pack charging	Power line communication active (if available)
Driving operation	no	no	yes/no	no
Charging operation	yes	yes	yes	yes
Preconditioning	yes	yes/no	yes/no	yes/no
On-grid parking	yes	yes	no	yes
Off-grid parking or parking	yes	no	no	no

Contributing factors:

- › Additional operating states beside driving:
 - On-grid parking
 - Vehicle-Preconditioning (battery as well as driver comfort like cabin heating)
 - Charging

Consequences:

- › Increase in operating times

→ Increase in reliability requirements

Design for Reliability: Challenges and Motivation

Requirements based on operating situation

Courtesy of Ulrich Abelein
(Infineon Technologies AG)



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Operating states for e-vehicles according to LV124

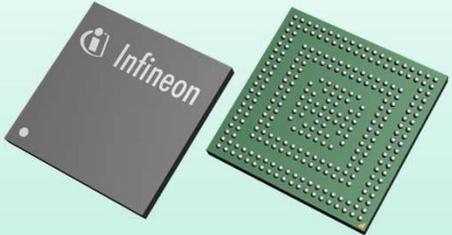
Example requirements

Operating situation	Hours accumulated hours over lifetime
Driving operation	8,000 h
Charging operation	30,000 h
Off-grid parking	92,000 h

Note: 5,500 h comfort-preconditioning (e.g. heating the cabin) might be estimated although not required as a state in the table.

Design for Reliability: Challenges and Motivation

Extended mission profiles E-mobility (data from 2018)



Example:
Microcontroller for **use in a battery charging system**

Lifetime (same like vehicle): 15 years

- > Op. Ambient Temp. Range: -40 °C to 125 °C
- > Non-operating time: 91,400 hours
- > Operating time: 40,000 hour

Customer's Mission Profile*

T _{ambient} [°C]	Time [h]
Operating	
125	400
120	3,200
76	26,000
23	8,000
-40	2,400
Non Operating	
85	914
80	7,312
60	59,410
23	18,280
-40	5,484

*) Arbitrary chosen, corresponding to "Automotive Application Questionnaire for Electronic Control Units and Sensors", ZVEI, October 2006

Is today's AEC-Q100 qualification covering this lifetime requirement?

More details on AEC: <http://www.aecouncil.com/>
 Example: AEC-Q100 Rev H: http://www.aecouncil.com/Documents/AEC_Q100_Rev_H_Base_Document.pdf

Design for Reliability: Challenges and Motivation

Extended mission profiles E-mobility (data from 2018)

Courtesy of Ulrich Abelein
(Infineon Technologies AG)



Equivalent HTSL stress time

Assumptions:

Arrhenius Model with $E_a=0.7$ eV, Self heating: 20 °C

Result:

$T_{\text{stress,eq}}$ @175 °C = 1,521 h

$T_{\text{stress,eq}}$ @150 °C = 4,437 h

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AEC-Q100 stress test conditions (Grade 1)

500 hours @ 175 °C or

1000 hours @ 150 °C

**<30% coverage
of extended
requirements**

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AEC-Q100 stress test conditions (Grade 1)

500 hours @ 175 °C or
1000 hours @ 150 °C

AEC-Q100 stress test conditions (Grade 0)

1000 hours @ 175 °C or
2000 hours @ 150 °C

**<30% coverage
of extended
requirements**

**~60% coverage
of extended
requirements**

→ Today's AEC-Q100 qualifications do not cover extended requirements

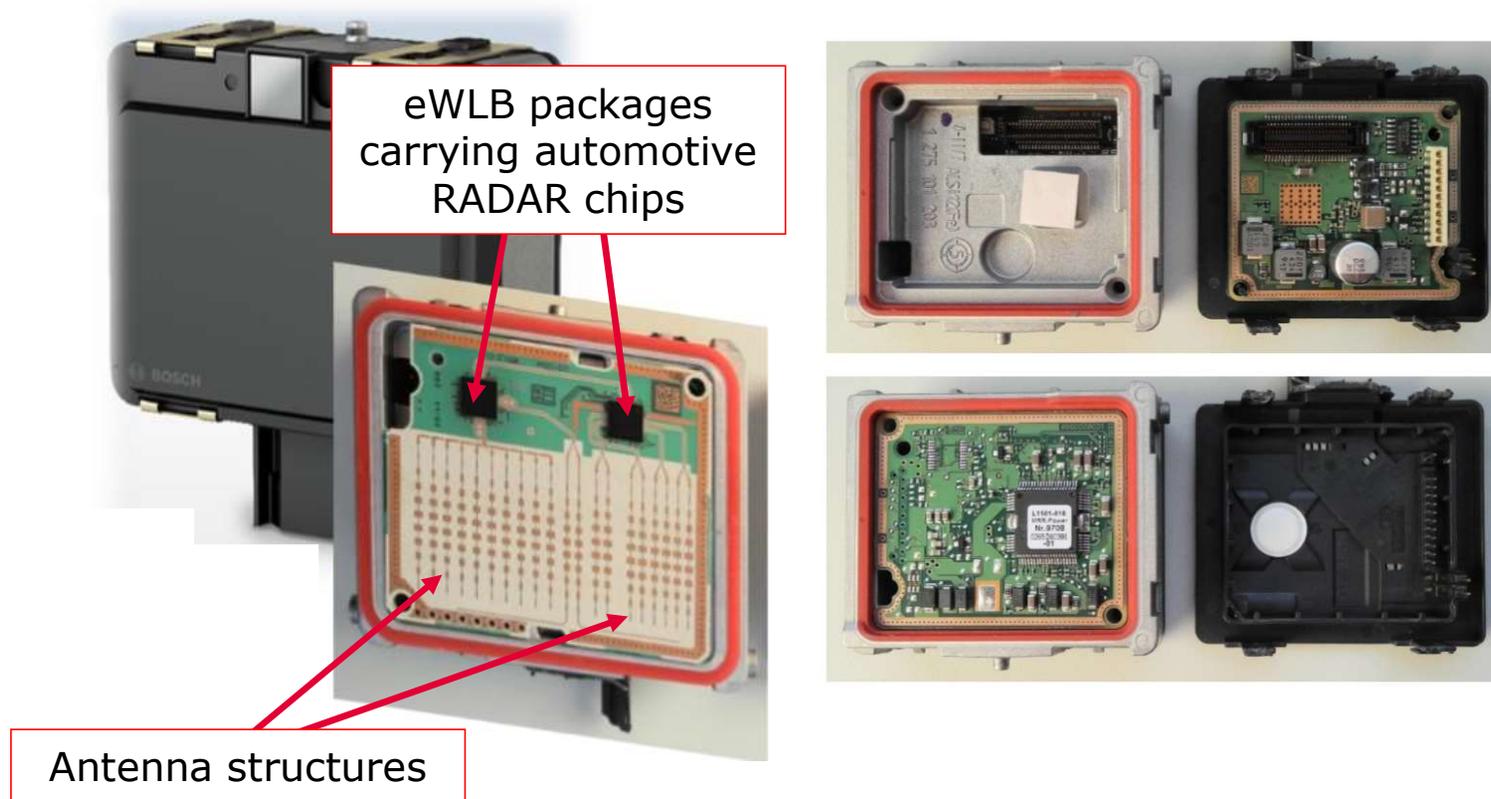
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Investigated application

