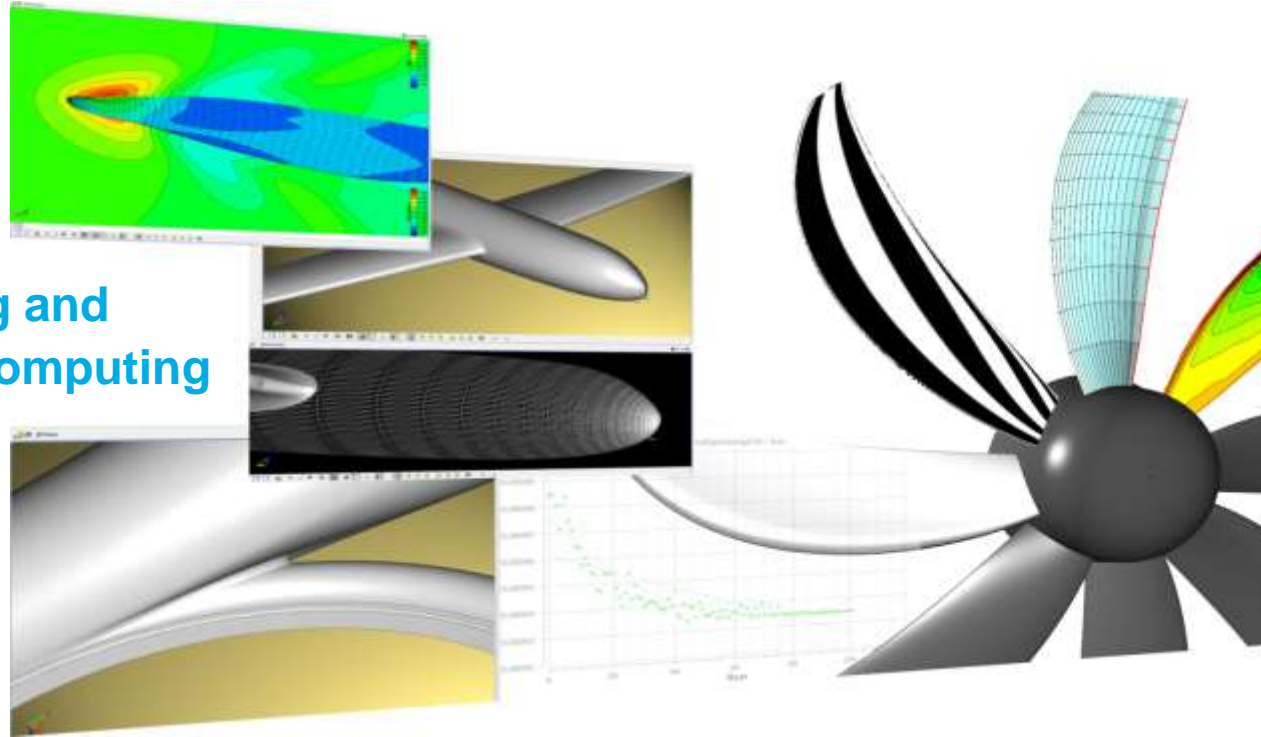


Robust Ship Design Optimization using Multidisciplinary Optimization and Stochastic Analysis.

Dirk Roos
Institute of Modelling and
High-Performance Computing

**Stefan Harries &
Jörg Palluch**
Friendship Systems

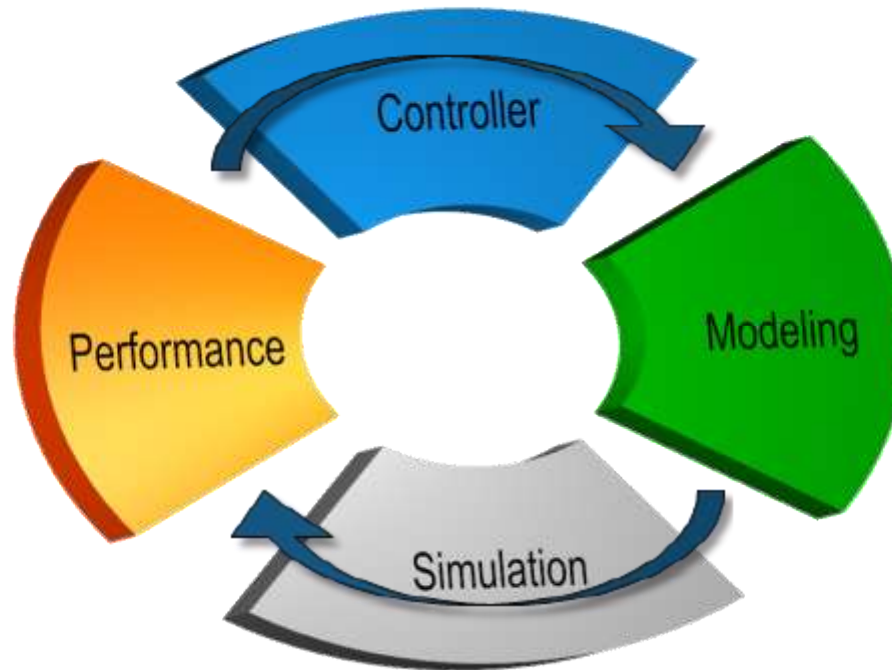
12/5/2012



Simulation-driven design

Approach

Utilize simulation, in particular Computational Fluid Dynamics (CFD), to get optimal shapes



Simulation-driven design of functional surfaces

Typical bottlenecks

CFD is resource intensive and shapes need to be of high quality

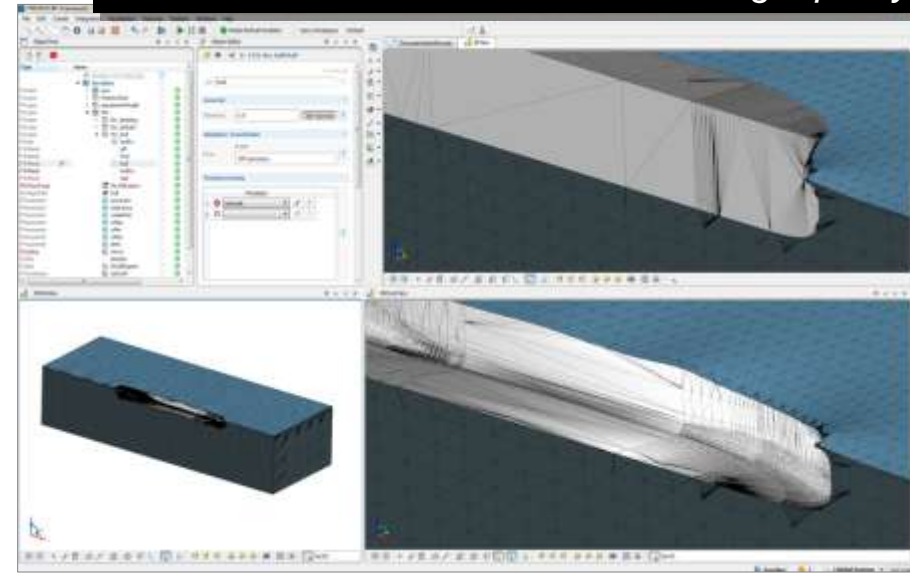
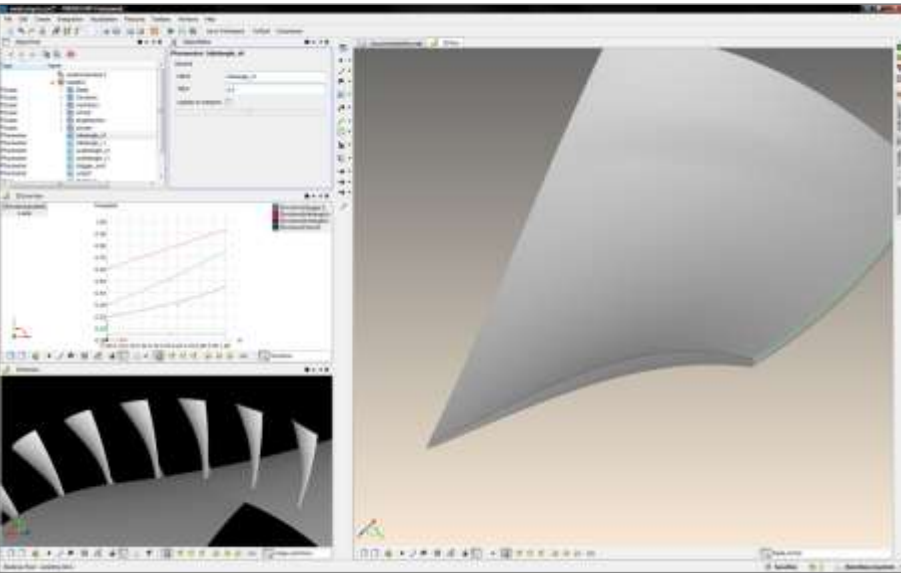
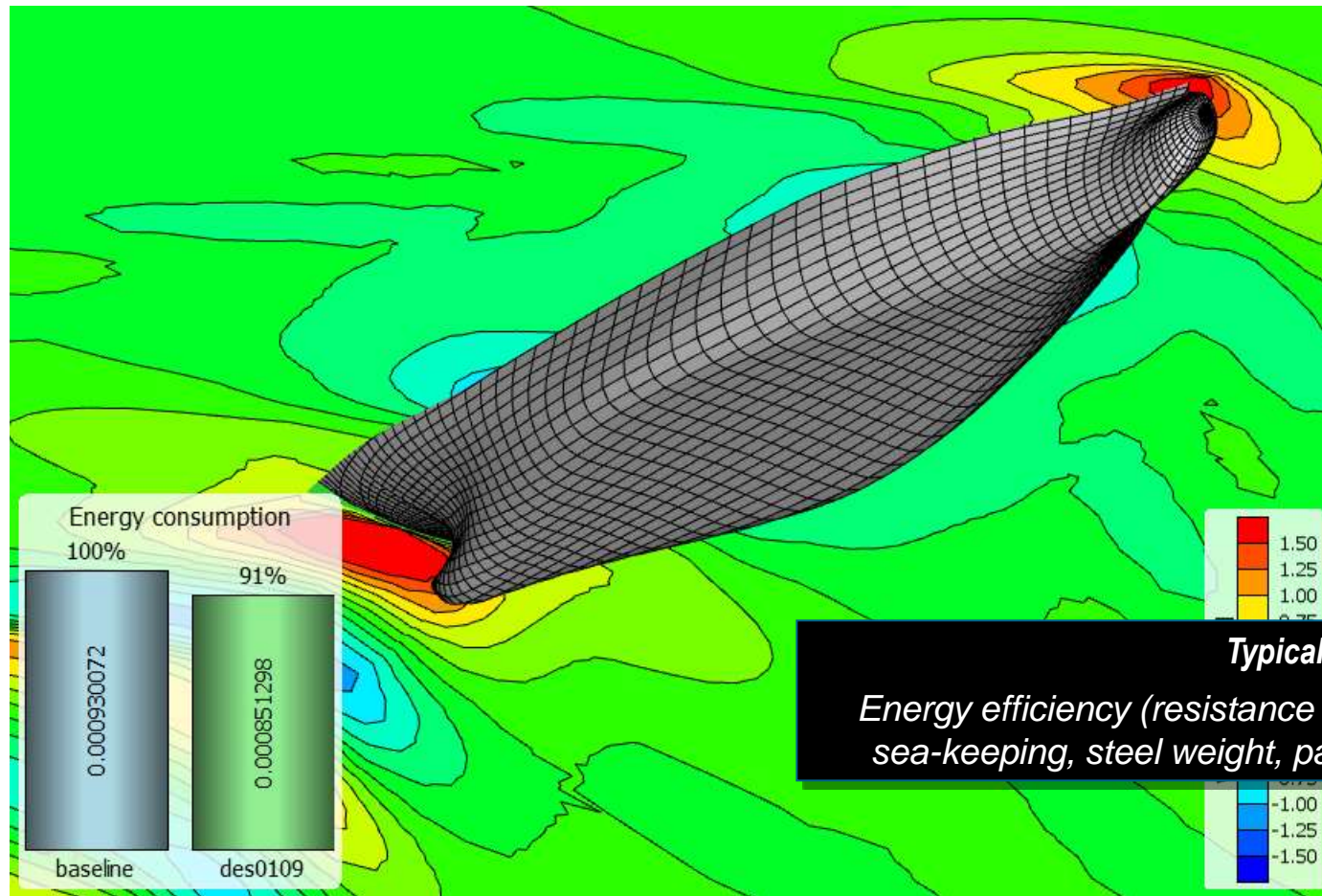


