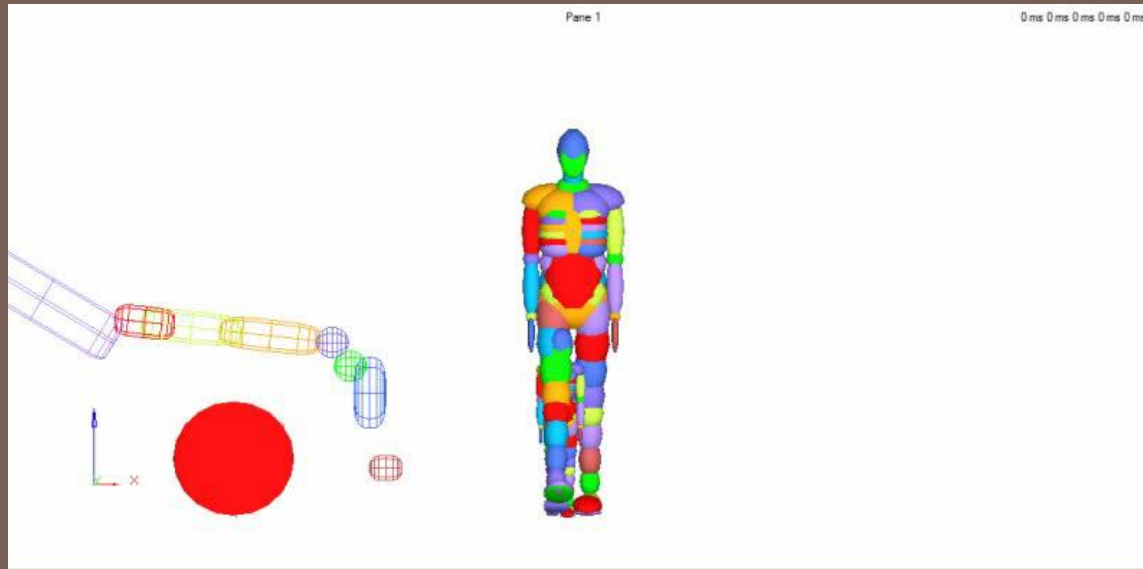




VEHICLE PROFILE OPTIMIZATION TO MINIMIZE THREAT TO PEDESTRIANS

Supervisors:

Prof. Anoop Chawla
IIT Delhi

Prof. Sudipto Mukherjee
IIT Delhi

Prof. Dietmar Goehlich
TU Berlin

24/09/2013

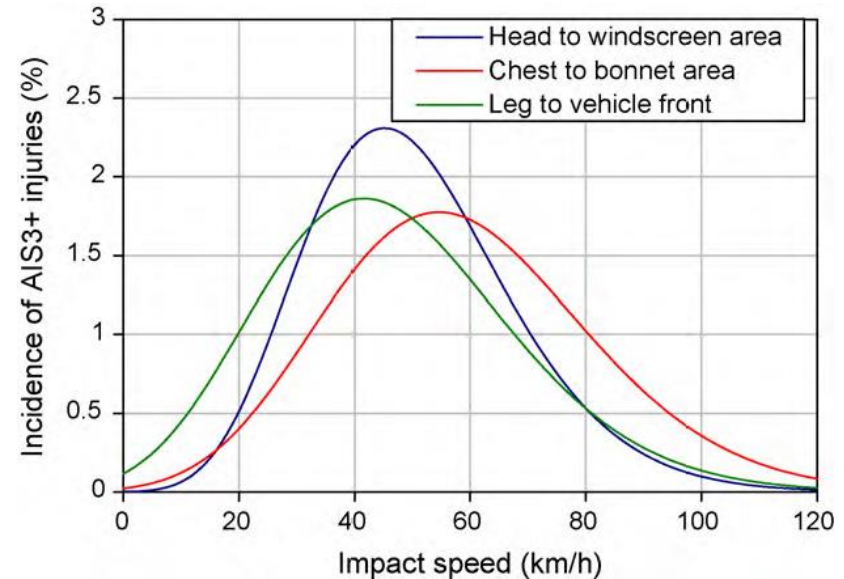
Presented by : Hariharan S Subramanian, IIT Delhi

Safety of Vulnerable Road Users - Pedestrians

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- Vulnerable Road users
 - Bicyclists
 - Motorized two wheelers
 - Pedestrians (least protection)
- “In the majority of crashes, the pedestrian’s side is impacted by the front of the car.” Yao et. al. 2008
- “For 93% of the collisions of VRU with cars the shapes of the vehicle front were similar to a standard form” – Otte D et. al., 2012



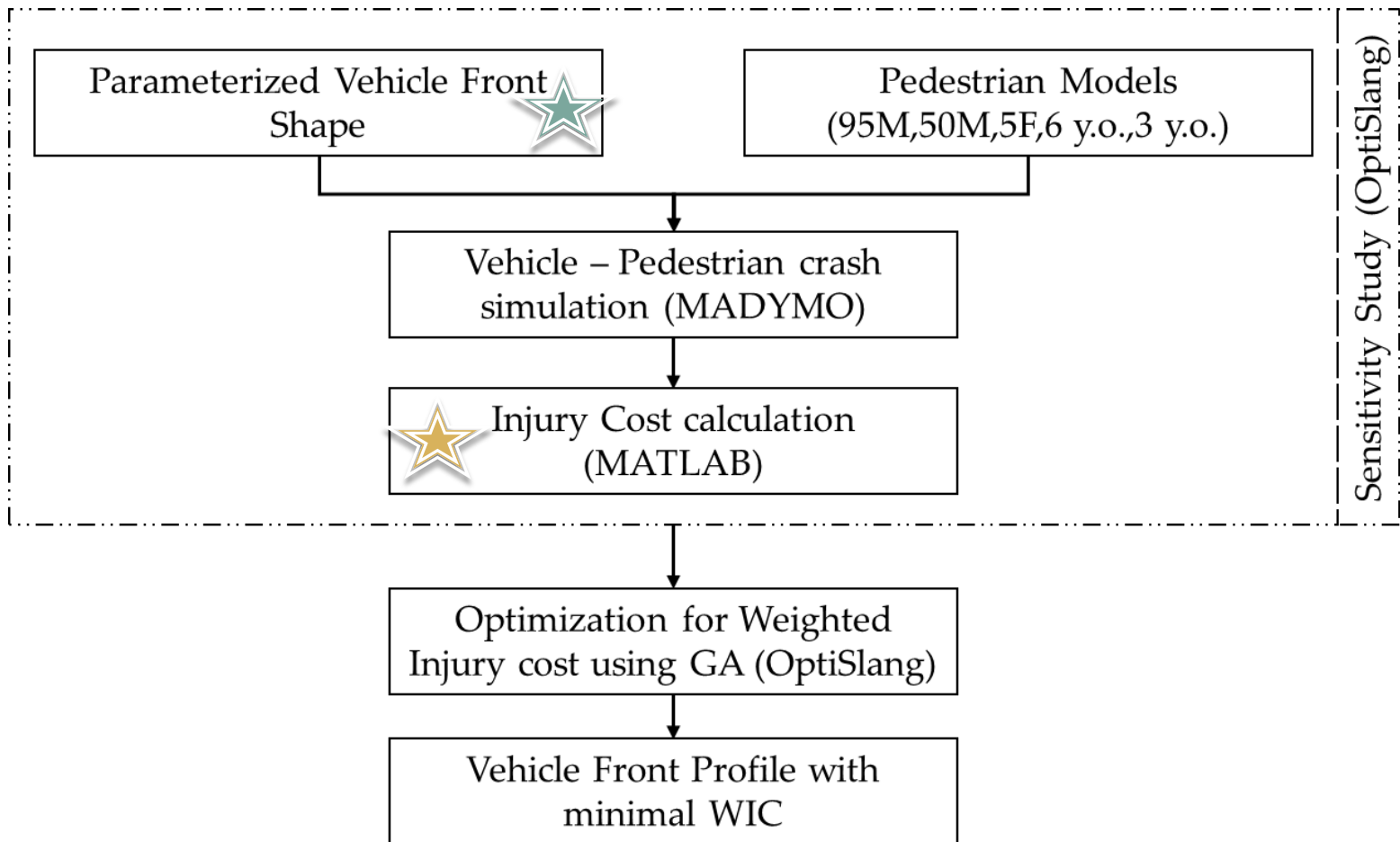
Collision speed of above 40 kmph resulted in more AIS 3+ injuries for kinematic combinations indicated