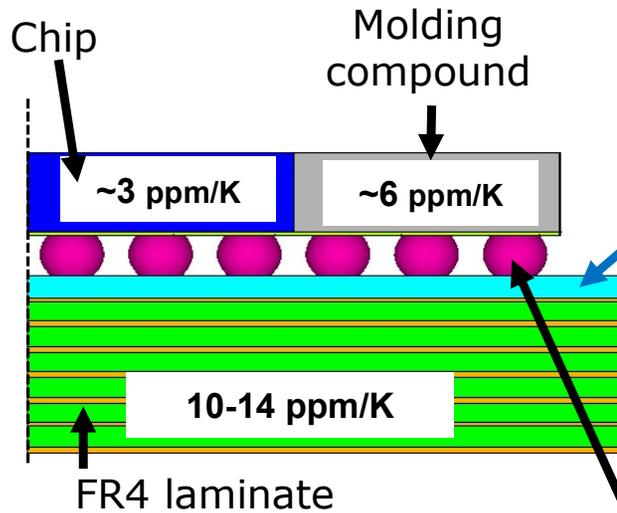
Automotive RADAR



Source: M. Eichhorst *et al.*, VII. SGW-Forum, 2019

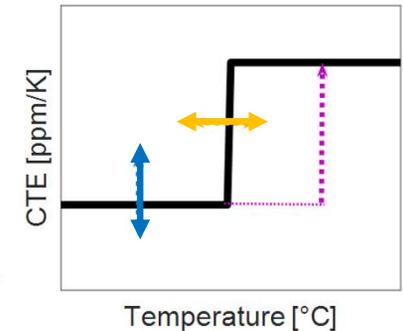
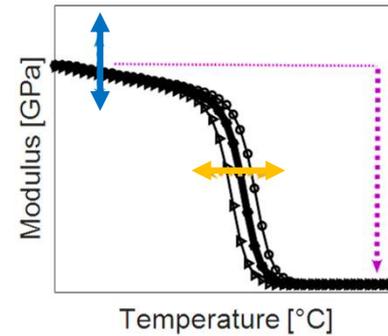
Key findings WOST2019

Solder joint reliability of eWLB radar package



RF laminate (top layer)

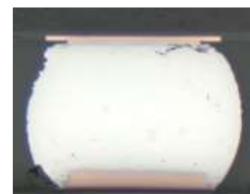
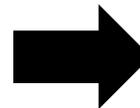
Material properties



CTE mismatch



Cyclic Stress



Solder ball (healthy)



Solder ball (broken)