Illustration from ship design



Hull form development

DSME



***Typical performance improvements even for
good initial designs: 5%***

*Representative savings for a megaboxer of
13 000 TEU: 3 000 t of heavy fuel oil per year
= 22 222 bathtubs, i.e.,
about 1 500 000 US \$ every year*

Photo by courtesy of DSME

Typical users of the *FRIENDSHIP-Framework* (selected references)

Blohm+Voss Naval

China Ship Development and Design Center

Daewoo Shipbuilding & Marine Eng. (DSME)

FutureShip GmbH

Hamburgische Schiffbau-Versuchsanstalt
(HSVA)

Hudong Zhonghua

KSB AG

Meyer Werft

MTU Friedrichshafen

Pusan National University (PNU)

Rolls-Royce Aeroengines

Shanghai Jiao Tong University

Shanghai Merchant Ship Design and Research
Institute (SDARI)

STX Offshore & Shipbuilding

Sumitomo Heavy Industries

Sungdong Shipbuilding Marine Engineering

SVA Potsdam

Technische Universität Hamburg-Harburg

Universidade de Sao Paulo (USP)

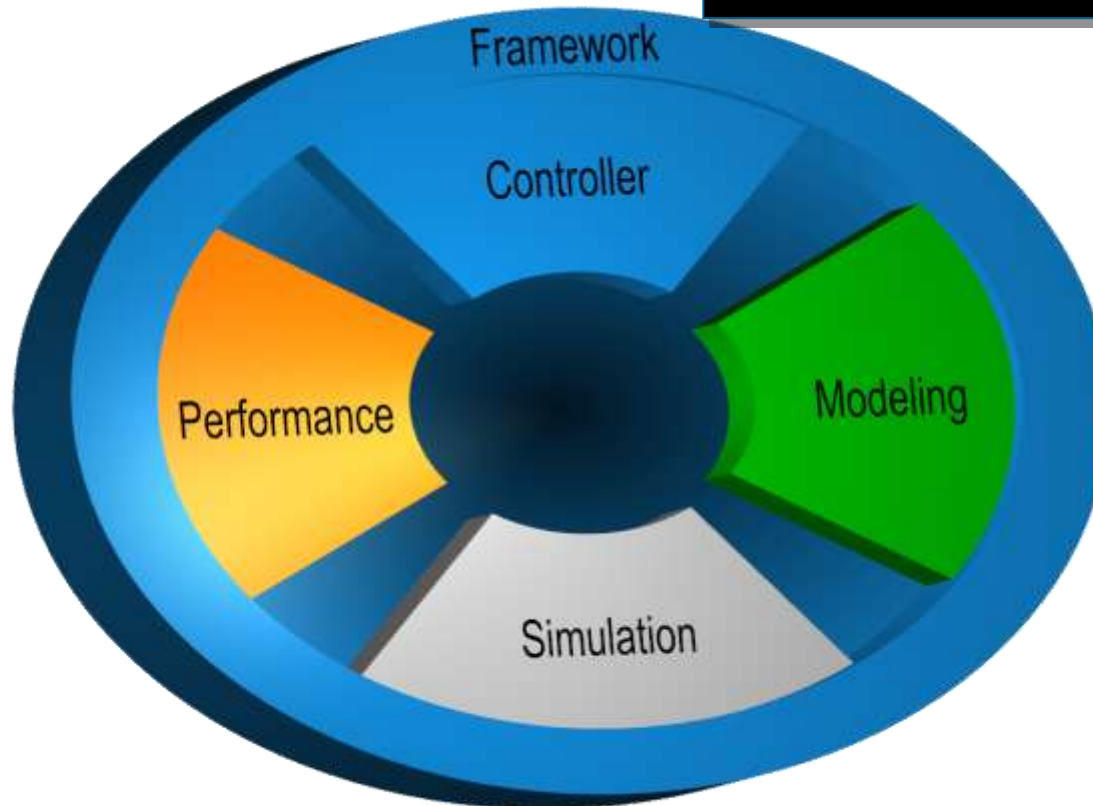
Voith Turbo Schneider Propulsion



The *FRIENDSHIP*-Framework

Modes of operation

Use in batch mode as geometric engine or as complete CAE environment with full process control



The *FRIENDSHIP*-Framework

Computer Aided Engineering and integration platform for

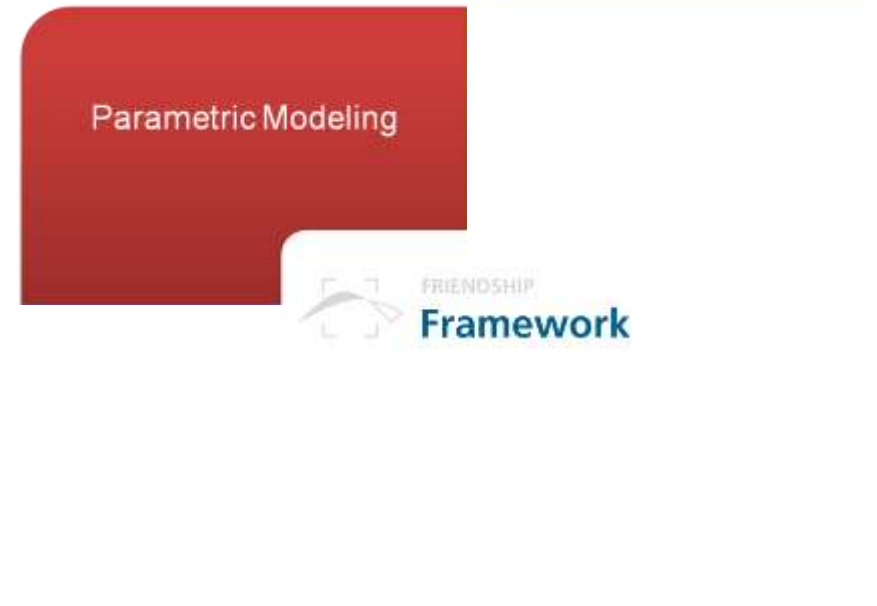
Design studies

Formal optimization

Focus on geometric modeling of functional surfaces

Complex geometries with
internal and external flows

In particular, free-form surfaces
that are challenging to
parameterize



User defined parametrics

Fully parametric modeling

Complete geometry and all
changes are defined
parametrically

Partially parametric modeling

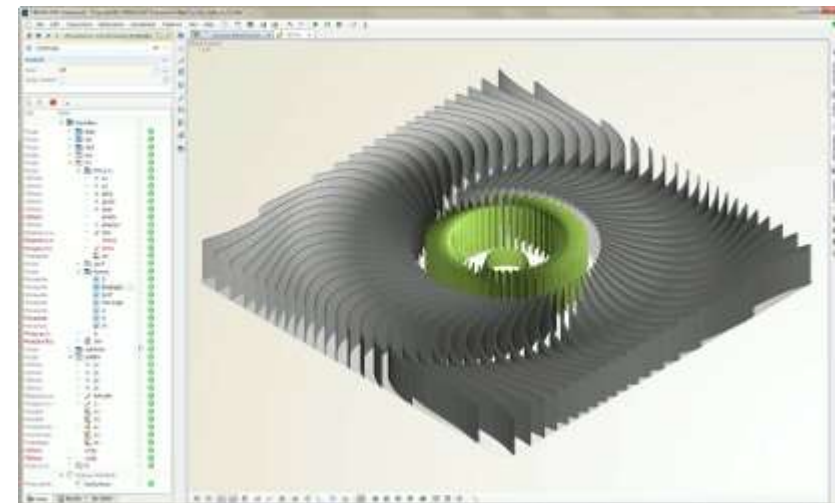
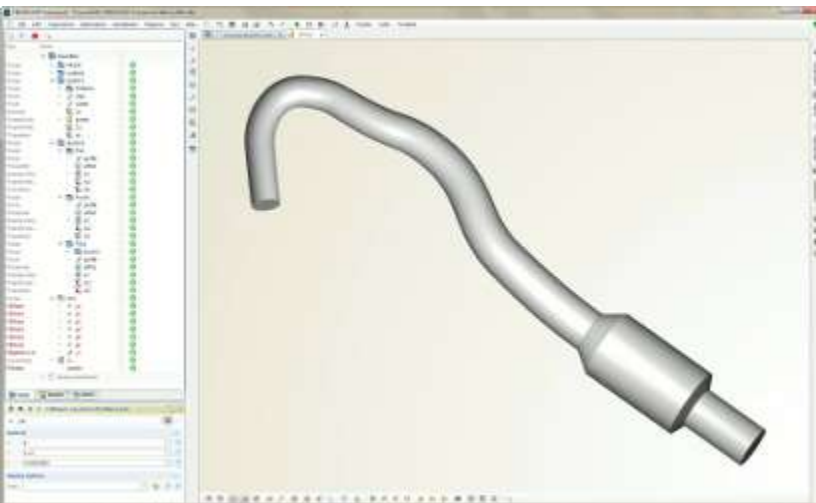
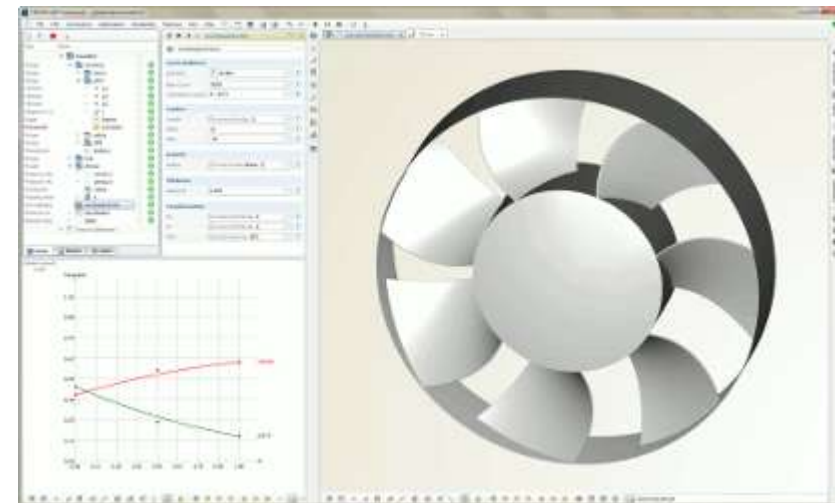
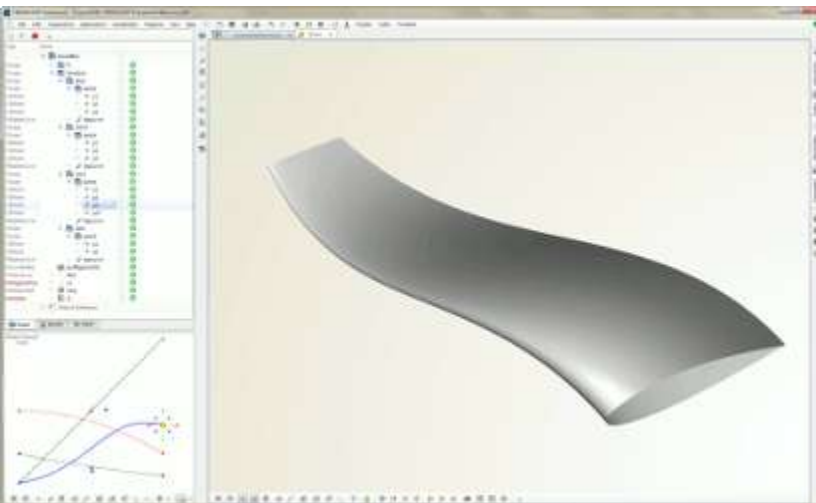
Given geometry
Changes are realized parametrically
Applicable to all shapes