Fredrikkson R et. al., 2010

Flow chart for Study - OptiSlang

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How to model vehicle?

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Car photos

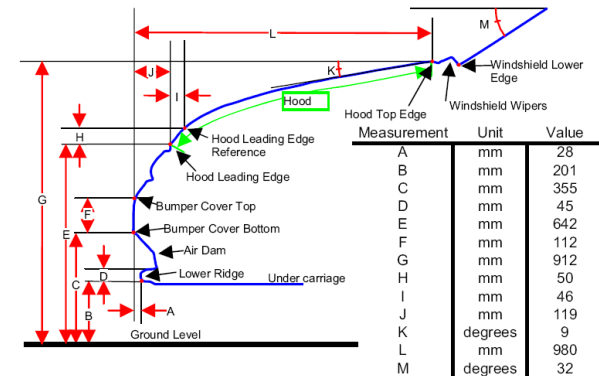


Compact*, sedan and SUV – 14 nos.

Extract dimensions

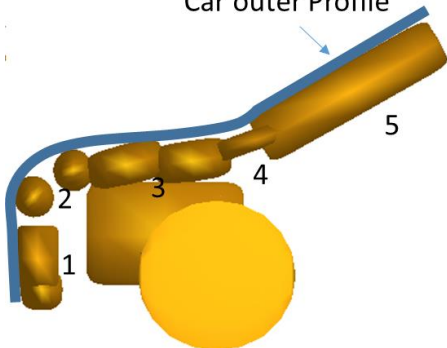


Tabulate dimensions

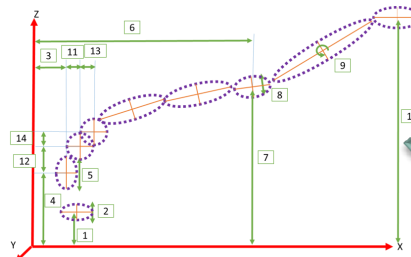


From Kerrigan 2008

Car outer Profile



Vehicle profile

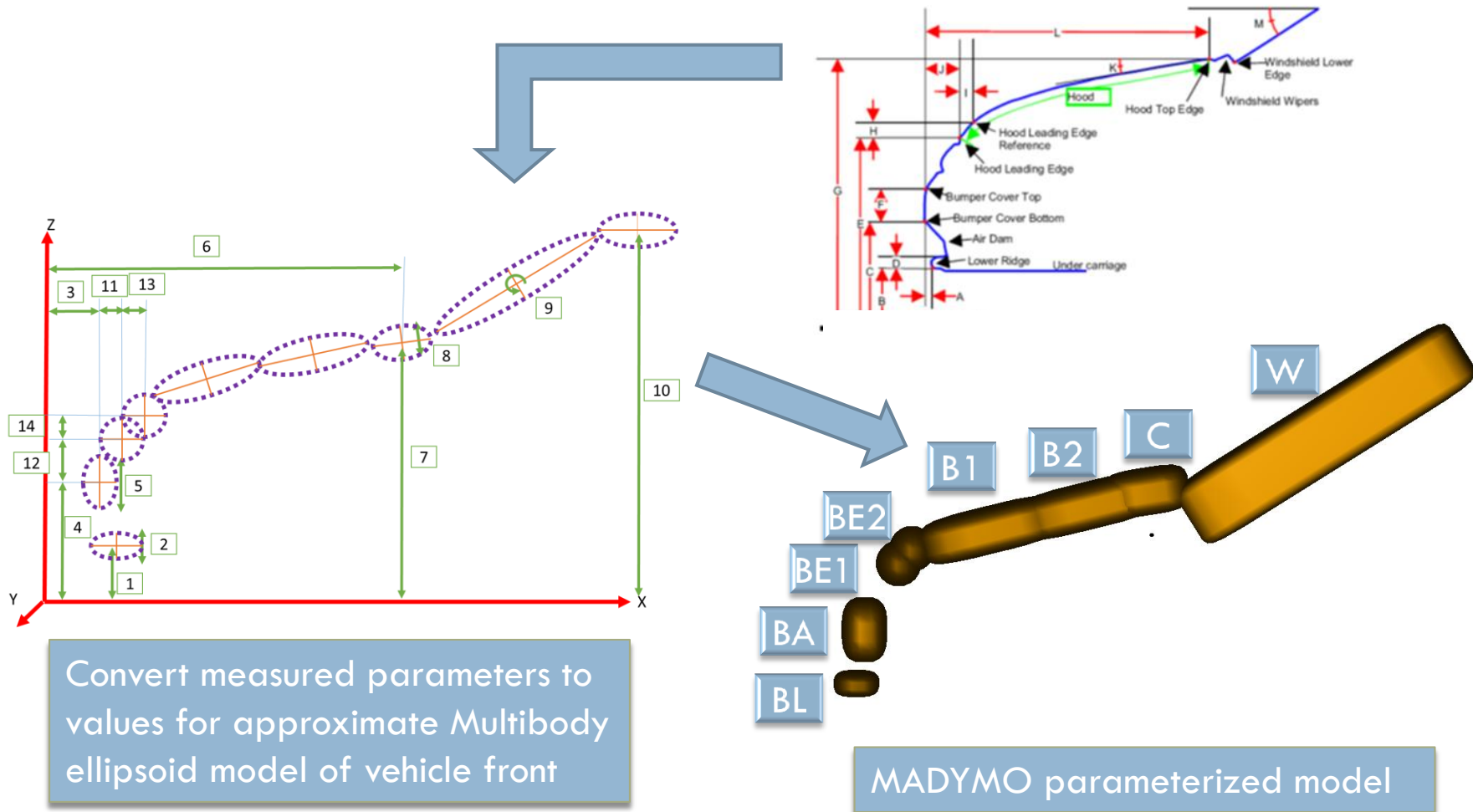


Bumpers (2 Ellipsoids)
Bonnet front (2 Ellipsoids)
Bonnet Middle(2 Ellipsoids)
Bonnet rear (1 Ellipsoid)
Windscreen (1 Ellipsoid)

Steps to create a parameterized MADYMO model

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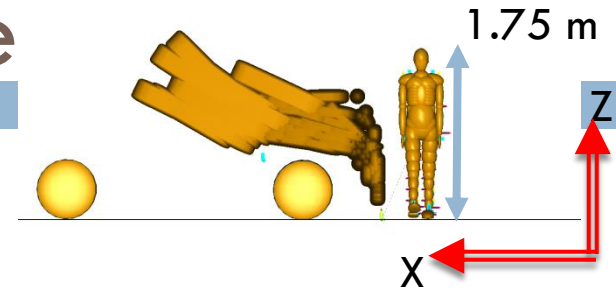
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Range of values for Variables based on the design space

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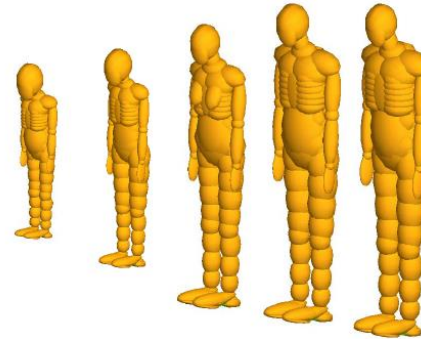
Parameter	Description	Min	Max
1	BL Ellipsoid CG location in Z direction	0.594	0.170
2	BL Ellipsoid width along Z direction	0.166	0.000
3	BA Ellipsoid CG location in X direction	-0.138	-0.010
4	BA Ellipsoid CG location in Z direction	0.895	0.411
5	BA Ellipsoid width along Z direction	0.320	0.038
6	C Ellipsoid CG location in X direction	-1.343	-0.471
7	C Ellipsoid CG location in Z direction	1.280	0.840
8	C Ellipsoid angle about Y axis	0.873	0.052
9	W Ellipsoid angle about Y axis	0.785	0.436
10	Location of point along Z direction on W ellipsoid along center plane indicated by red dot in Figure 4	1.976	1.370
11	BA Ellipsoid to BE1 Ellipsoid CG location distance in X direction	0.165	0.013