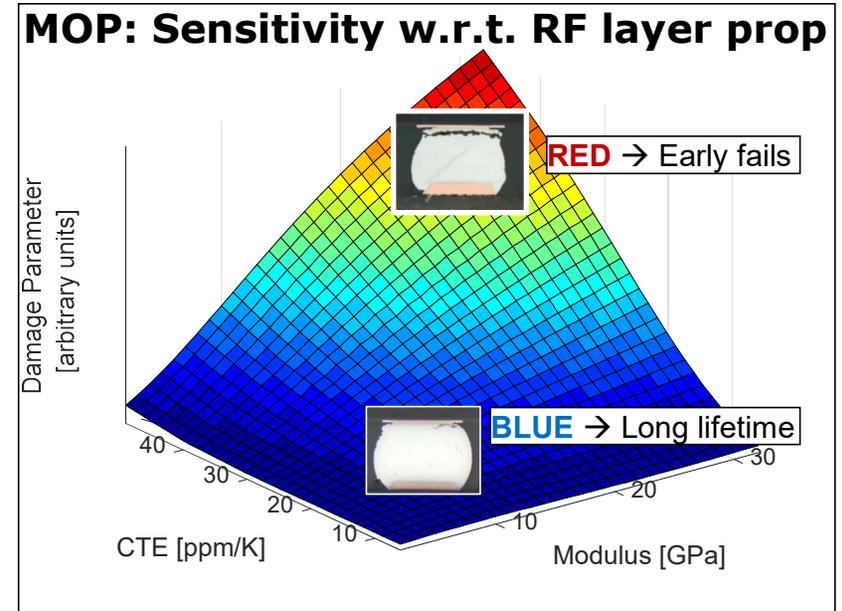
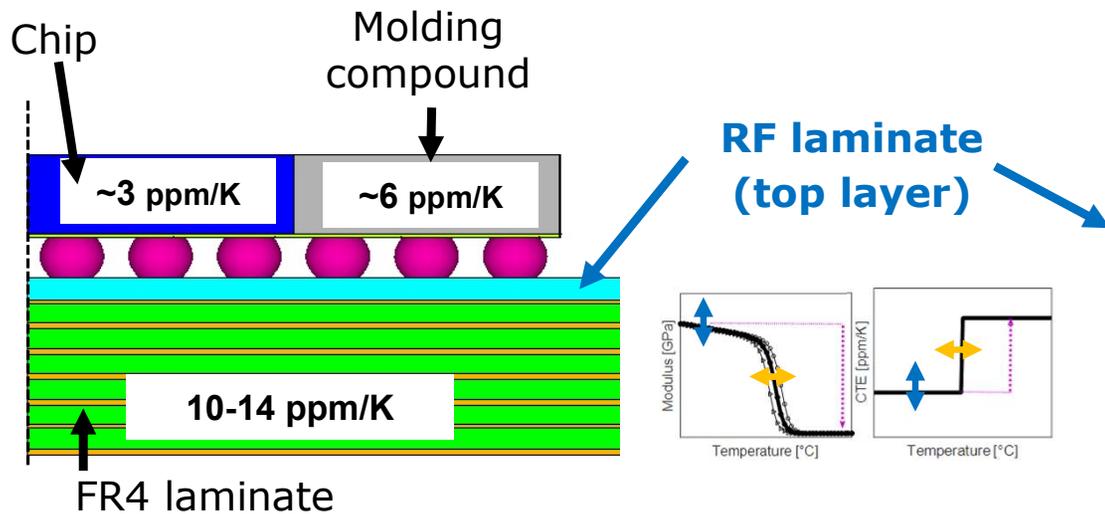
> Impact of material properties of RF laminate on solder joint reliability was investigated

For more details see archive of WOST2019:

https://www.dynardo.de/fileadmin/Material_Dynardo/bibliothek/WOST16/4_WOST2019_Session_3_Niessner.pdf

Key findings WOST2019

Solder joint reliability of eWLB radar package



> Summary of sensitivity study:

- For low CTE, the RF laminate generates a “CTE transition” between the PCB and the package
- For low E modulus, the RF laminate becomes a “buffer”

For more details see archive of WOST2019:

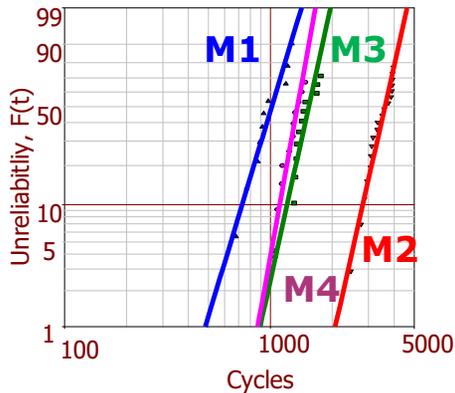
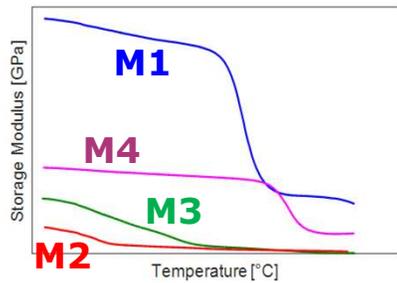
https://www.dynardo.de/fileadmin/Material_Dynardo/bibliothek/WOST16/4_WOST2019_Session_3_Niessner.pdf

Key findings WOST2019 (continued)

Experimental validation 2019 and 2020

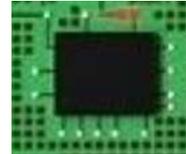


Reliability experiment

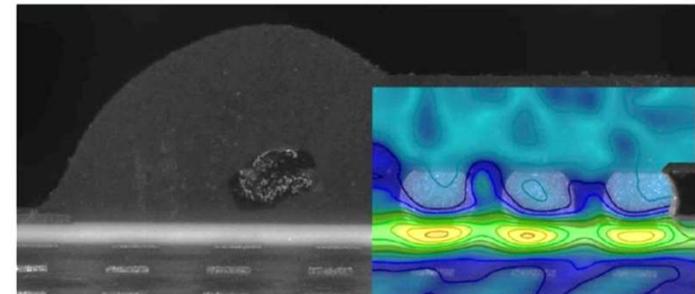
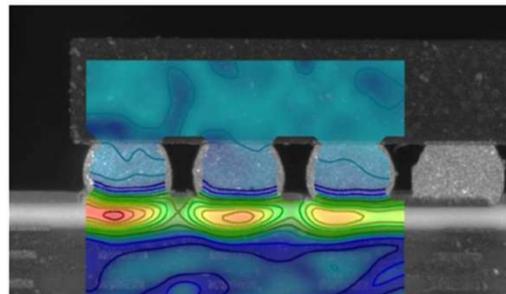