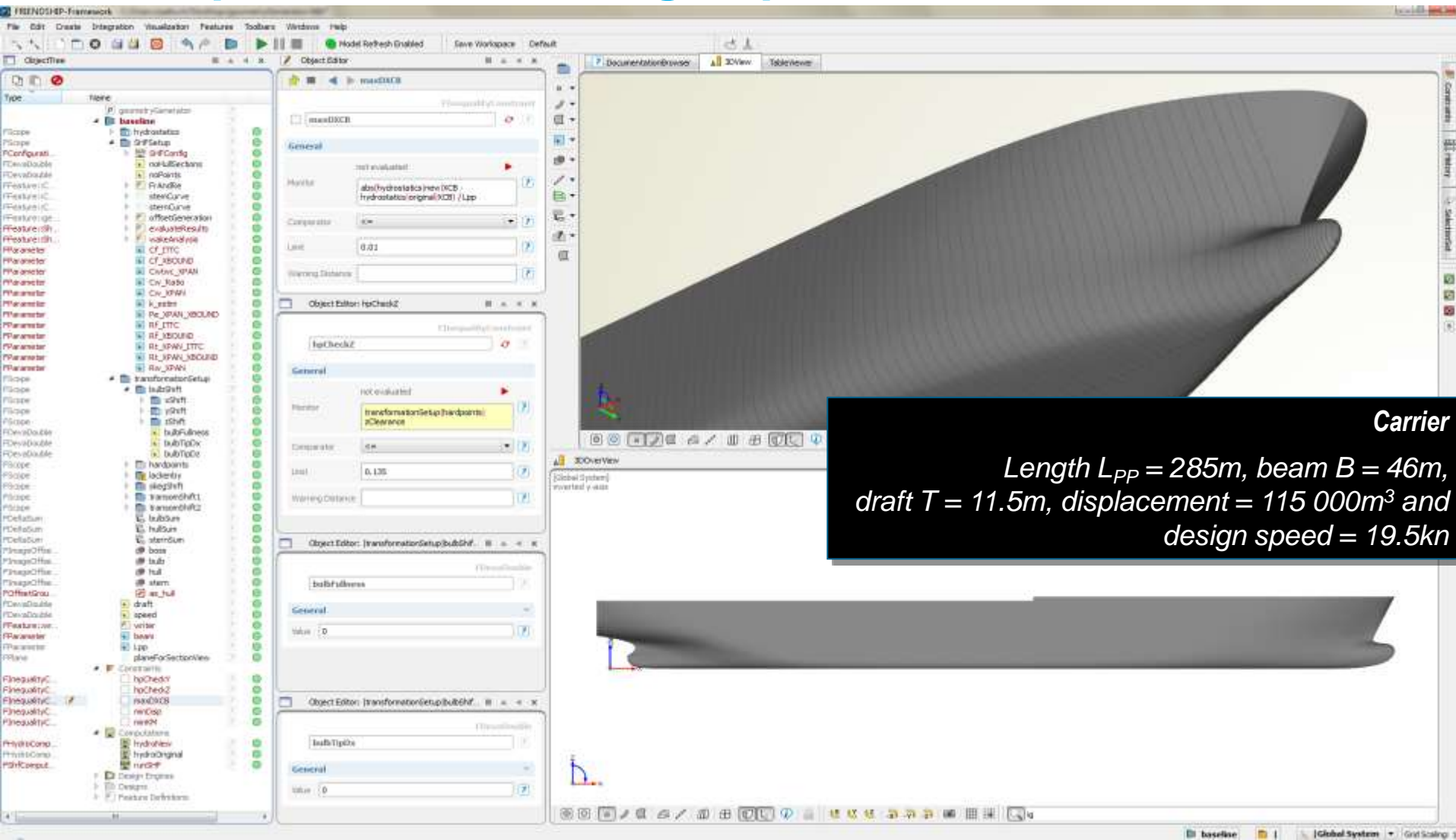
Modeling within the FRIENDSHIP-Framework

*Users define their own high level objects,
exported shapes are always named the same*

Parameterize and model functional surfaces



Example for robust design optimization



Input Parameters | Bulb

bulbFullness

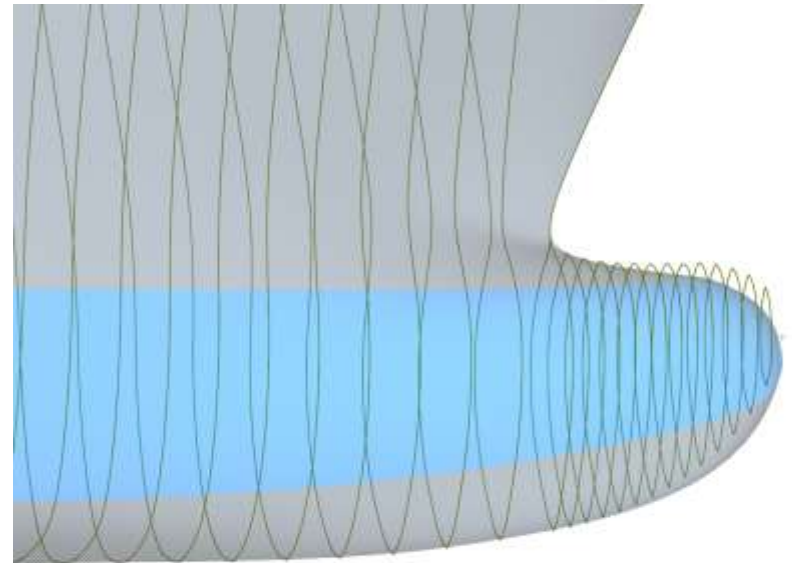
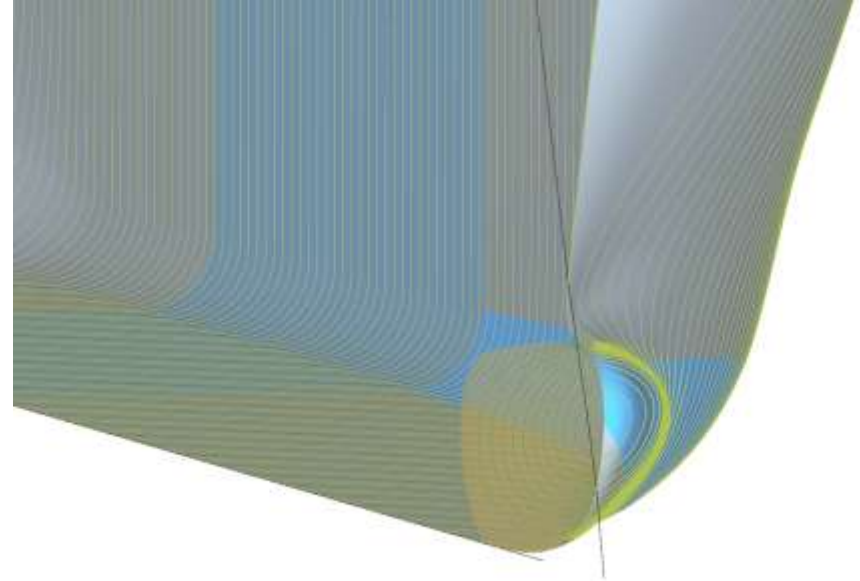
Controls the volume in the bulb