12	BA Ellipsoid to BE1 Ellipsoid CG location distance in Z direction	0.435	0.073
13	BE1 Ellipsoid to BE2 Ellipsoid CG location distance in X direction	0.219	0.000
14	BE1 Ellipsoid to BE2 Ellipsoid CG location distance in Z direction	0.222	0.03

Simulation conditions

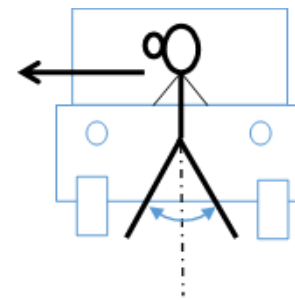
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- Force deflection data from Martinez 2007
 - ▣ Orange level of F-D characteristics considered
 - ▣ The data collected from actual European vehicle fleet (subjected to Euro-NCAP tests)
- Geometrical limits
 - ▣ Sedan + SUV
 - ▣ Representative of Indian vehicle population
- Pedestrian Models
 - ▣ 3 y.o. and 6 y.o. child
 - ▣ 5th %le Female
 - ▣ 50th and 95th %le Male
- Braking values from Matsui 2011
 - ▣ Hard braking 4.7 m/s^2 .
 - ▣ Time complete stop after initial hit = 100 ms

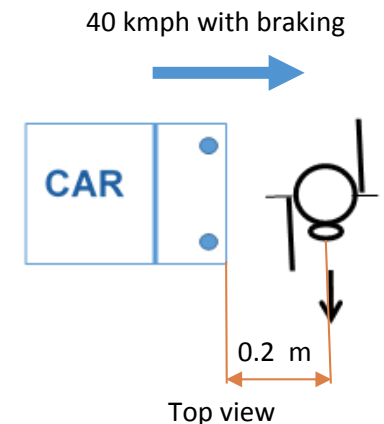


From TNO,
Madymo human
models, 2012



0.4 radian

Front view



Top view

A single measure for threat – Injury Cost (IC)

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- The AIS levels of injury severity mapped to an indicative "**injury cost (IC)**" using ISO: 13232
- “No way do such injury costs consider, nor are they intended to consider, the market level costs of a proposed protective device”.
- The "costs" are a **convenient, common basis** for **combining** and **comparing** across body regions and crash tests and **on a relative basis**, different types, locations, and severities of injuries.
- The optimization problem being reduced to a **single objective problem** seems to converge to an optimal solution for the profile of a vehicle front-end design.