In-plane DIC

Free PCB
No
Cornerbond



Free PCB
With
Cornerbond



radar4FAD

Courtesy of



Chemnitzer
Werkstoffmechanik GmbH

GEFÖRDEBT VOM

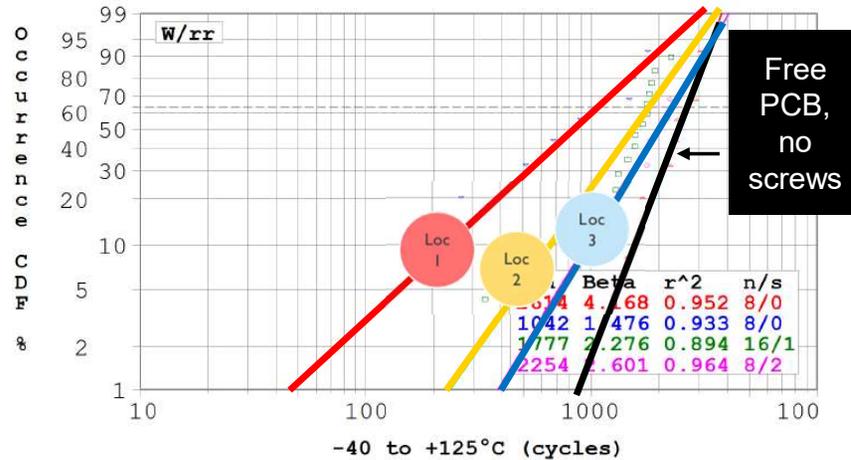
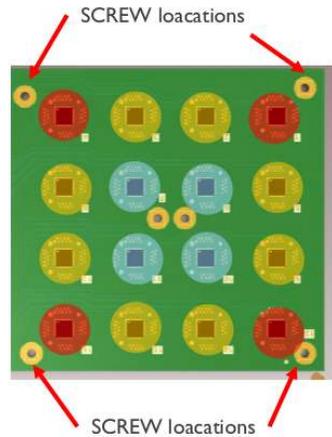


Bundesministerium
für Bildung
und Forschung

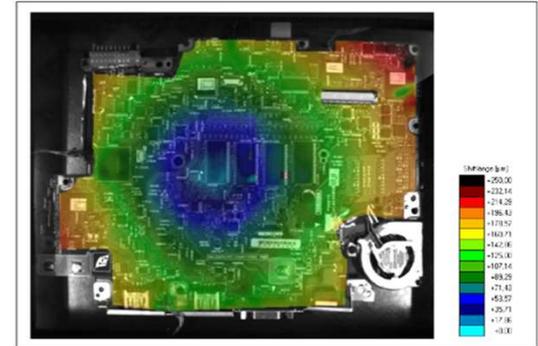
> Findings from sensitivity study are experimentally verified

Next steps in WOST2020

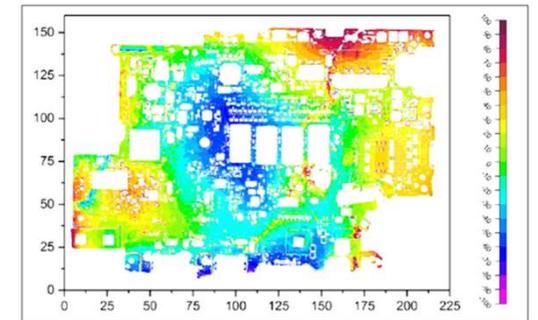
Investigation along value chain



Source: Bart Vandeveld, EuWoRel 2019



In-plane deformation



Out-of-plane deformation

- > Experiments show that solder joint reliability is locally reduced when the PCB is no longer free, but mounted in a housing
- > **Limitation:** Suppliers of electrical components can only do testing on free, non-mounted PCBs as module design unknown
- > **Consequence:** Delta between Tier2 and Tier1 reliability results

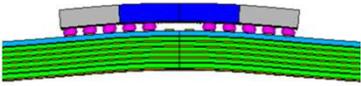
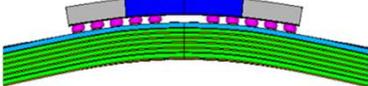
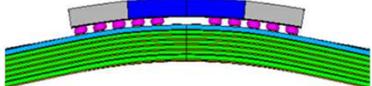
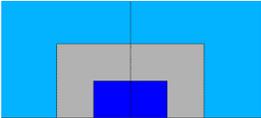
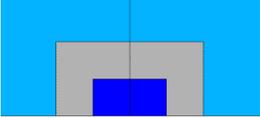
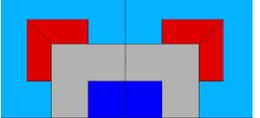


Source: M. Eichhorst et al., VII. SGW-Forum, 2019

Next steps in WOST2020

Investigation along value chain using MOP



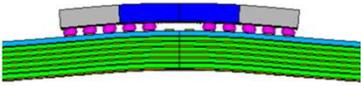
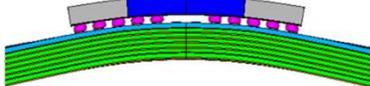
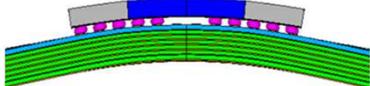
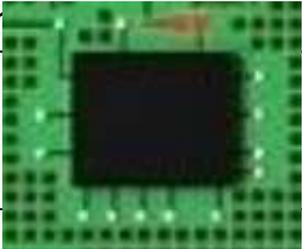
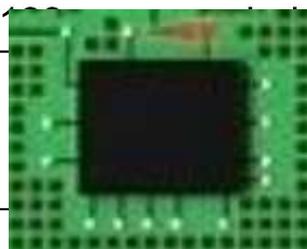
Case	#1	#2	#3
Situation	Tier2 type reliability test	Tier1 type module loading	Tier1 type module loading + cornerbond
Temperature loading	Yes	Yes	Yes
Bending because PCB is fixed to housing	No	Yes	Yes
View of deformation during loading	 100x over-scaled	 100x over-scaled	 100x over-scaled
Top view (half model)			