bulbTipDx

Longitudinal position of the bulb tip

bulbTipDz

Vertical position of the bulb tip



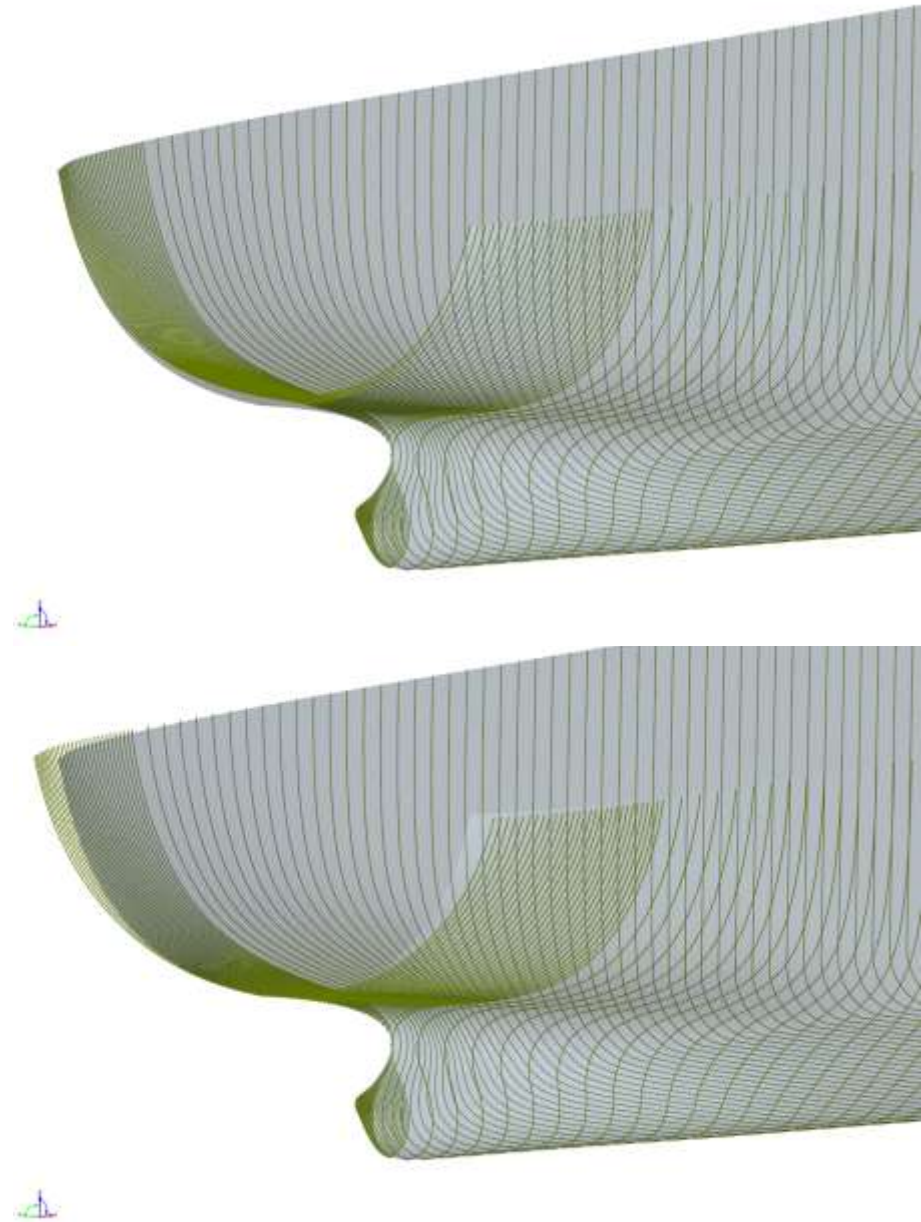
Input Parameters | Transom

transomDz

Vertical shift of the lower edge

transomDy

Width of the transom



Input Parameters | Global Displacement Shift

deltaCP

Change of the prismatic coefficient, allows smoothly increasing or decreasing the hull's displacement

deltaXCB

Controls the change of the longitudinal position of the hull's center of buoyancy

midTan

Controls the middle tangent of the displacement shift function

lackenbyXMid

Controls the longitudinal mid position of the displacement shift function (related to midTan)



Input Parameters | Skeg

dyLowMax

Maximum extension of the lower
skeg transformation

dyUppMax

Maximum extension of the upper
skeg transformation

xDyLowMax

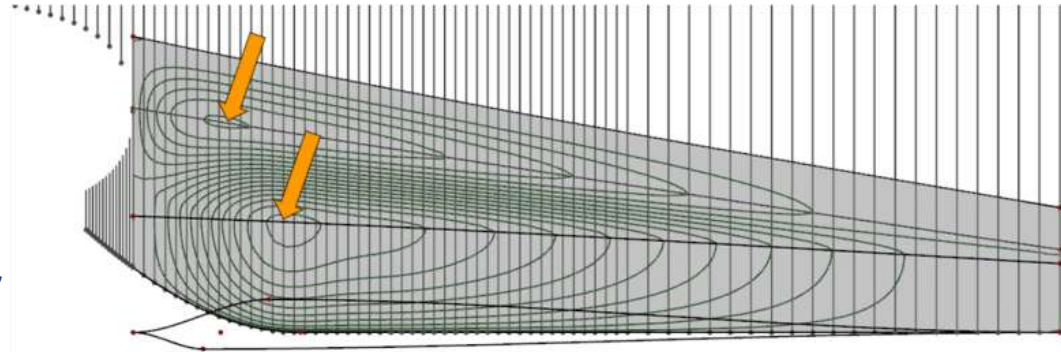
Longitudinal position of the lower
maximum extension

xDyUppMax

Longitudinal position of the upper
maximum extension

dvXFwd

End position of the skeg shift



Output Parameters | Objectives

CWTWC

Wave resistance coefficient from
transverse wave cut,
initial design: 0.227 E-03

CW

Wave resistance coefficient from
pressure integration,
initial design: 0.862 E-03

CF

Frictional resistance coefficient,
initial design: 1.439 E-03

CFD system used here: SHIPFLOW

*Integrations exist to STAR-CCM+, FINE/Turbo,
OpenFOAM, ICON FOAM Pro, CFX etc.*

Output Parameters | Constraints

hpCheckY

Hard point's check in y-direction

hpCheckZ

Hard point's check in z-direction

maxDXCB

Maximum percental change allowed
for longitudinal position of the
hull's center of buoyancy

minDISP

Minimum displacement for
modified hull shape

minKM

Minimum stability value for
modified hull shape

Parametric model

*Takes care of further constraints implicitly,
e.g. operational and production aspects*

Output Parameters | Objective function

$$p(f_i(x_1, x_2, \dots, x_{14})) = \sum_{i=1}^2 W_i \frac{f_i(\mathbf{x})}{\Gamma_i}$$

$$Rt = (1.0 \cdot CWTWC + 1.2 \cdot CF) \left(0.5 \cdot dens \left(Re \frac{visc}{Lpp} \right)^2 Sref \cdot Lpp^2 \right)$$

Sref

Wetted surface at zero speed

Dens

Water density

Visc

Water kinematic viscosity

Lpp

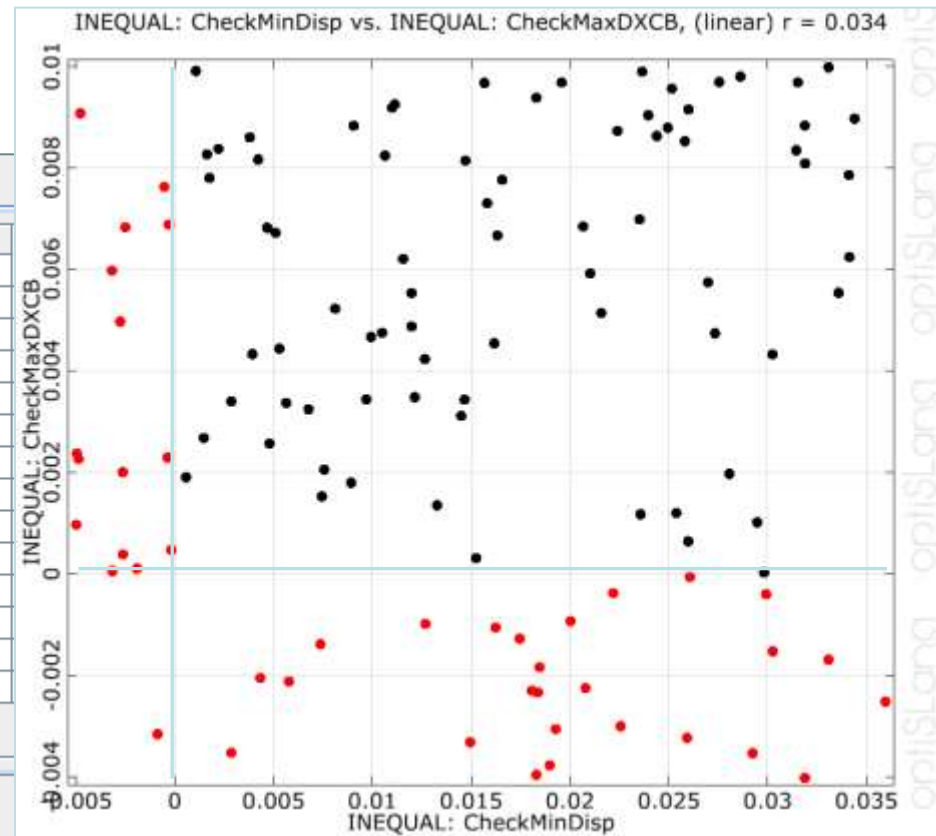
Length between perpendiculars

Re

Reynolds number

Sensitivity analysis I

Opti	Robust	Output	Strings	Constraints	Objectives
#	Name	Value	Ref.Value	Lower Bound	Upper Bound
1	bulbFullness	0.0000	0.0000	-0.5	2.5
2	bulbTipDx	0.0000	0.0000	-1.0	1.0
3	bulbTipDz	0.0000	0.0000	-1.0	1.0
4	deltaCP	0.00000000	0.00000000	-0.01	0.02
5	deltaXCB	0.00000000	0.00000000	-0.0020	0.0080
6	midTan	0.0000	0.0000	-30.0	40.0
7	lackenbyXMid	128.970	128.970	120.0	140.0
8	transomDz	0.0000	0.0000	-1.0	0.5
9	transomDy	0.0000	0.0000	-2.0	2.0
10	dyLowMax	0.0000	0.0000	-0.5	0.5
11	dyUpMax	0.0000	0.0000	-0.5	0.5
12	xDyLowMax	13.000	13.000	11.0	20.0
13	xDyUpMax	12.000	12.000	11.0	20.0
14	dvXFwd	40.000	40.000	35.0	50.0

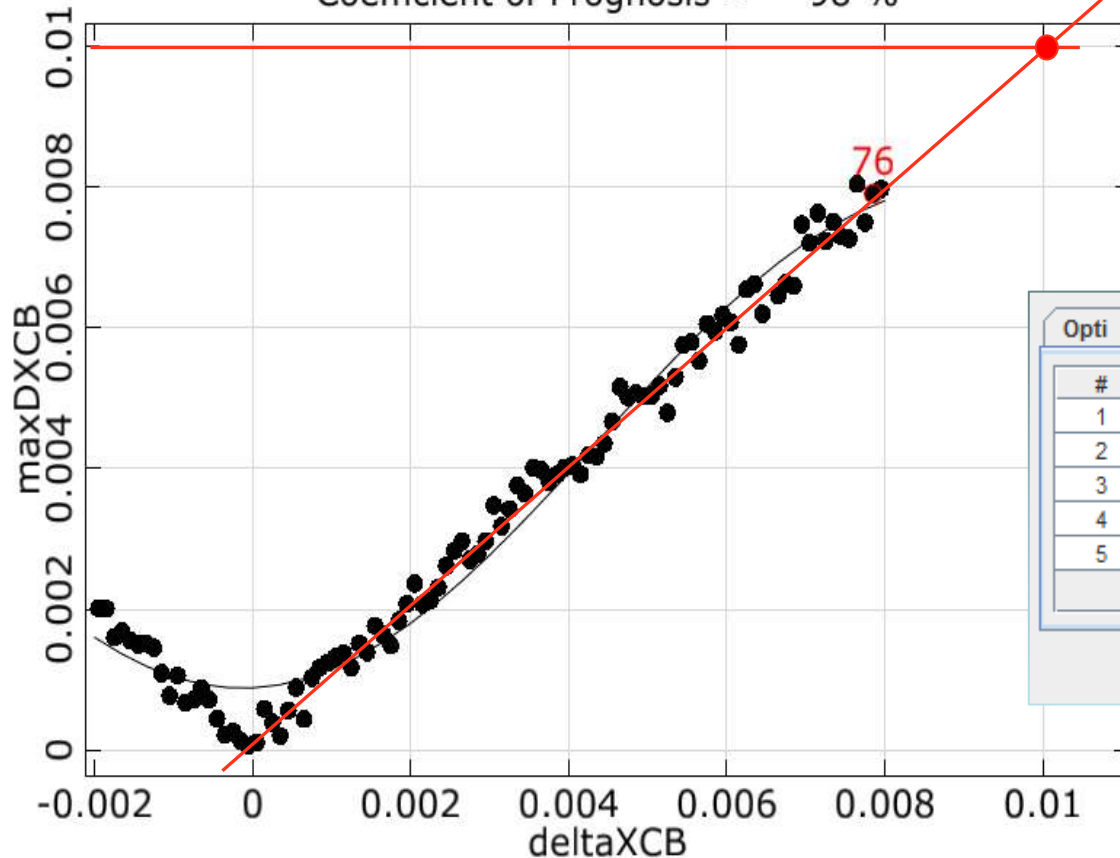


- Defined design (optimization) parameters $n_D = 14$ and responses (output)
- Given reference values
- Lower and upper bounds to define the box constraints used within optimization