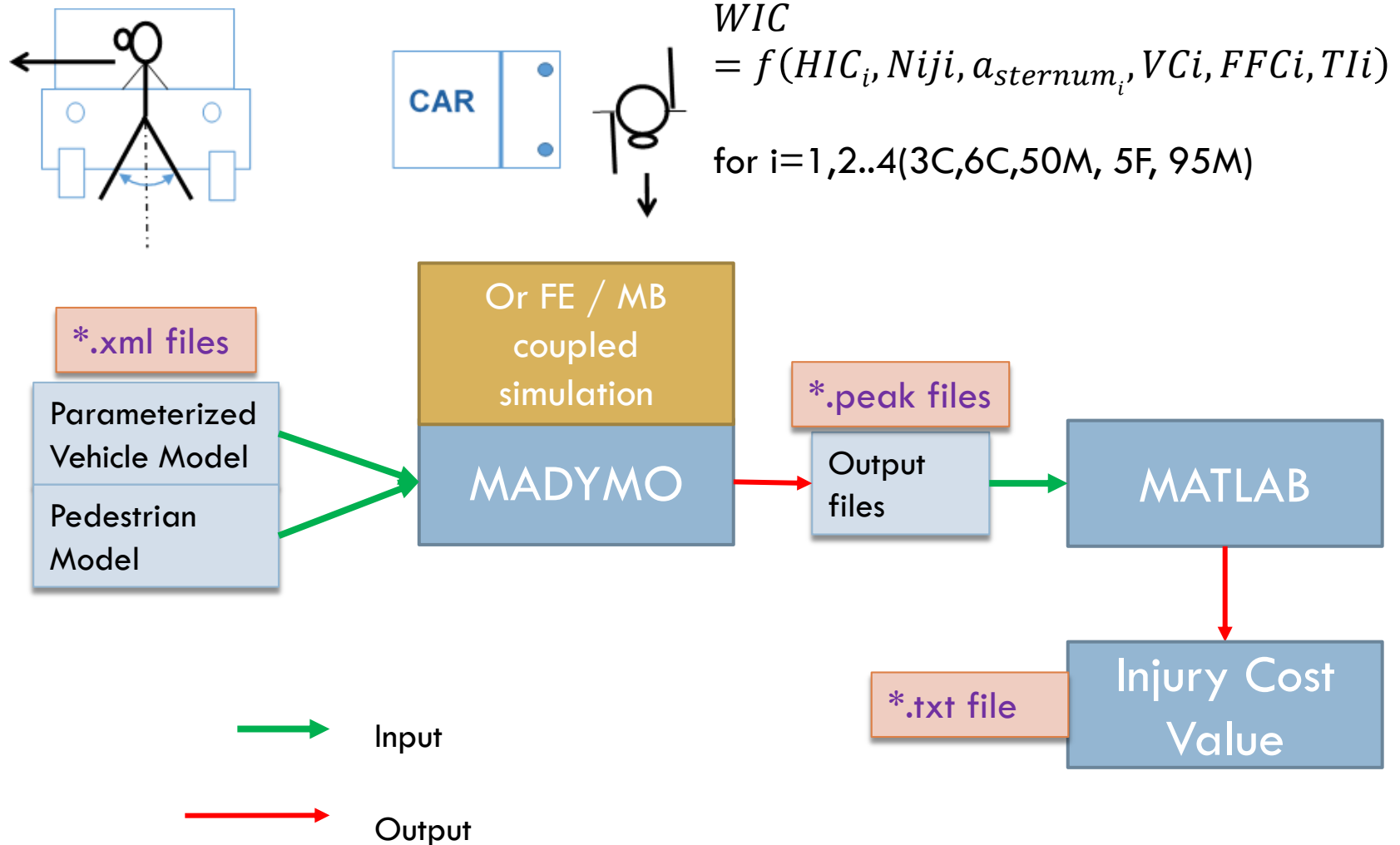
Body region	AIS injury severity	Cost \$
Head	1	784
Head	2	3 807
Head	3	14 169
Head	4	72 349
Head	5	263 306
Neck	3	20 509
Neck	4	440 037
Neck	5	530 695

ISO 13232:part 5

How to compute IC from Simulation ?

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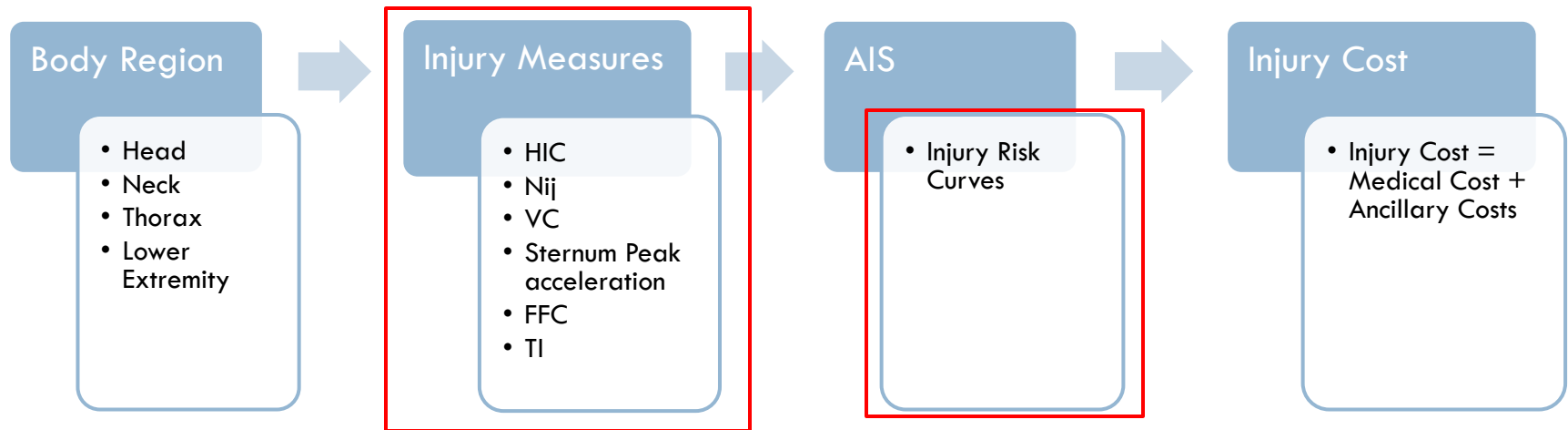
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Calculation of IC

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HIC to AIS		
HIC	AIS Code	Level Of Brain Concussion And Head Injury
135 – 519	1	Headache or dizziness
520 – 899	2	Unconscious less than 1 hour – linear fracture
900 – 1254	3	Unconscious 1 – 6 hours – depressed fracture
1255 – 1574	4	Unconscious 6 – 24 hours – open fracture
1575 – 1859	5	Unconscious greater than 25 hours – large haematoma
> 1860	6	Non survivable

*Table taken from Payne and patel,2001

Injury Values obtained	Car 1_50		
	Value	AIS	Cost
HIC	793	2	14625
Nij	0.369	1	0
VC	0.002	0	0
FFC (kN)	10.9	4	128302
TI	0.31	0	
Force above knee on femur (kN)	11.17	4	
Lower Extremity PPI	0.27		
Total Injury Cost (USD)	142927		