- > MOPs are used for studying the solder joint reliability along the value chain, especially regarding the RF material design space

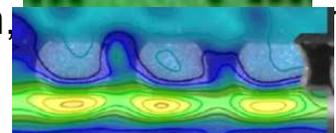
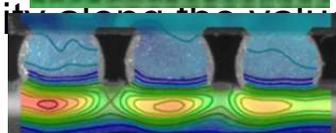
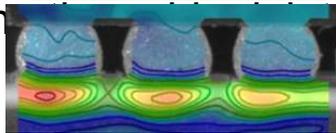
Next steps in WOST2020

Investigation along value chain using MOP



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Temperature loading	Yes	Yes	Yes
Bending because PCB is fixed to housing	No	Yes	Yes
View of deformation during loading			
Top view (half model)			

> MOPs are used for studying reliability along the value chain, including the RF material design space



Reliability Analysis based on MOP

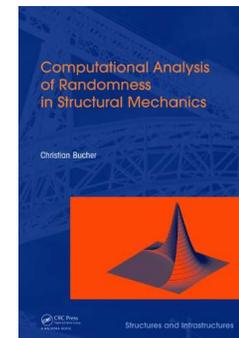
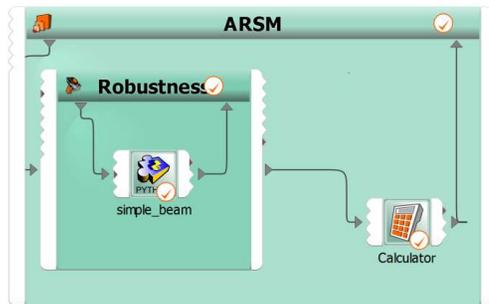
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Stochastic Days 2020

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Reliability and the Probability of Failure

- Optimization is introduced into virtual prototyping for more than 20 years
- Robustness evaluation and reliability analysis are key methodologies for safe, reliable and robust products
- The combination leads to robust design optimization (RDO) strategies



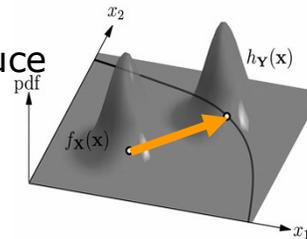
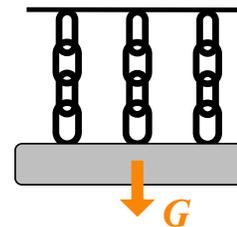
- The complementary of reliability is the probability of failure. This can be computed taking into account the scattering, variations of the input.
- Applications for example in ADAS, Microelectronics, ...:
 - Driving Scenarios
 - Solder Joint Fatigue

Probability of Failure Calculations in Microelectronics

- The complementary of *Reliability* is the *Probability of Failure*
- This can be computed for different failure mechanism, like
 - Solder Joint Fatigue (e.g. solder balls)
 - Delamination
 - Interconnect failure (e.g. wire lift-off inside package)
- Total Probability of Failure of the system depends on redundancy, dependencies for example
 - Series system: fails if one single component fails
 - Parallel system: fails if all components fail
- Criteria need to be defined for the failure
 - This leads to limit state function(s)
 - Algorithms to detect this limit state function reduce the number of necessary simulation significantly

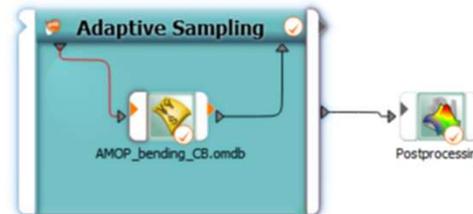
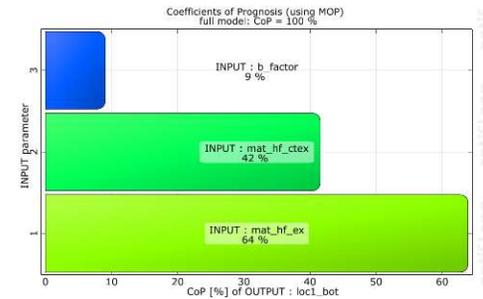
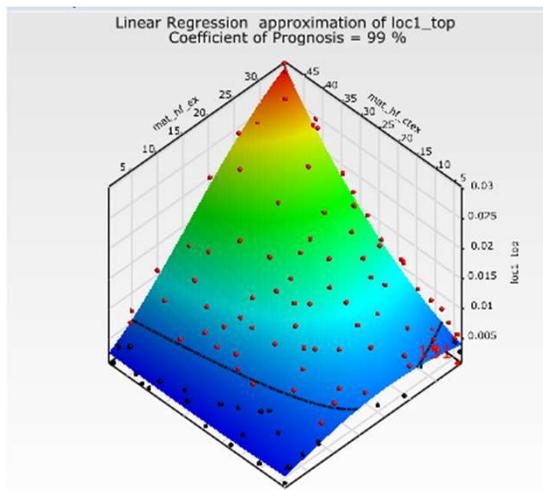