Sensitivity Analysis II

- Extrapolation of the design parameters to make accessible optimization potential

Quadratic no mixed regression of maxDXCB
Coefficient of Prognosis = 98 %



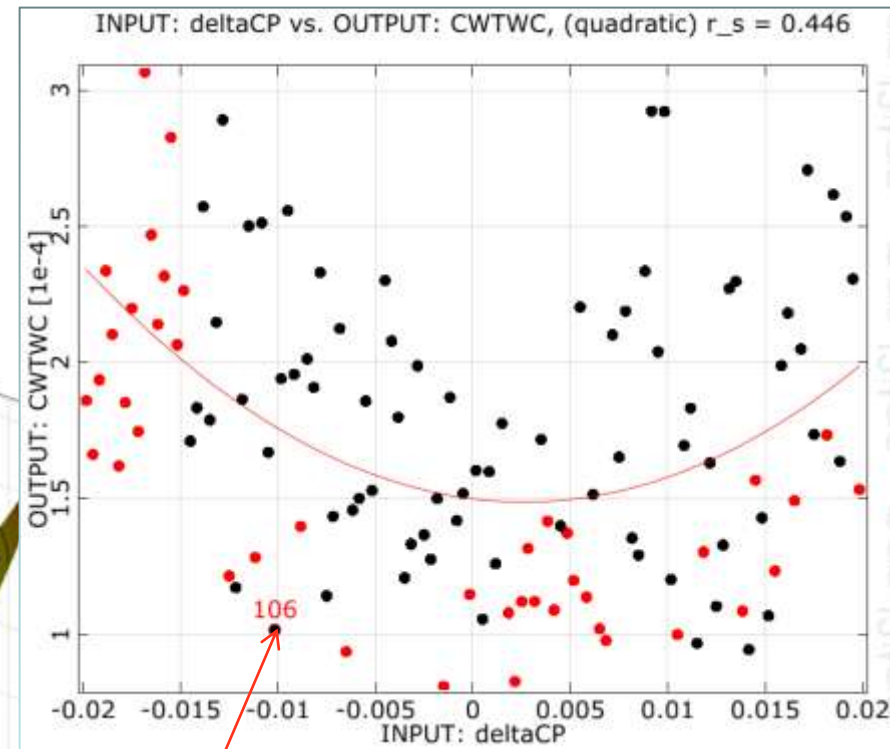
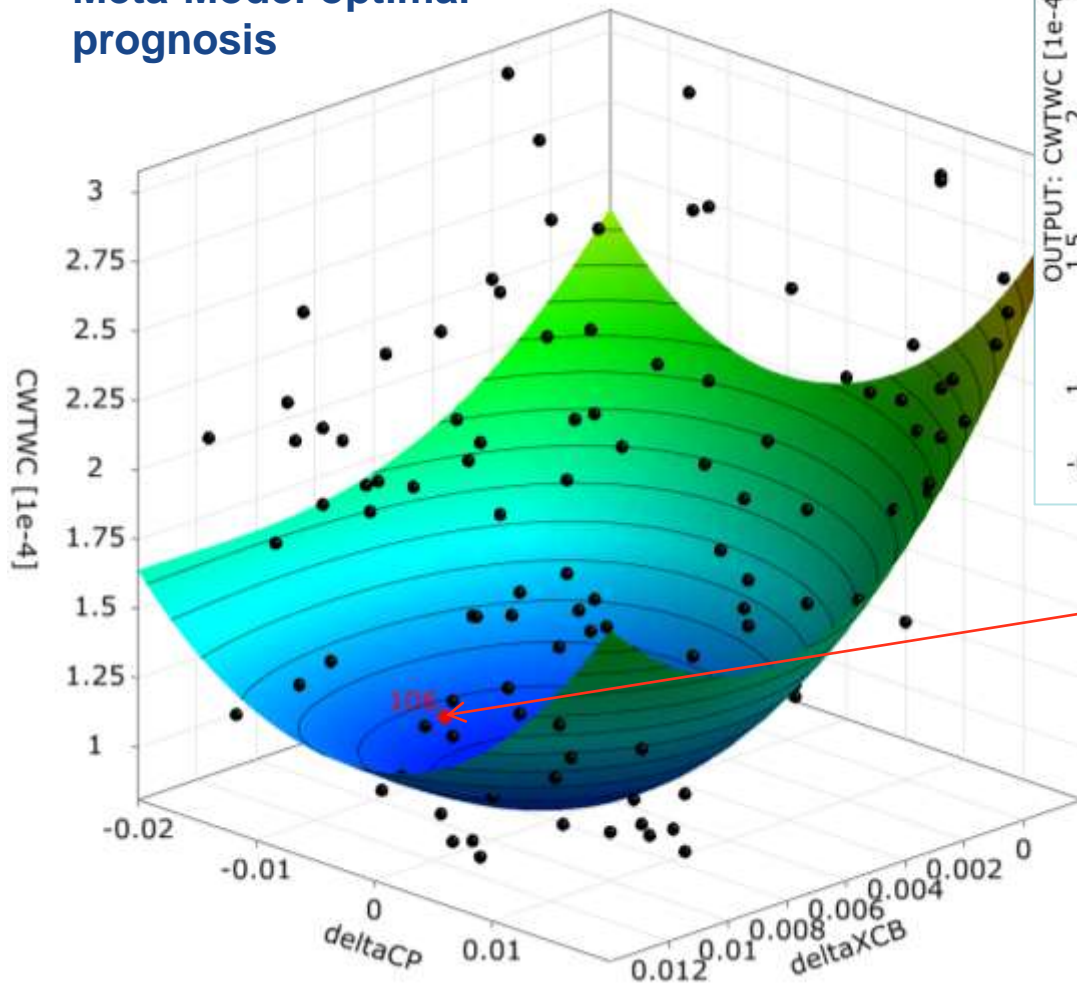
Opti	Robust	Output	Strings	Constraints	Objectives
#	Name	Type	Formula	Active	
1	CheckMinKM	inequality	minKM-0.98	<input checked="" type="checkbox"/>	
2	CheckZ	inequality	0.135-hpCheckZ	<input checked="" type="checkbox"/>	
3	CheckY	inequality	hpCheckY+0.405	<input checked="" type="checkbox"/>	
4	CheckMaxDXCB	inequality	0.01-maxDXCB	<input checked="" type="checkbox"/>	
5	CheckMinDisp	inequality	minDISP-0.985	<input checked="" type="checkbox"/>	

Cancel

OK

Response: CWTWC

Meta-Model optimal prognosis

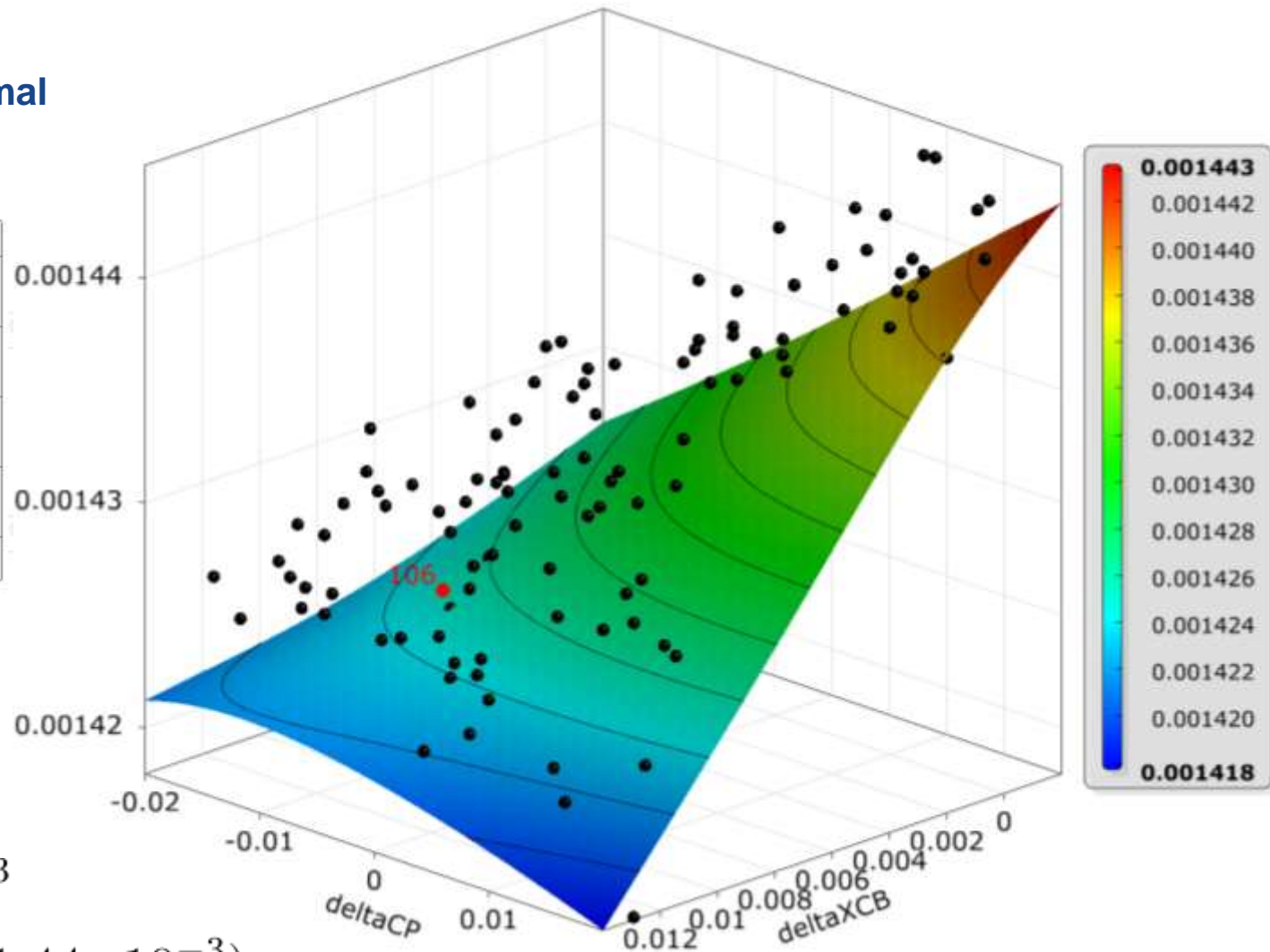
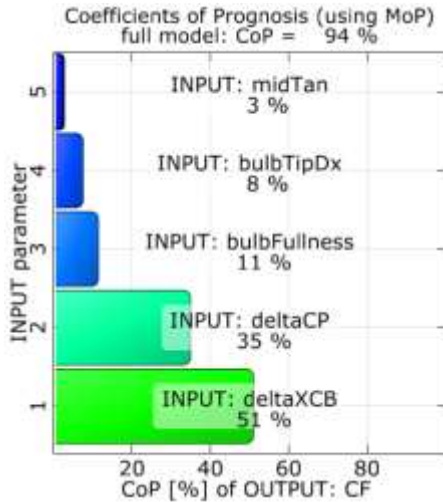