*Costs calculated based on ISO 13232:part 5

IC calculation for pedestrian population

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Total potential IC for a population = $x_1 * IC_{6C} + x_2 * IC_{5F} + x_3 * IC_{50M} + x_4 * IC_{95M}$

Where,

95 M = 95th %ile Male

50M = 50th %ile Male

5F = 5th %ile Female

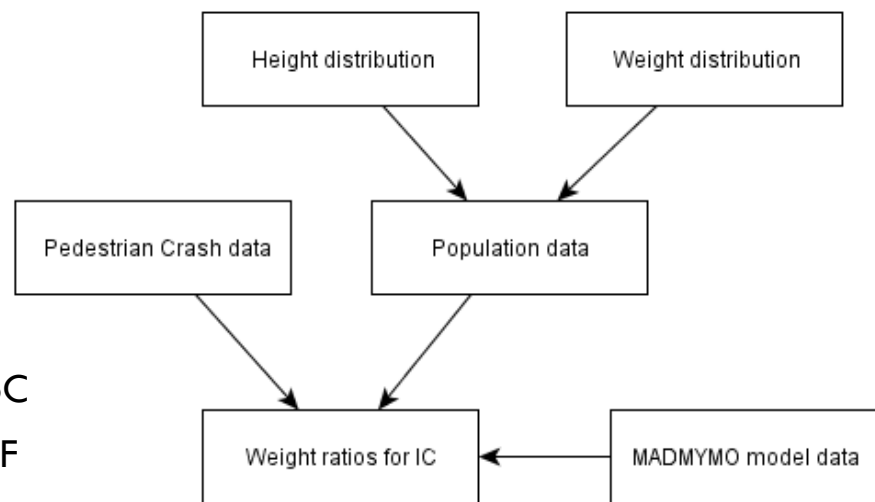
6C = 6 year old Child

x_1 = weighting factor for IC calculated from 6C

x_2 = weighting factor for IC calculated from 5F

x_3 = weighting factor for IC calculated from 50M

x_4 = weighting factor for IC calculated from 95M



Equi-weight IC (EIC) = $0.25 * IC_{6C} + 0.25 * IC_{5F} + 0.25 * IC_{50M} + 0.25 * IC_{95M}$

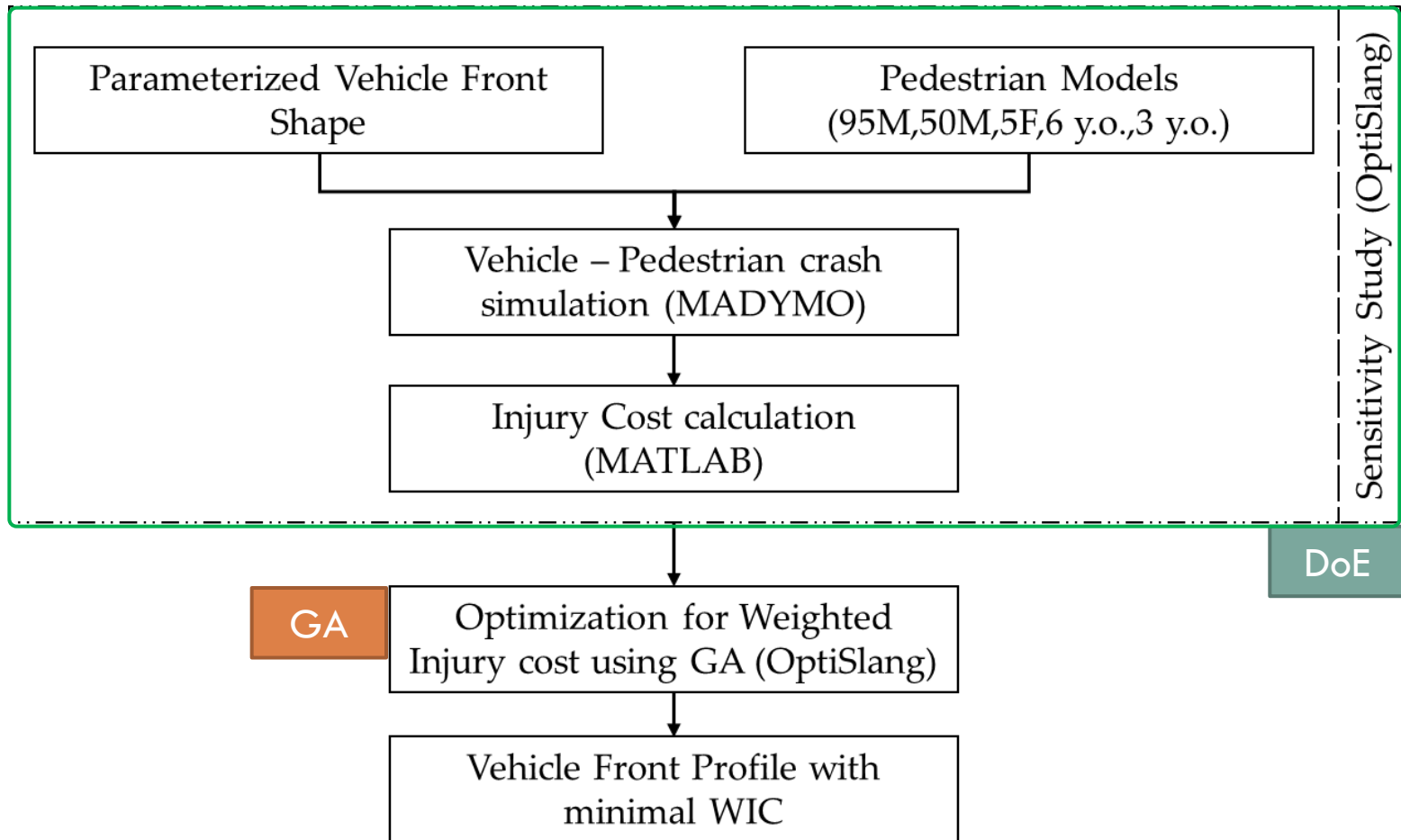
Population weighted IC (WIC)⁺ = $0.45 * IC_{6C} + 0.47 * IC_{50M} + 0.08 * IC_{5F}$