- Parallel system: fails if all components fail



Metamodel of Optimal Prognosis (MOP)

- Selection of the **important variables** by sensitivity indices
- Determination of **best surrogate model** without overfitting
- Objective measure of **prognosis quality**
- Fast **Optimization** based on MOP
- Fast **Reliability Analysis** based on MOP



MOP Surface: Case 3 with b_factor = 1.5; isoline loc1_top = 0.0055

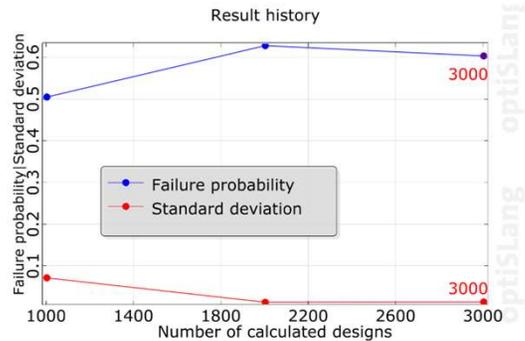
Probability of Failure at a constant damage limit level using uniform distribution across full design space

Method : Adaptive Sampling (AS)

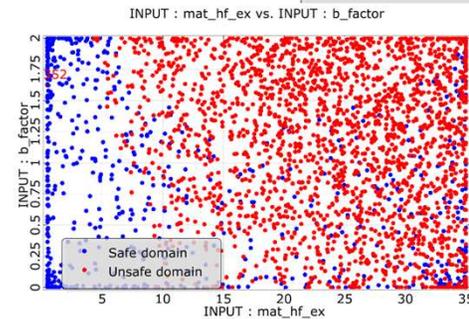
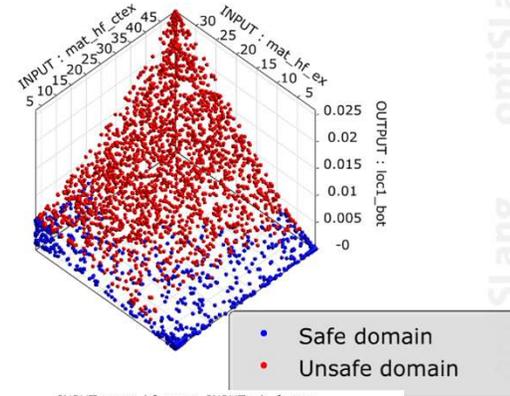
Complete iterations : 3 / 3
Selected data : All designs

Probability of Failure : 0.603392
Standard deviation error : 0.01331
Reliability Index : -0.262136

Number of designs
Total : 3000
Safe domain : 810
Unsafe domain : 2190
Failure strings : 0
Failed : 0



INPUT : mat_hf_ctex vs. INPUT : mat_hf_ex vs. OUTPUT : loc1_bot



Limit State Function defined by $loc1_top < 0.0055$

Reliability Algorithm: Adaptive Sampling

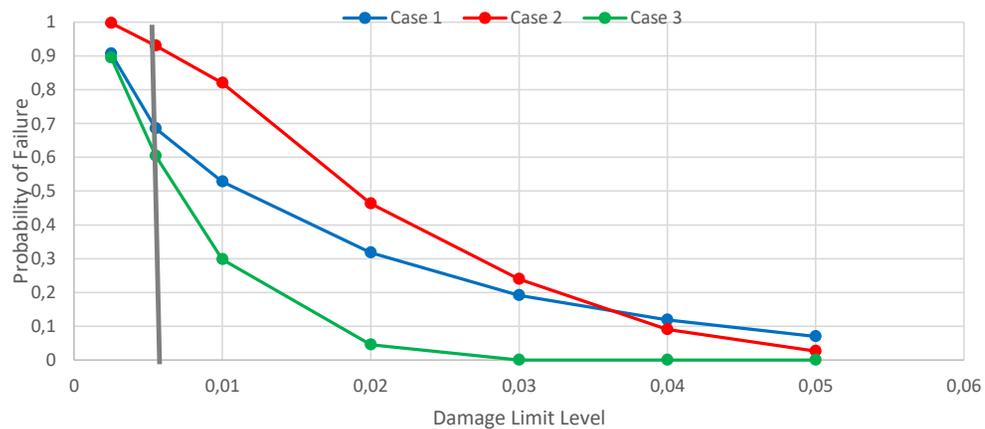
Probability of Failure for whole design space with uniform distribution Case 1: 0,69; Case 2: 0,95; Case 3: 0,60
for Case 3 displayed: Reliability Information, Cloud plot, Result History and Anthill Plot

Probability of Failure as a function of damage limit level using uniform distribution across full design space

Adaptive Sampling

Parameter	Start designs	Nominal design	Criteria	Adaptive Sampling	Other	Result de
Name	Parameter type	Reference value	PDF	Type	Distribution parameter	
1 b_factor	Stochastic	1		UNIFORM	0; 2	
2 mat_hf_ctex	Stochastic	26.5		UNIFORM	3; 50	
3 mat_hf_ex	Stochastic	17.75		UNIFORM	0.5; 35	