Best design within the latin hypercube sampling

$$CWTWC = 1.02 \cdot 10^{-4} \\ \rightarrow (45\% \text{ of } 2.27 \cdot 10^{-4})$$

Response: CF

Meta-Model optimal prognosis



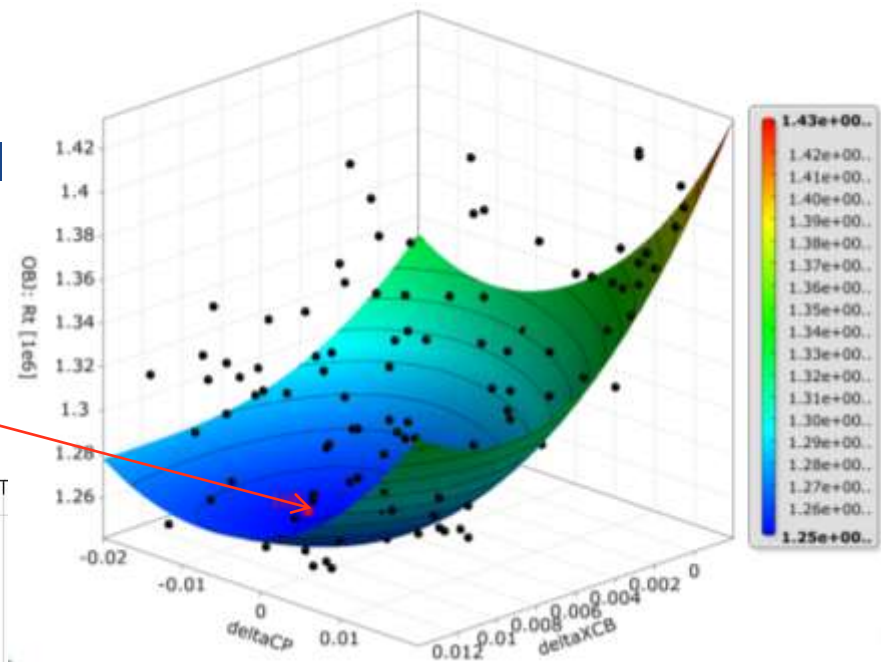
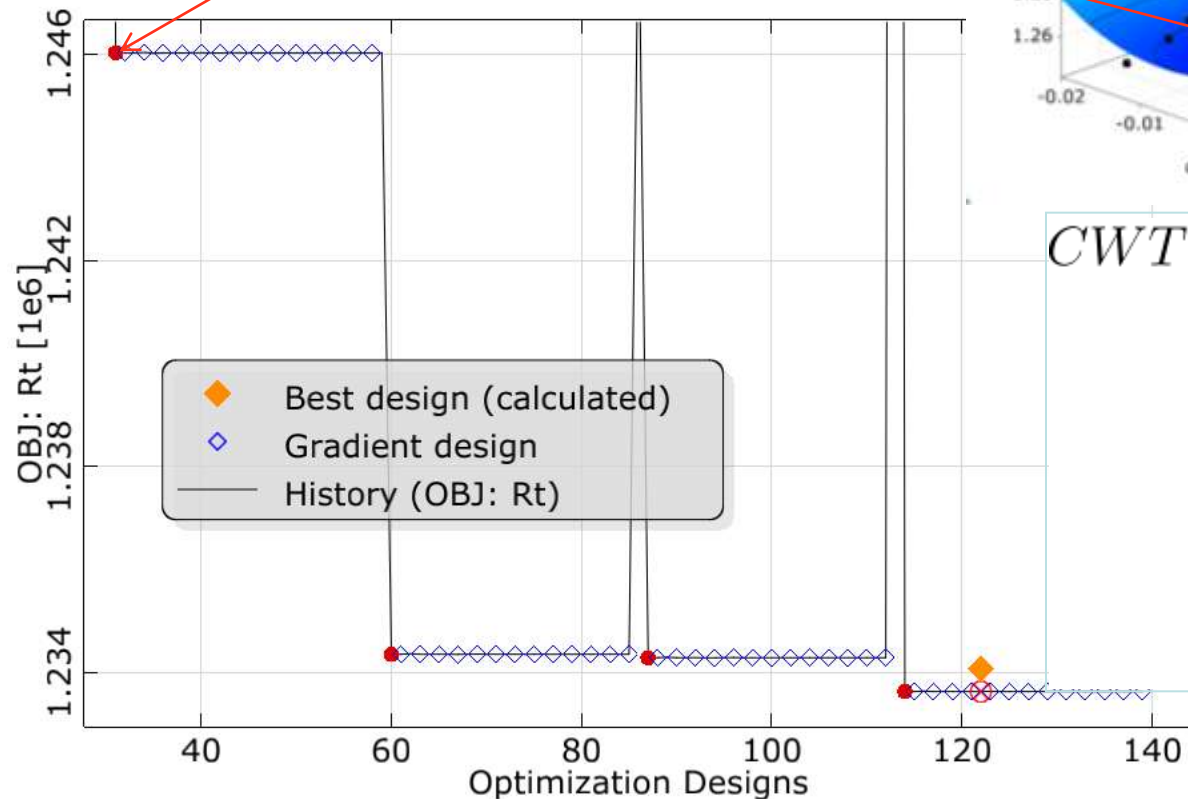
$$CF = 1.43 \cdot 10^{-3}$$
$$\rightarrow (99\% \text{ of } 1.44 \cdot 10^{-3})$$

Nonlinear Optimization

Gradient-based on surrogate model

objective $Rt = 1.246 \cdot 10^6$

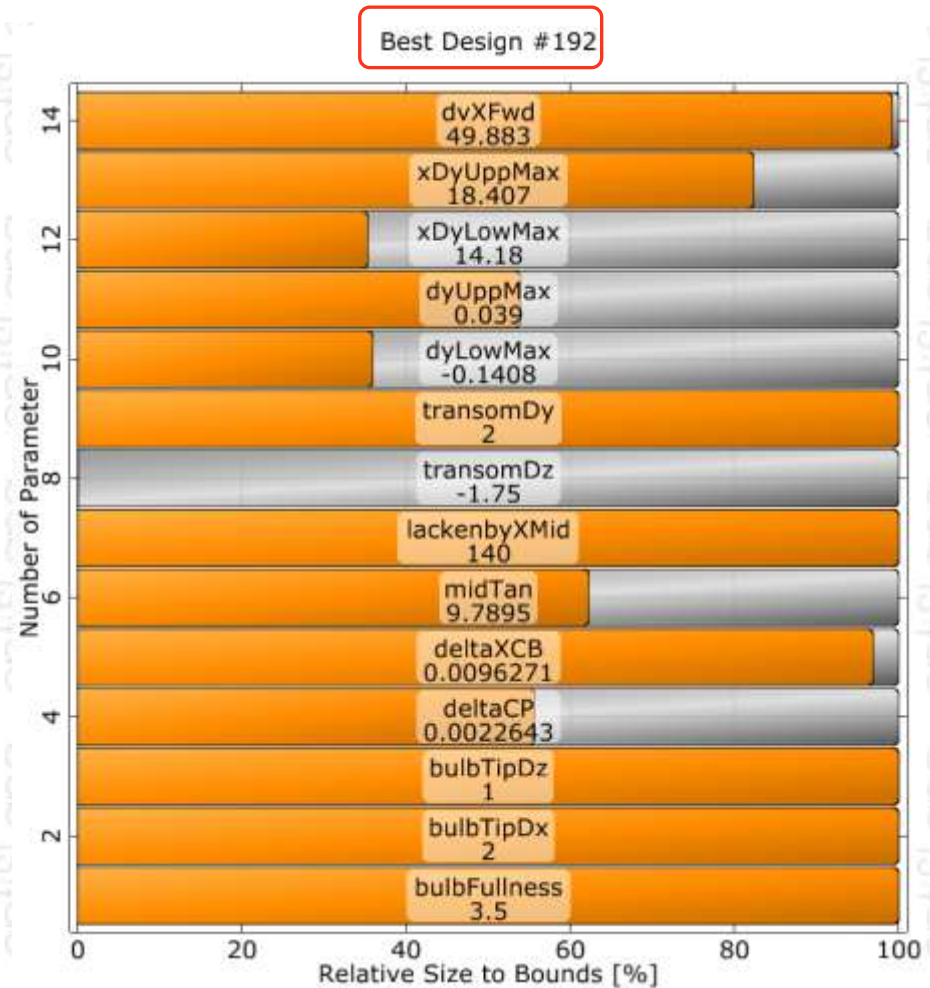
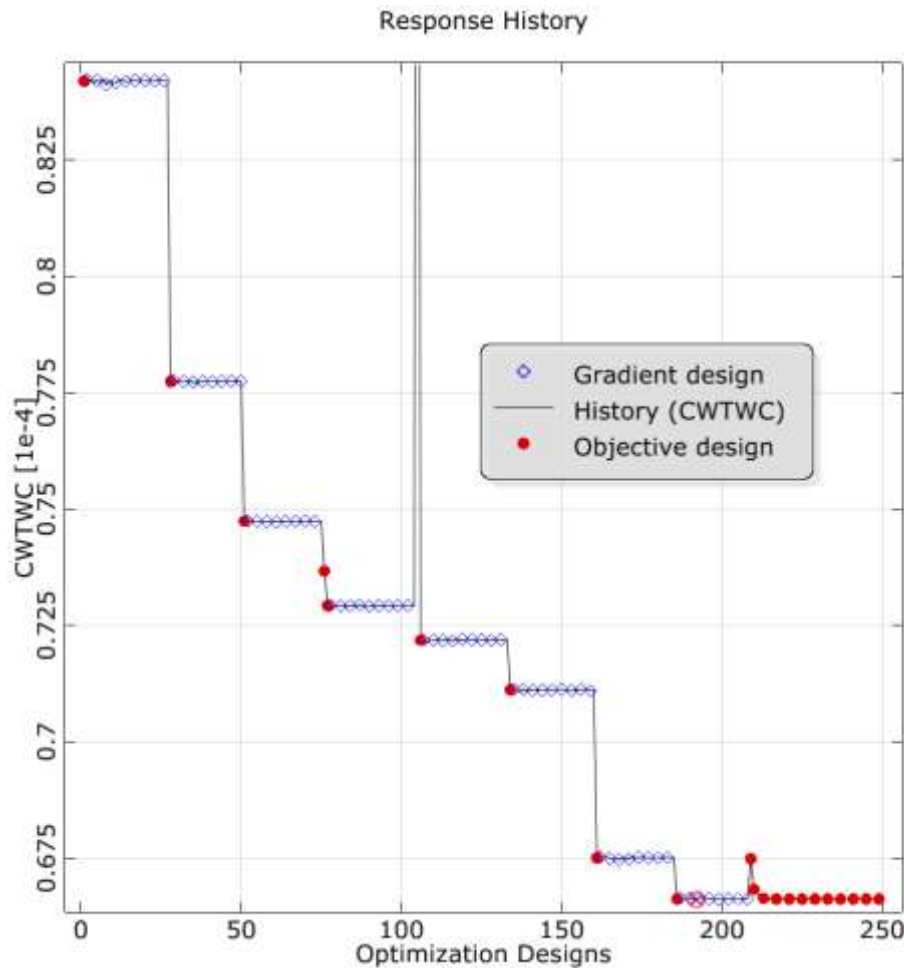
Objective Data History