⁺ - Michigan, USA crash data and US Census data

Flow chart for Study - OptiSlang

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Results from OptiSlang

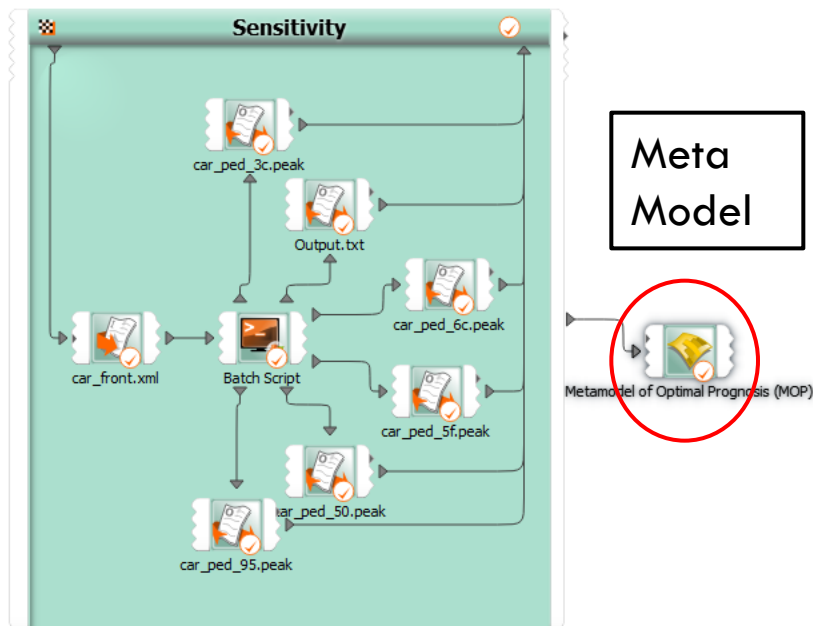
Design of Experiments followed by Optimization

Design of Experiments – Problem formulation

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Sensitivity model



Input Variables

	Name	Parameter type	ference val	Constant	Value type	Resolution	Range	Range plot
1	Parameter_01	Deterministic	0.336	☐	REAL	Continuous	0.17 0.594	
2	Parameter_02	Deterministic	0.073	☐	REAL	Continuous	0.01 0.166	
3	Parameter_03	Deterministic	0.116	☐	REAL	Continuous	0.01 0.138	
4	Parameter_04	Deterministic	0.74	☐	REAL	Continuous	0.411 0.895	
5	Parameter_05	Deterministic	0.102	☐	REAL	Continuous	0.038 0.32	
6	Parameter_06	Deterministic	1.326	☐	REAL	Continuous	0.471 1.343	
7	Parameter_07	Deterministic	1.22	☐	REAL	Continuous	0.84 1.28	
8	Parameter_08	Deterministic	0.307	☐	REAL	Continuous	0.052 0.873	
9	Parameter_09	Deterministic	0.696	☐	REAL	Continuous	0.436 0.785	
10	Parameter_10	Deterministic	1.683	☐	REAL	Continuous	1.37 1.976	
11	Parameter_11	Deterministic	0.032	☐	REAL	Continuous	0.013 0.165	
12	Parameter_12	Deterministic	0.259	☐	REAL	Continuous	0.073 0.435	
13	Parameter_13	Deterministic	0.009	☐	REAL	Continuous	0.01 0.219	
14	Parameter_14	Deterministic	0.017	☐	REAL	Continuous	0.03 0.222	

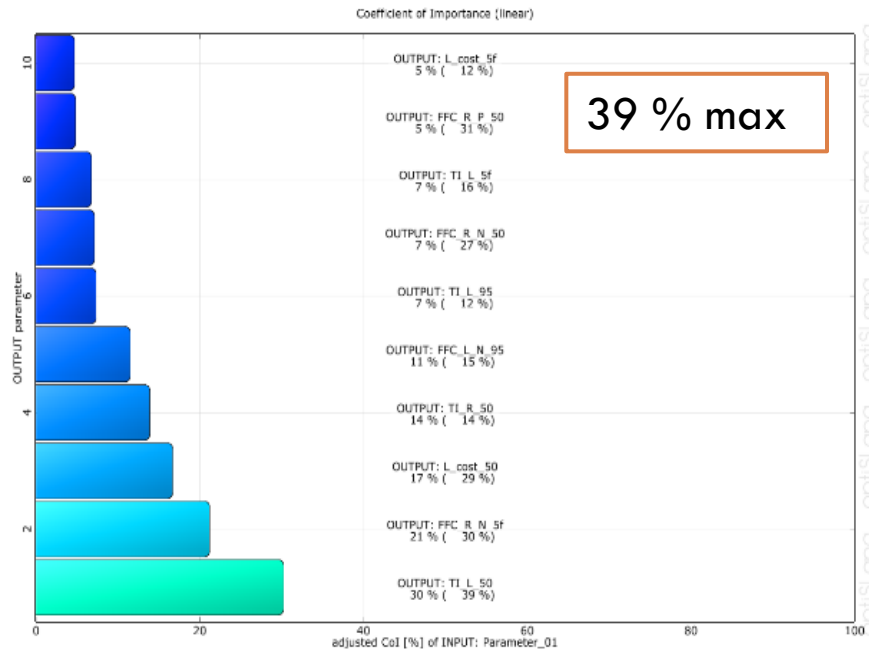
Continuous variables, range to avoid zero values : cover selected Indian vehicles dimensions

Coefficient of Importance - Linear

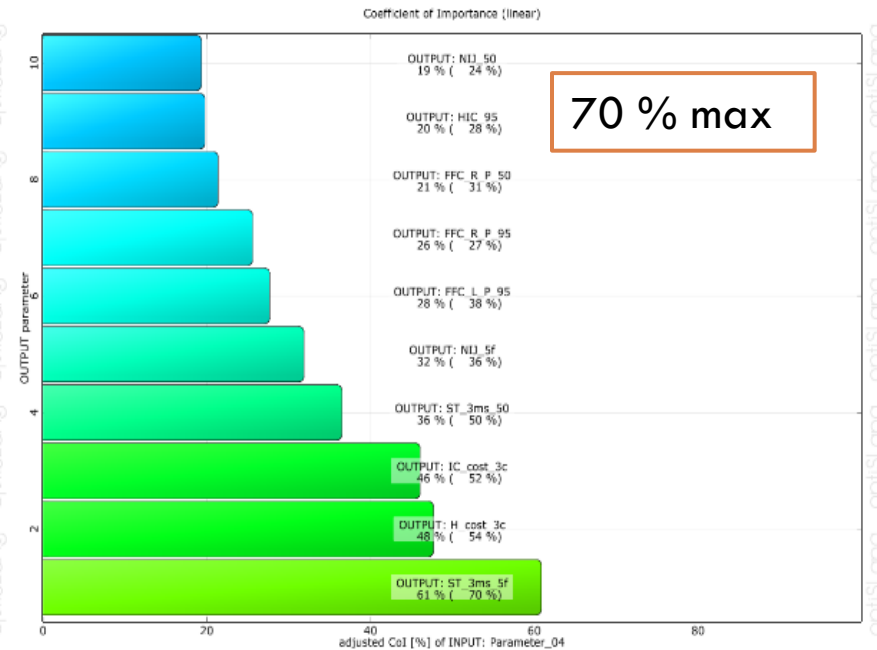
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Parameter 01