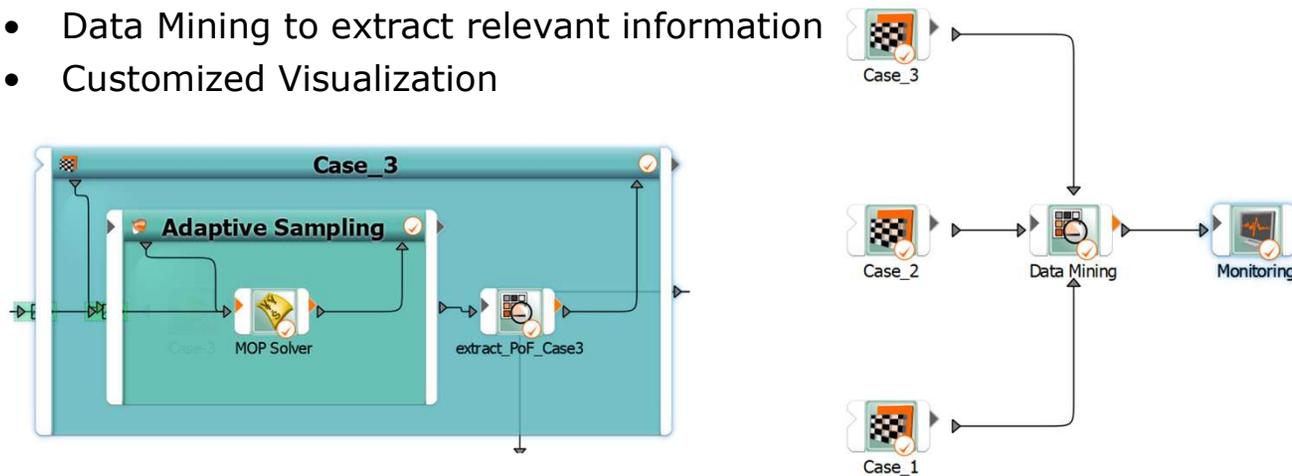
Probability of Failure as a function of Damage Limit Level



Higher damages are much more probable in Case 2 than in Case 3

Automated Workflows for Reliability Analyses

- Using Reliability Methods Integrated in Workflows
- Loop over threshold values to calculate Probability of Failure curves
- Branches for different cases
- Data Mining to extract relevant information
- Customized Visualization

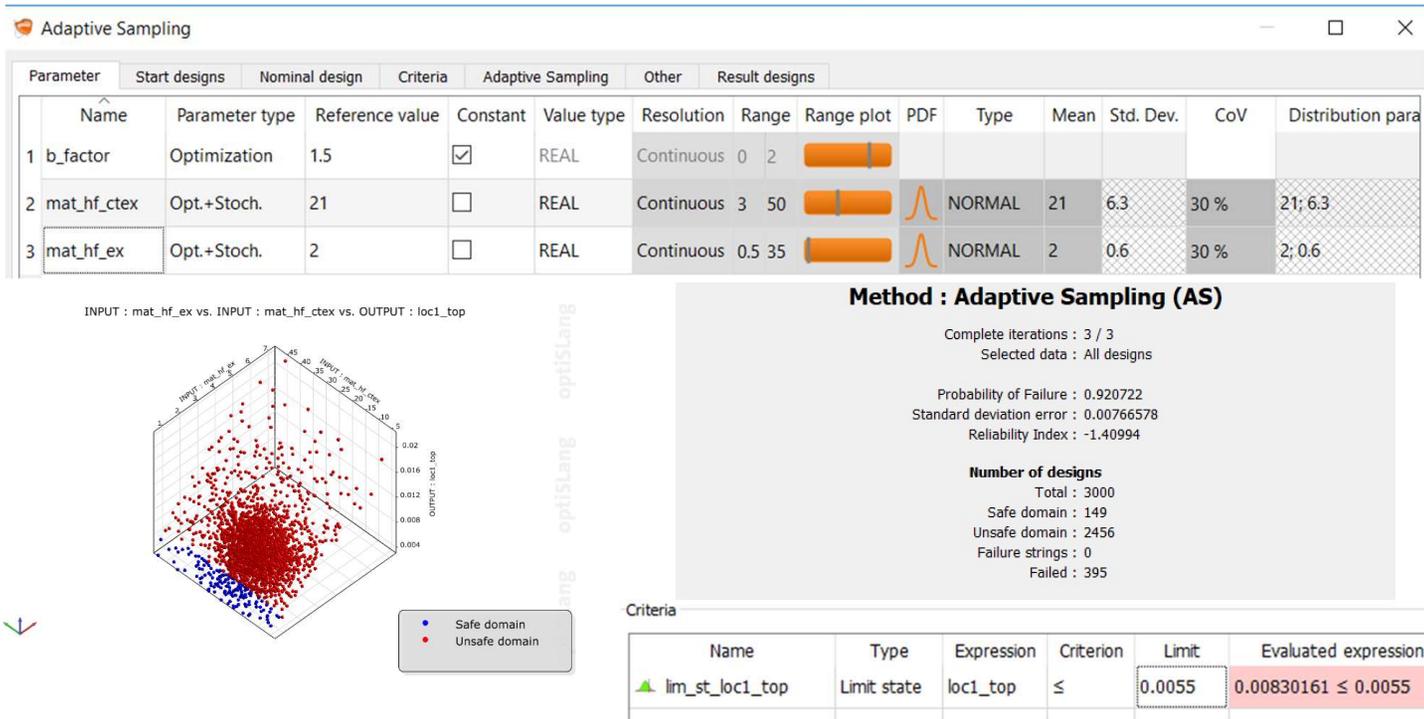


Case_3 - Sensitivity

Parameter	Start designs	Criteria	Dynamic sampling	Other	Result designs					
Name	Parameter type	Reference value	Constant	Value type	Resolution	Range	Range plot	PDF	Type	Distribution p
1 criteria_limit_state	Optimization	0.003	<input type="checkbox"/>	REAL	Discrete by value	0.00...				
2 b_factor	Stochastic	1	<input type="checkbox"/>	REAL	Continuous				UNIFORM	0; 2