$$\begin{aligned} CWTWC &= 7.64 \cdot 10^{-5} \quad (\text{MoP}) \\ &= 7.66 \cdot 10^{-5} \quad (\text{calc}) \\ &\rightarrow (34\% \text{ of } 2.27 \cdot 10^{-4}) \\ CF &= 1.42 \cdot 10^{-3} \quad (\text{MoP}) \\ &= 1.42 \cdot 10^{-3} \quad (\text{calc}) \\ &\rightarrow (98\% \text{ of } 1.44 \cdot 10^{-3}) \end{aligned}$$

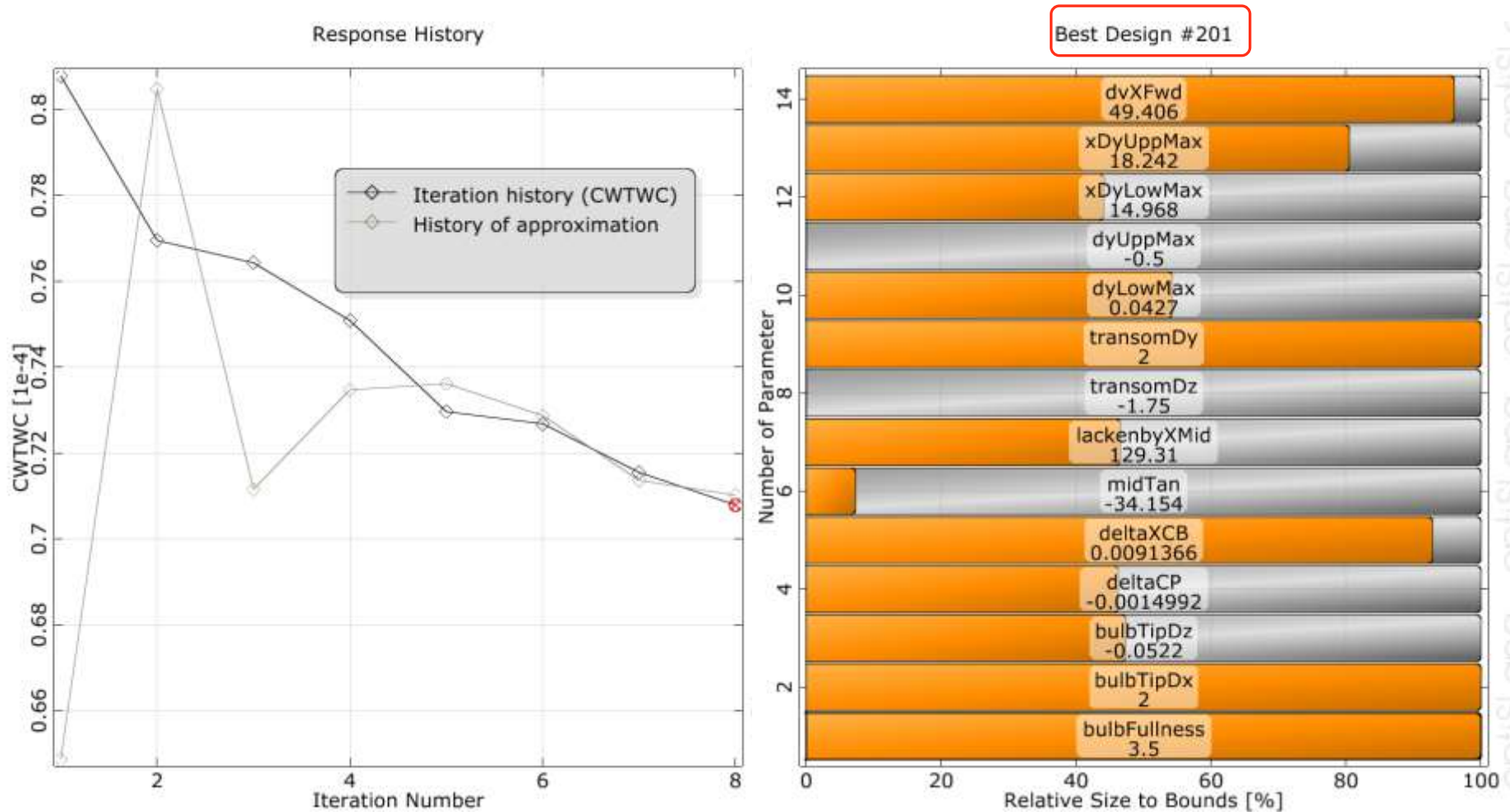
Nonlinear Optimization

Gradient-based optimization (SQP)



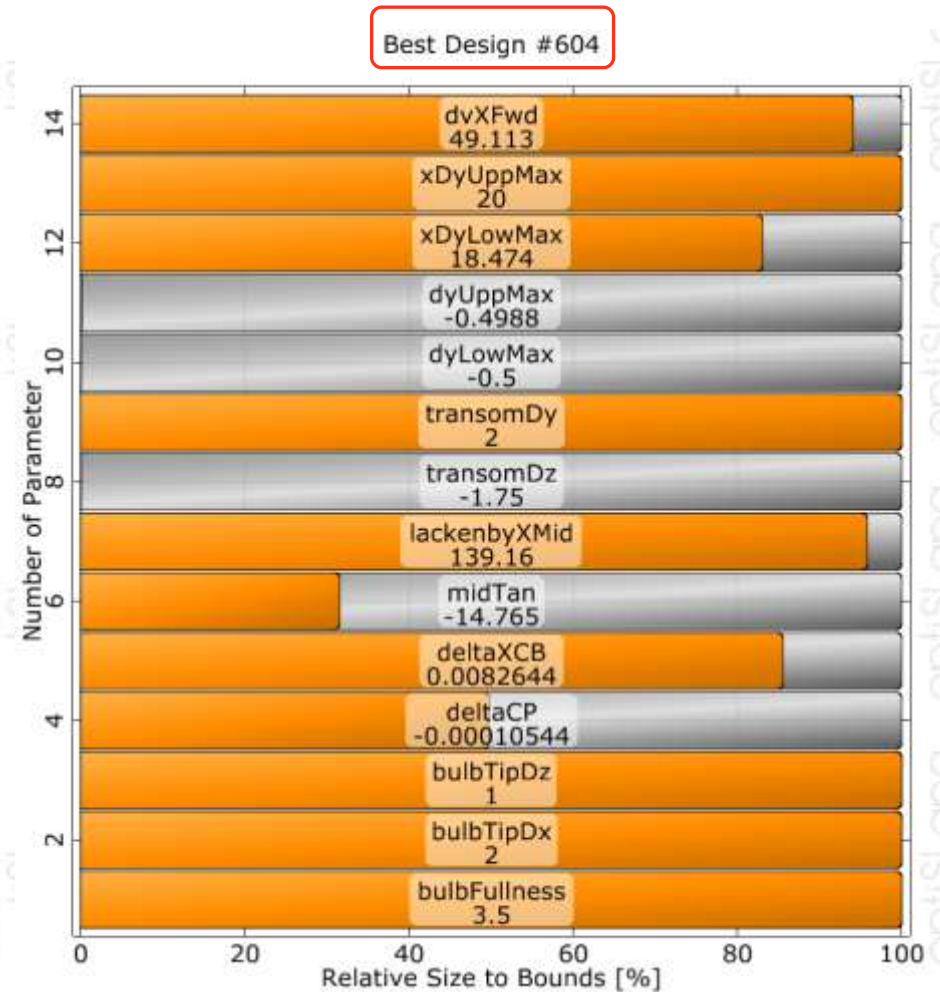
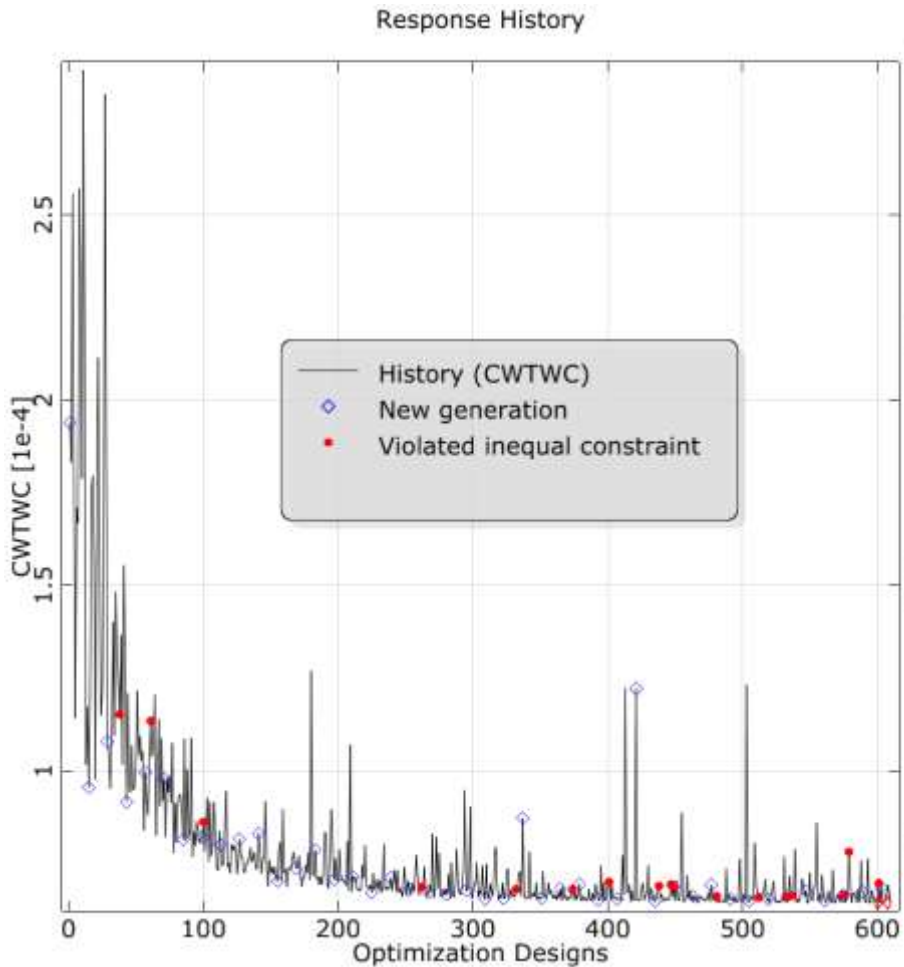
Nonlinear Optimization