Parameter 04



Higher the CoI (Linear) indicates better linear correlation with specified output parameter

Significance Filter

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Bumper Lower - Z

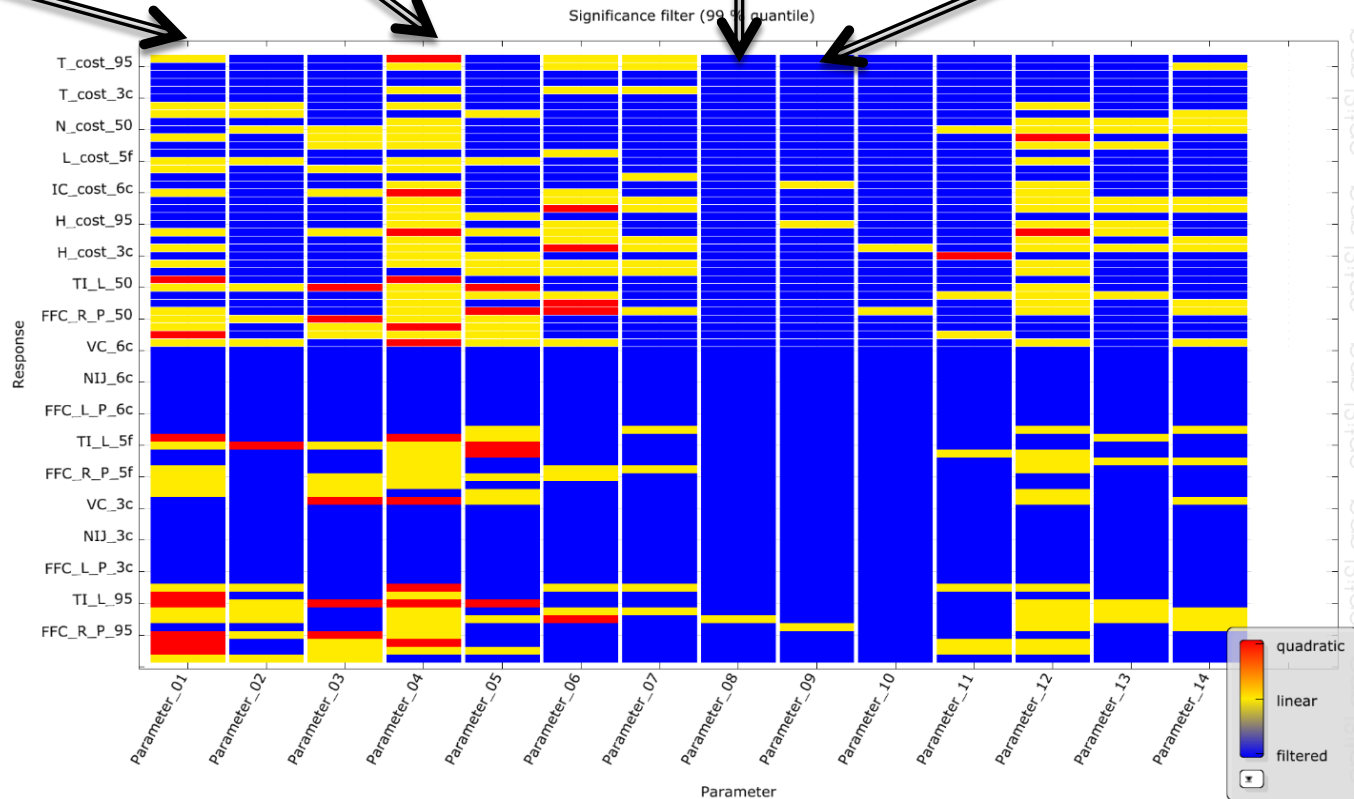
Bumper Actual - Z

Cowl - θ_y

Windscreen - θ_y

Significant

Non
Significant



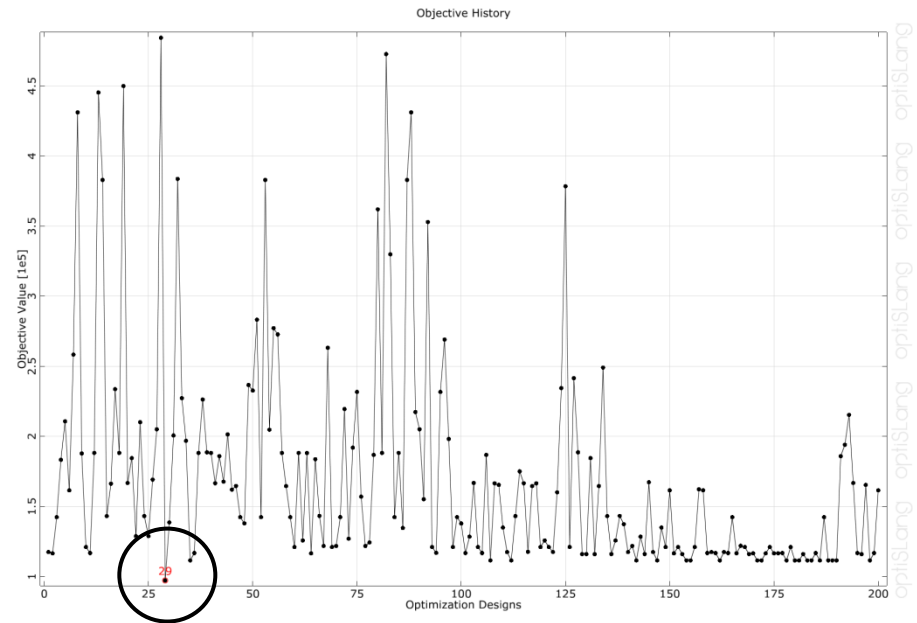
Parameters 01, 04, 12, 05, 06 indicate to have Col with output.