Specific Design Point with a Probability Distribution

- Walking on the unsafe side, Case 2



Assuming the b_factor of 1.5 in Case 2 we have a design on the unsafe side

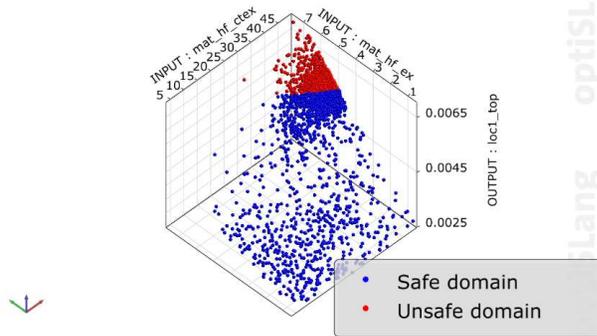
Same Design Point with same Probability Distribution

- Walking on the safe side, Case 3

Adaptive Sampling

Parameter	Start designs	Nominal design	Criteria	Adaptive Sampling	Other	Result designs							
Name	Parameter type	Reference value	Constant	Value type	Resolution	Range	Range plot	PDF	Type	Mean	Std. Dev.	CoV	Distribution parameter
1 b_factor	Optimization	1.5	<input checked="" type="checkbox"/>	REAL	Continuous	0 2							
2 mat_hf_ctex	Opt.+Stoch.	21	<input type="checkbox"/>	REAL	Continuous	3 50			NORMAL	21	6.3	30 %	21; 6.3
3 mat_hf_ex	Opt.+Stoch.	2	<input type="checkbox"/>	REAL	Continuous	0.5 35			NORMAL	2	0.6	30 %	2; 0.6

INPUT : mat_hf_ctex vs. INPUT : mat_hf_ex vs. OUTPUT : loc1_top



Method : Adaptive Sampling (AS)

Complete iterations : 3 / 3
Selected data : All designs

Probability of Failure : 1.65916e-12
Standard deviation error : 1.36946e-13
Reliability Index : 6.96354

Number of designs
Total : 3000
Safe domain : 1443
Unsafe domain : 644
Failure strings : 0
Failed : 913

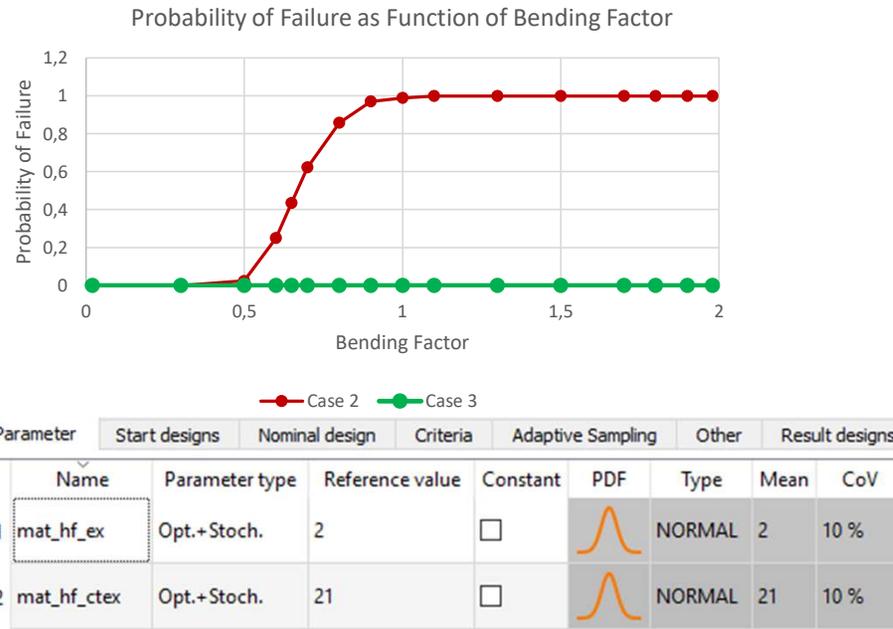
Criteria

Name	Type	Expression	Criterion	Limit	Evaluated expression
lim_st_loc1_top	Limit state	loc1_top	≤	0.0055	0.00298585 ≤ 0.0055

Algorithm using MOP detects with only 3000 runs very low probability of failure: $1.7 \cdot 10^{-1}$

Examples of Fragility Curves:

Studying the Probability of Failure in dependence of important parameters for a specific design



Specific design with mean E, CTE const.; Gaussian distribution; CoV 10%; bending factor varying from 0 to 2; limit level loc1_top = 0.0055

Conclusions and Outlook



- *Superior reliability using additional corner bonds is shown by the reliability analysis*
- *The probability of failure has been used in calculations as the complementary of reliability*
- *This analysis has been done based on MOP as an example for a possible important exchange mechanism between companies*
- *Efficient workflows are developed using the MOP that can be used for simulation runs to calculate probability of failures based directly from simulation runs (i.e. detailed analysis for transition regions, verification)*
- *Fragility Curves are useful to understand the design behavior*

*Future possible research include extension of Fragility Curves to several dimensions:
Metamodels of Probabilities of Failures*

*High quality Metamodels of Probabilities of Failures can be an essential component for
Digital Twins*



Thanks !