Adaptive response surface (ARSM)



Nonlinear Optimization

Evolutionary algorithm



Nonlinear Optimization Summary

	Start	SA	MoP	SQP	ARSM	EA
CWTWC	$2.27 \cdot 10^{-4}$	$1.02 \cdot 10^{-4}$	$7.66 \cdot 10^{-5}$	$6.66 \cdot 10^{-5}$	$7.08 \cdot 10^{-5}$	$6.43 \cdot 10^{-5}$
	100%	45%	34%	29%	31%	28%
CF	$1.44 \cdot 10^{-3}$	$1.43 \cdot 10^{-3}$	$1.42 \cdot 10^{-3}$	$1.42 \cdot 10^{-3}$	$1.42 \cdot 10^{-3}$	$1.42 \cdot 10^{-3}$
	100%	99%	98%	98%	98%	98%
Design Evaluations	-	312	1	192	201	604
		Total:	505			

Design improvement considering uncertainties?



Robustness evaluation

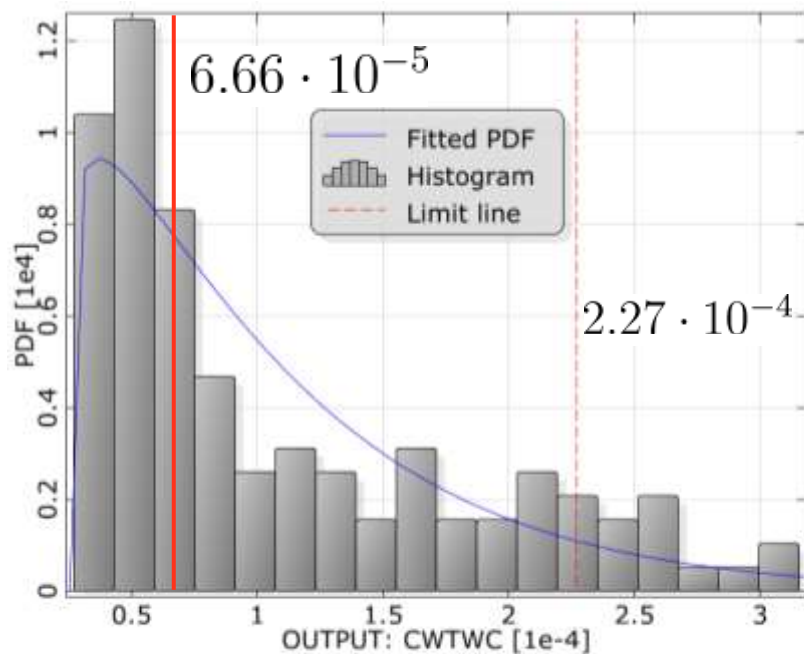
Opti	Robust	Output	Strings	Constraints	Objectives					
#	Name	Distribution	Mean	CoV	Stddev	Lower Cut	Upper...	For...	A...	C...
1	noHullSections	Normal	150.0	0.05	7.5	-	-	%3i	<input checked="" type="checkbox"/>	<input type="checkbox"/>
2	noPoints	Normal	100.0	0.05	5.0	-	-	%3i	<input checked="" type="checkbox"/>	<input type="checkbox"/>
3	bulbFullness	Normal	3.5	0.002857142857142857	0.01	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
4	bulbTipDx	Normal	2.0	0.0050	0.01	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
5	bulbTipDz	Normal	1.0	0.01	0.01	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
6	deltaCP	Normal	0.00226434	0.04416297905791533	1.0E-4	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
7	deltaXCB	Normal	0.00962715	0.01038729011181918	1.0E-4	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
8	midTan	Normal	9.7895	0.05107513151846366	0.5	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
9	lackenbyXBeg	Normal	20.0	0.1	2.0	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
10	lackenbyXMid	Normal	140.0	0.014285714285714285	2.0	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
11	lackenbyXEnd	Normal	280.0	0.007142857142857143	2.0	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
12	transomDz	Normal	-1.75	-0.005714285714285714	0.01	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
13	transomDy	Normal	2.0	0.0050	0.01	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
14	dyLowMax	Normal	-0.1408	-0.07102272727272727	0.01	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
15	dyUppMax	Normal	0.039	0.25641025641025644	0.01	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
16	xDyLowMax	Normal	14.18	0.007052186177715092	0.1	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
17	xDyUppMax	Normal	18.407	0.005432715814635737	0.1	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
18	dvXFwd	Normal	49.883	0.010023454884429565	0.5	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
19	Fn	Normal	0.18972133	0.05000000000000001	0.009486066500000...	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
20	Rn	Normal	2.599113636363636...	0.05	1.299556818181818...	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
21	density	Normal	1025.0	0.025	25.625	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
22	draft	Normal	11.5	0.05	0.5750000000000001	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>
23	trim	Normal	0.0	Infinity	0.2	-	-	%...	<input checked="" type="checkbox"/>	<input type="checkbox"/>

Cancel

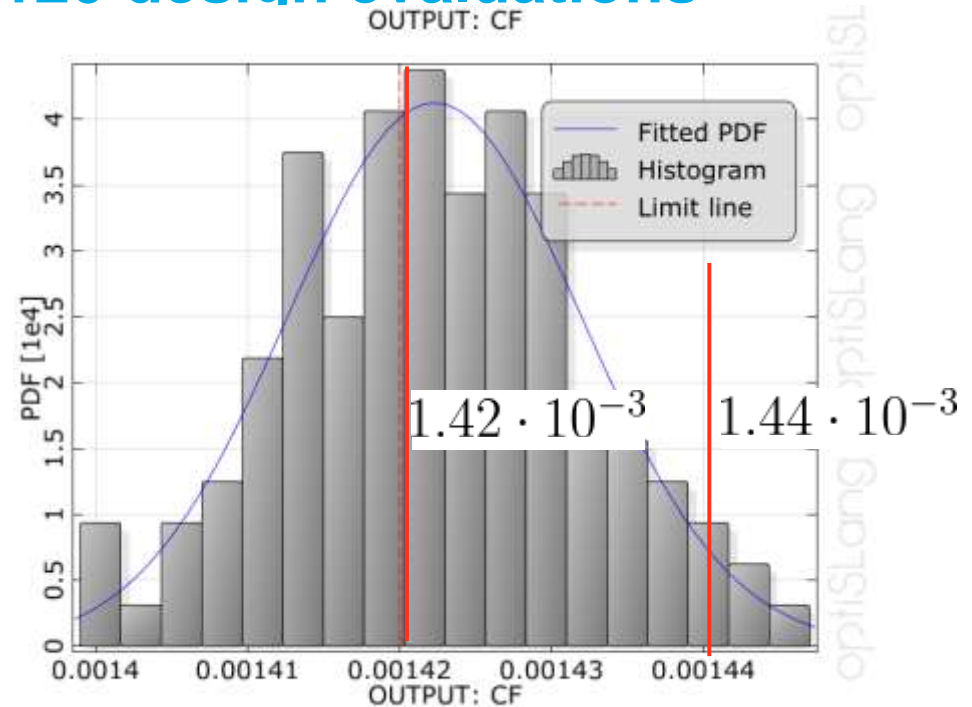
OK

Mean and modified standard deviation of the best design as result of the gradient-based optimization

Robustness evaluation with 120 design evaluations



Statistic data	
Min: 2.708e-005	Max: 0.0003155
Mean: 0.0001095	Sigma: 7.5e-005
CV: 0.6848	
Skewness: 0.986	Kurtosis: 2.757
Fitted PDF: Extreme Typ III (Max) Weibull	
Mean: 0.0001095	Sigma: 7.5e-005
Lower cut: 2.708e-005	
Limit x = 0.000227	
P_rel = 0.891667	P_fit = 0.921784
Probability P(X<x) = 0.95	
x_rel = 0.000265817	x_fit = 0.000258658



Statistic data	
Min: 0.001399	Max: 0.001447
Mean: 0.001422	Sigma: 9.671e-006
CV: 0.006799	
Skewness: -0.02388	Kurtosis: 2.831
Fitted PDF: Normal	
Mean: 0.001422	Sigma: 9.671e-006
Limit x = 0.00142	
P_rel = 0.425	P_fit = 0.405673
Probability P(X<x) = 0.95	
x_rel = 0.00144	x_fit = 0.00143822

Thank you very much for your attention



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Niederrhein University of Applied Sciences

Email: dirk.roos@hs-niederrhein.de



FRIENDSHIP SYSTEMS – A GL Company

GL Business Segments

Maritime

Classification

Consulting

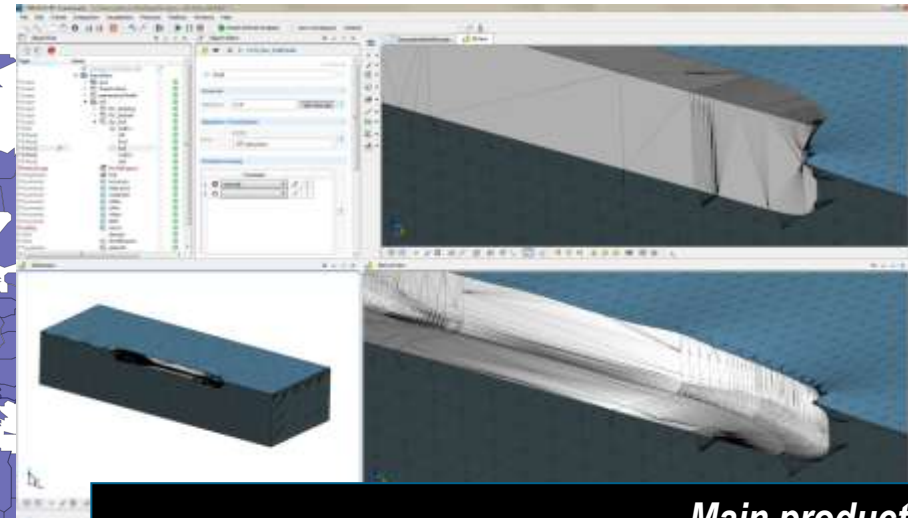
Software

Training

Systems Certification

Oil & Gas

Renewables



Main product
The FRIENDSHIP-Framework –
Software for simulation-driven design