Optimization results - Minimal Value

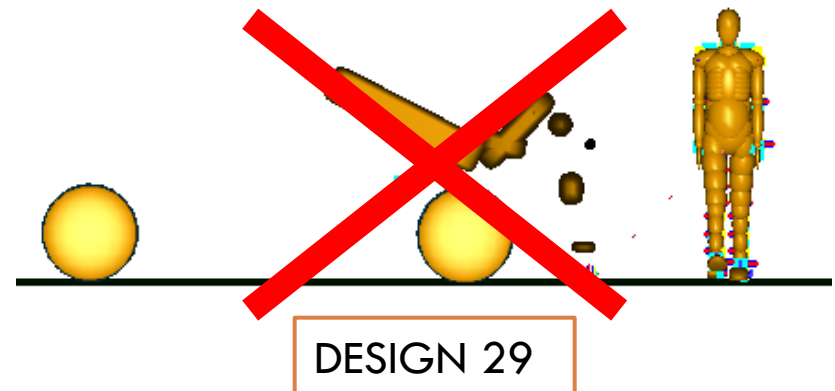
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- GA process
- Minimization of WIC
- 100 samples per generation
- Stagnation in 2 generation



- Design 29 was found to be **least WIC value**.
- Design 29 not acceptable
 - Driver visibility
 - Non-conventional look



Optimal Designs

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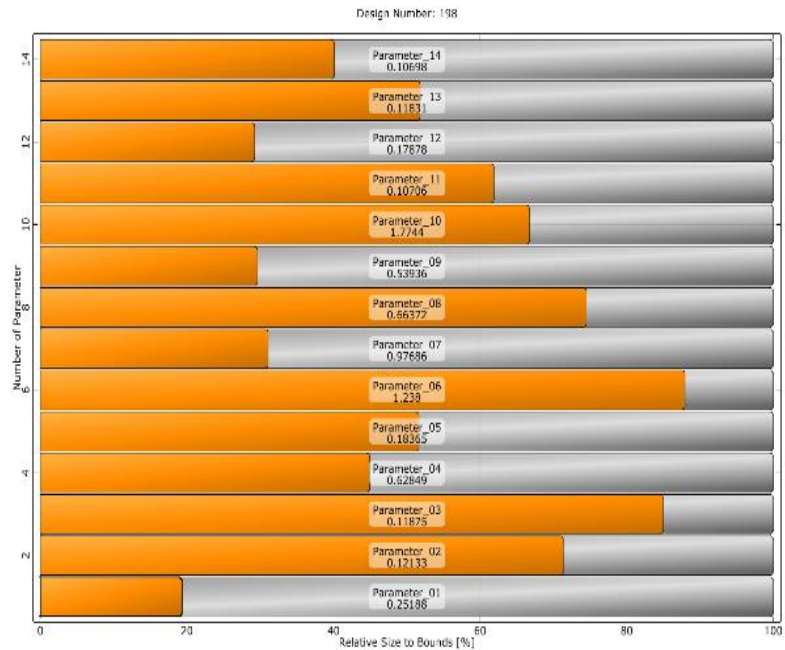
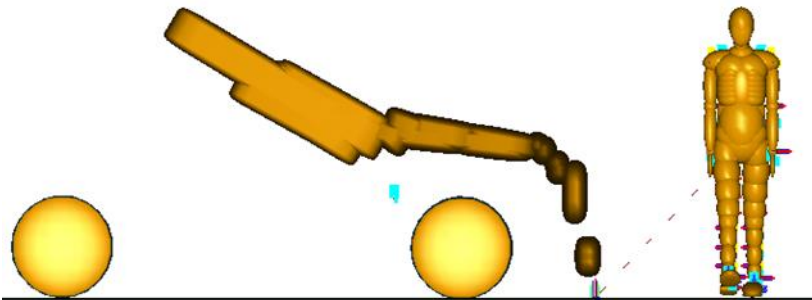


Figure :

- Variable values of one of the designs
- Gray represents the total range

- 14 more designs had WIC values 111534 USD.
- The shape corresponds to similar values
 - Bumper to ground - 0.25 m
 - Bumper width - 0.38 m
 - Bonnet leading edge height from ground - 0.85 m
 - Bonnet length - 1.12m



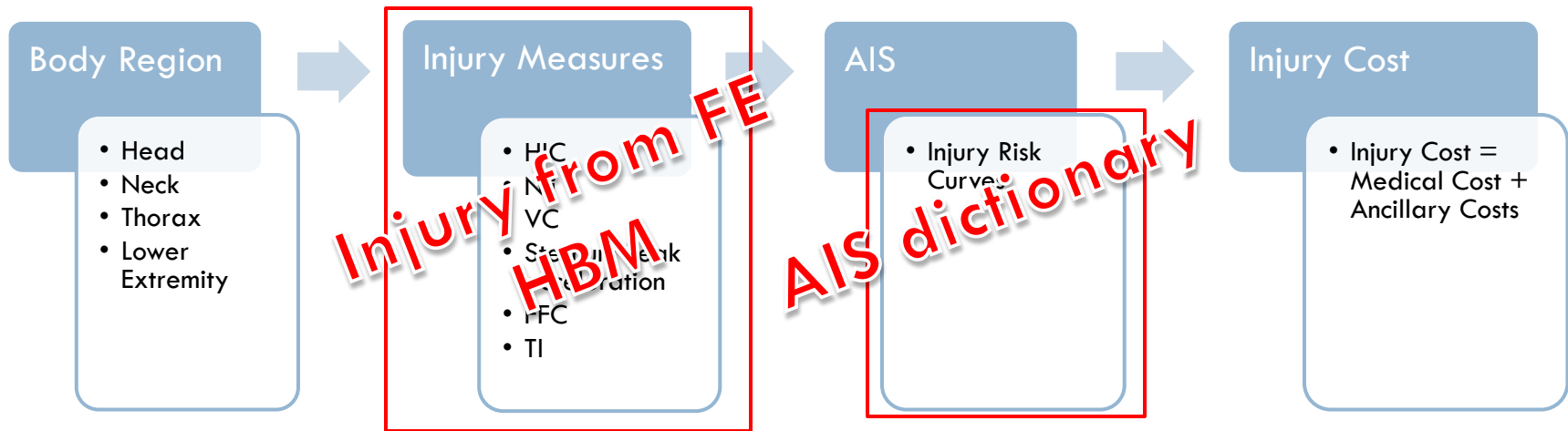
Conclusion

- The methodology allows a step by step identification and formulation of vehicle profile optimization problem
- The results indicate
 - ▣ Multiple solutions of non-significant variables as identified in DoE
 - ▣ Almost similar solutions from significant variables indicating one solution in the range considered.

Bigger Picture

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- With better human models like **Human Body FE model**, and validated **FE car** models a better injury prediction can be performed.
- With more crash and population anthropometry data, a suitable WIC tuned for Indian conditions* can also be developed.
- A robust solution with OptiSlang
- An appropriate research methodology

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Thank you

Acknowledgement :

- DAAD – Sandwich model doctoral research fellowship
- Transport Research and Injury Prevention Programme (TRIPP) , IIT Delhi

Contact : Hariharan Sankara Subramanian
hariharan.s@mech.iitd.ac.in